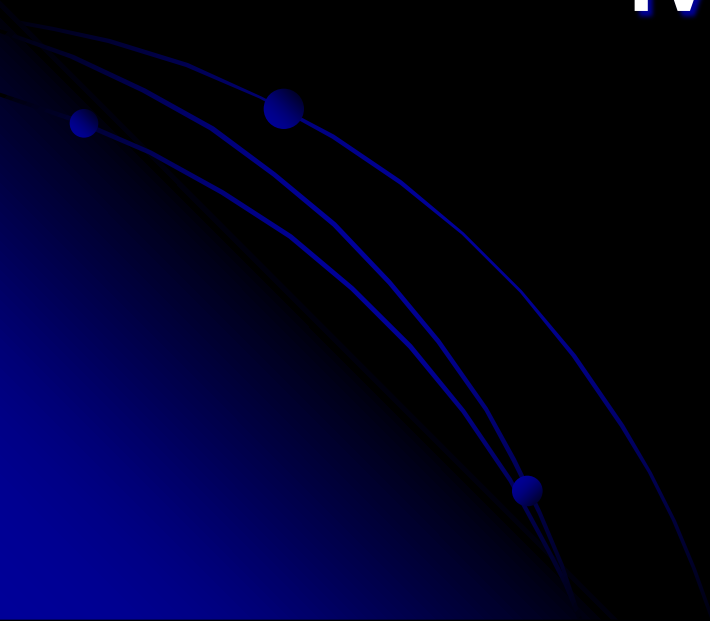


# Matematická Morfológia



# Matematická morfológia

η μορφή = forma, tvar

ο λόγος (τα λόγια) = slovo (slová)

Morfológia = štúdium formy a štruktúry (zvieratá, rastliny)

- Matematická morfológia = nástroj na popis komponentov obrazu, tvaru, štruktúry

Základ – teória množín

# Použitie

predspracovanie

filtrovanie šumu, zjednodušenie tvarov, ...

segmentácia

watershed, hrany, obrys, ...

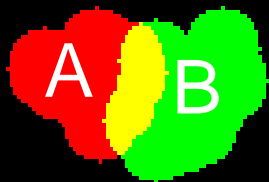
popis štruktúry objektov

kostra, konvexný obal, ...

- kvantitatívny popis

analýza tvaru (area, perimeter, ...),

granulometria, súvislé oblasti ...

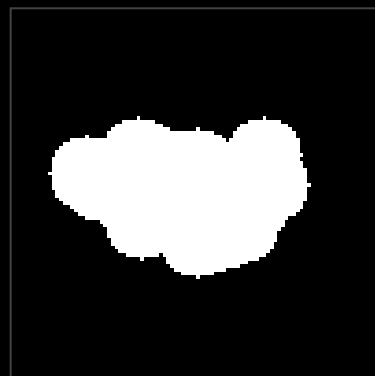


# Základné definície

- Prvok množiny  $x \in A$
- Prvok nepatriaci množine  $x \notin A$
- Prázdna množina – neobsahuje žiadny prvok  $\emptyset$
- Disjunktné množiny, ak  $A \cap B = \emptyset$
- Podmnožina  $A \subseteq B \Leftrightarrow (x \in A \Rightarrow x \in B)$

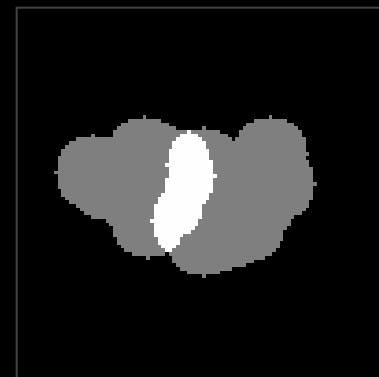
## Zjednotenie

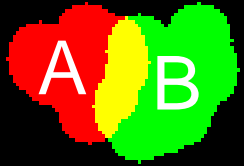
$$A \cup B = \{x \mid x \in A \vee x \in B\}$$



## Prienik

$$A \cap B = \{x \mid x \in A \wedge x \in B\}$$

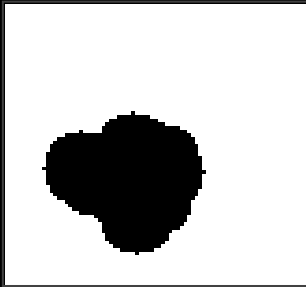




# Množinové operácie

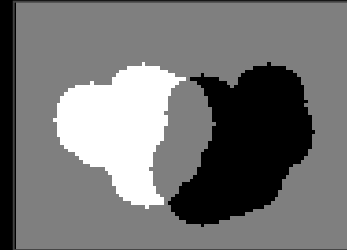
Komplement

$$A^c = \{x \mid x \notin A\}$$



Rozdiel

$$A - B = A \cap B^c = \{x \mid x \in A \wedge x \notin B\}$$



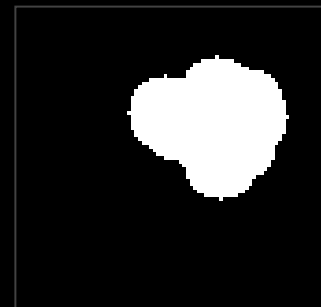
Zrkadlenie

$$\hat{A} = \{x \mid x = -a, \forall a \in A\}$$



Posunutie

$$A_z = A + z = \{x \mid x = a + z, \forall a \in A\}$$




# Morfologické operácie

Vzťah:

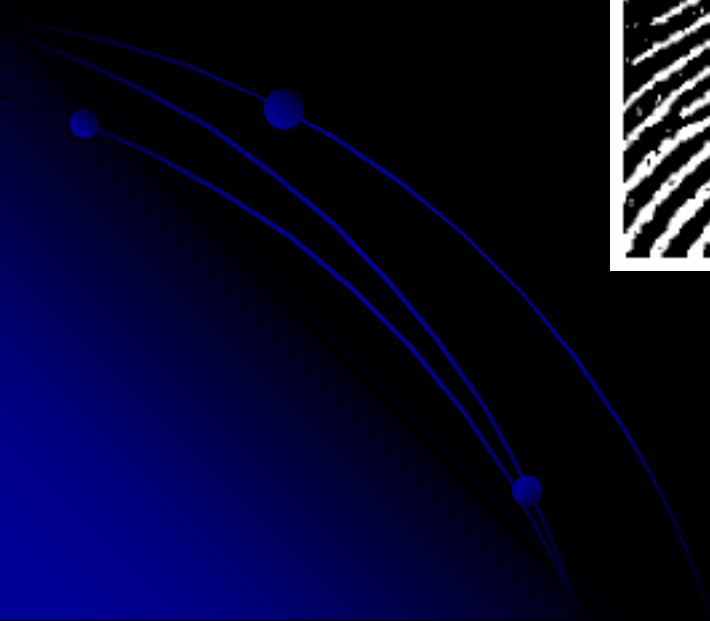
obraz (množina) – štruktúrálly prvok

Výsledok:

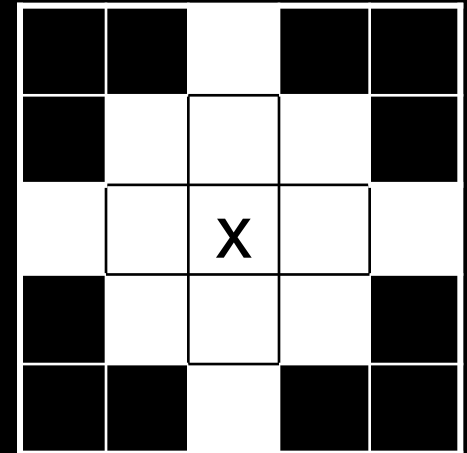
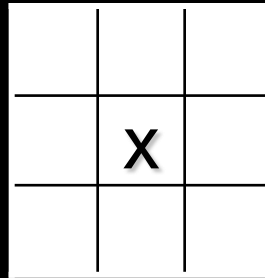
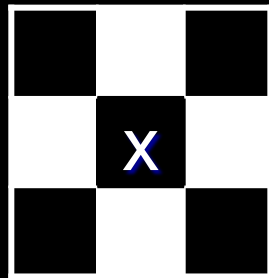
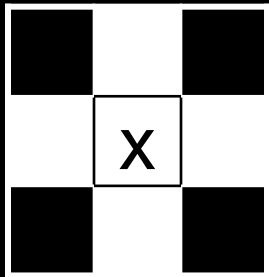
zmena, zmenšenie, zväčšenie množiny



# Binárna morfológia



# Štruktúrálny prvok



x – počiatok súr. sústavy (0,0)  
referenčný bod



# Štrukturálny prvok

tvar

veľkosť

orientácia

pozícia vzhľadom k  $x$

Závisia od aplikácie, ovplyvňujú výsledok

ŠP je (zvyčajne) **oveľa menší** ako obraz

# Dilatácia



Minkowského súčet  $\oplus$

$$A \oplus B = \bigcup_{b \in B} A_b$$

$$A \oplus B = \bigcup_{b \in B} \{a + b \mid a \in A\}$$

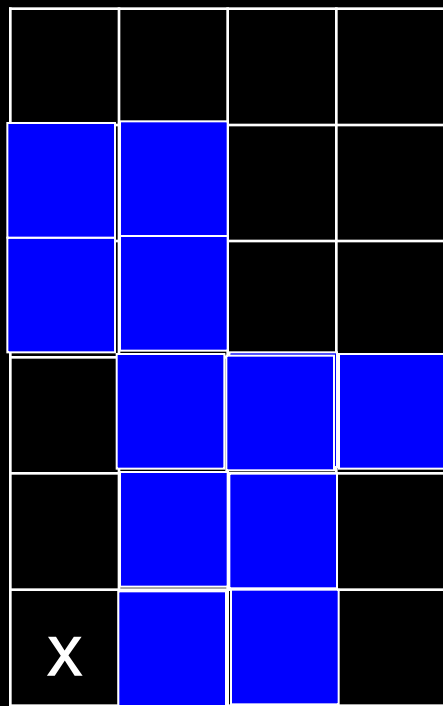
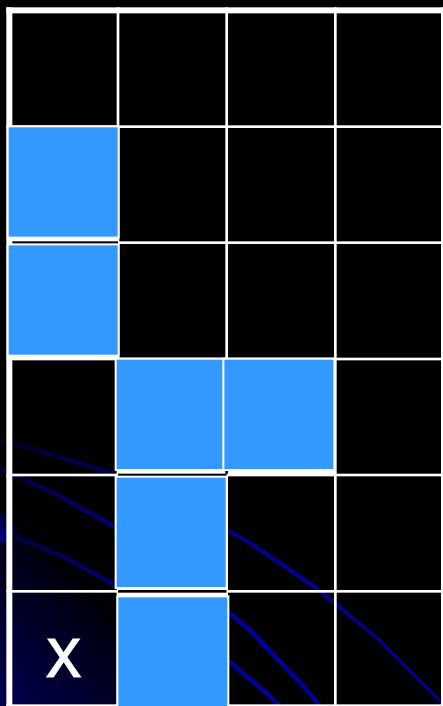
$$= \{a + b \mid a \in A, b \in B\}$$

$$A \oplus B = \{x \mid \hat{B}_x \cap A \neq \emptyset\}$$

Expanzívna operácia – zväčšuje množinu

$$A \oplus B = \bigcup_{b \in B} A_b$$

# Dilatácia



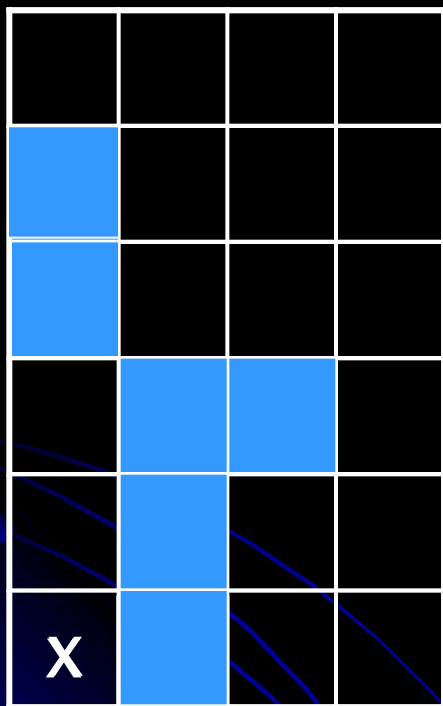
$$B = \begin{array}{|c|c|} \hline \text{x} & \\ \hline \end{array}$$

$b_1 \quad b_2$   
 $(0,0), (1,0)$

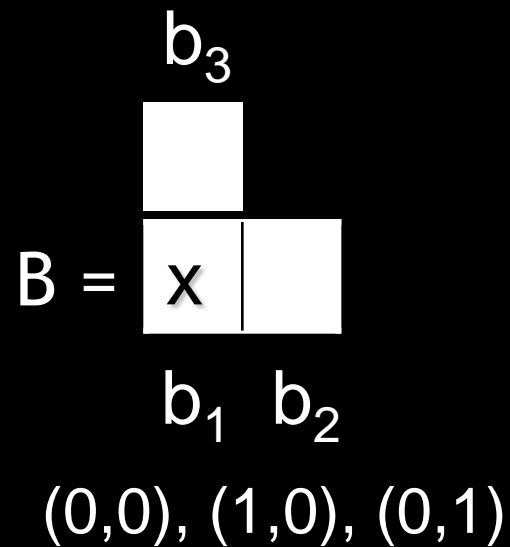
$(0,4), (0,3), (1,2), (2,2), (1,1), (1,0)$

$$A \oplus B = \bigcup_{b \in B} A_b$$

# Dilatácia



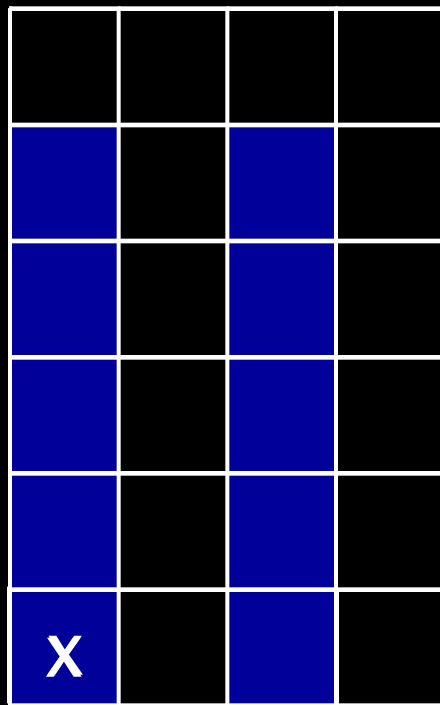
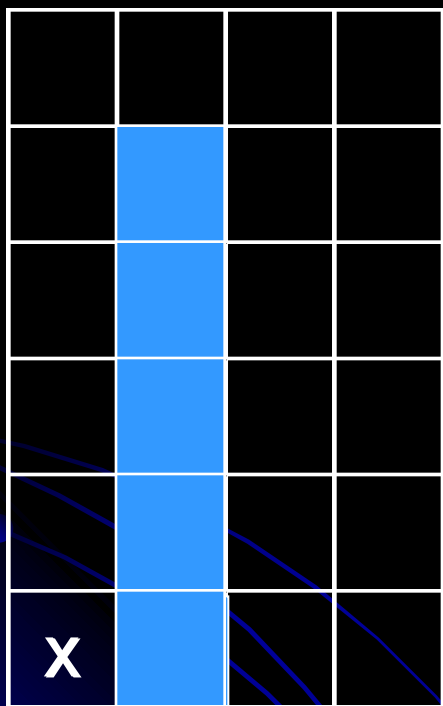
$(0,4), (0,3), (1,2), (2,2), (1,1), (1,0)$



$(0,0), (1,0), (0,1)$

$$A \oplus B = \bigcup_{b \in B} A_b$$

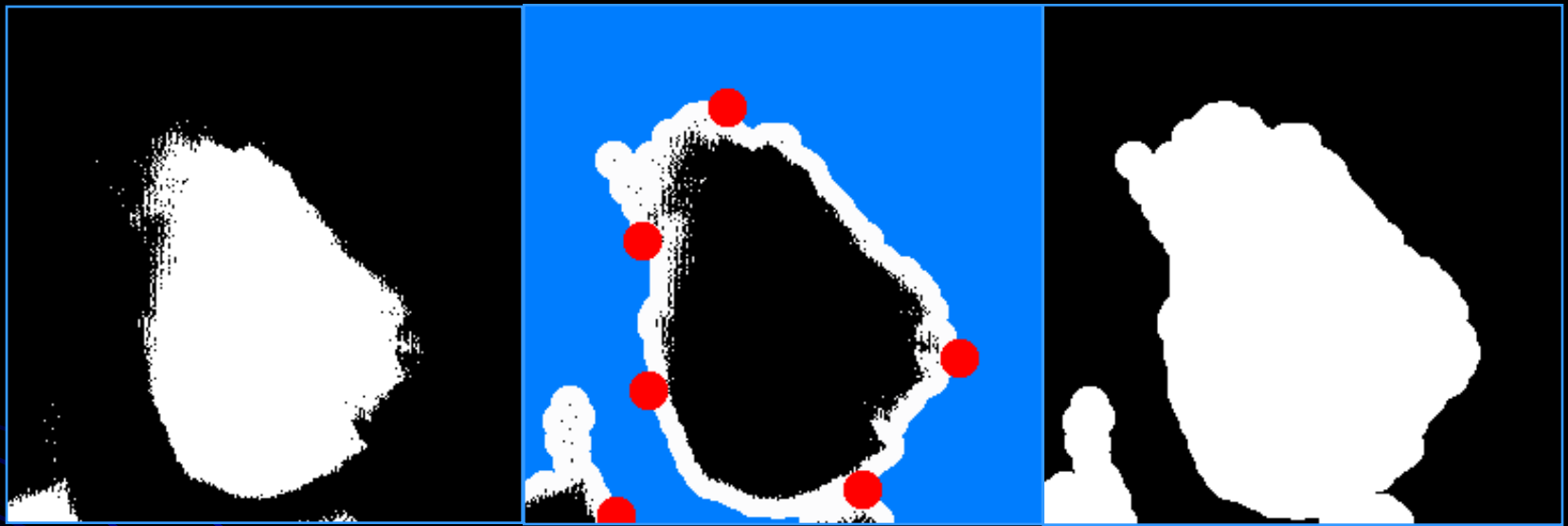
# Dilatácia



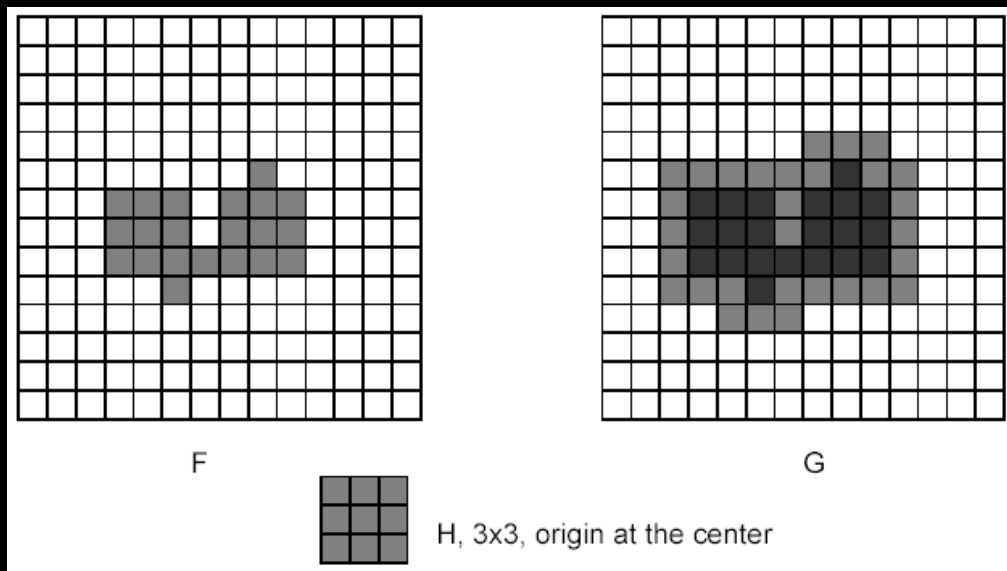
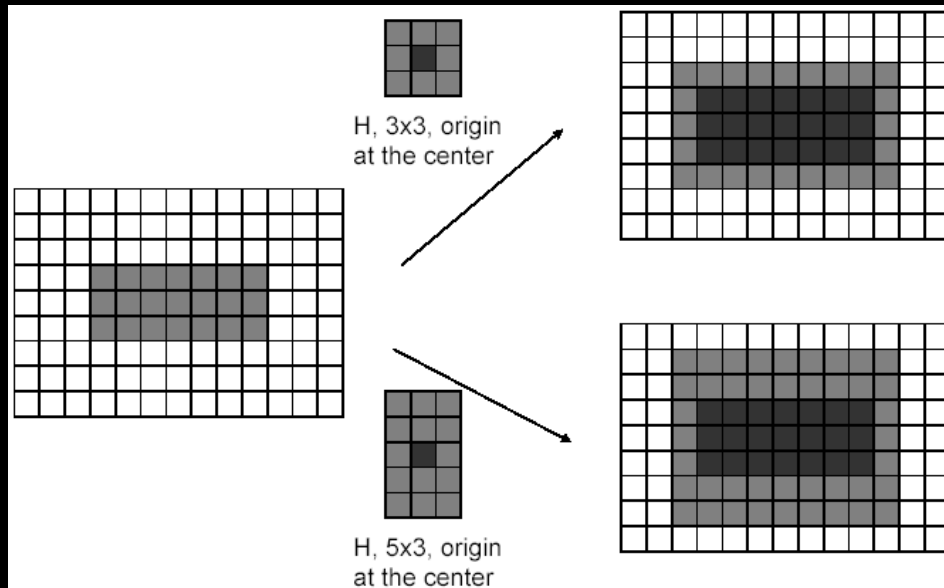
$$B = \begin{array}{ccc} & \text{x} & \\ b_1 & & b_2 \\ (-1,0), & (1,0) \end{array}$$

$(1,0), (1,1), (1,2), (1,3), (1,4)$

# Dilatácia



# Dilatácia



# Vlastnosti dilatácie

$$A \oplus B = B \oplus A$$

$$A \oplus (B \oplus C) = (A \oplus B) \oplus C$$

$$A_1 \subseteq A_2 \Rightarrow (A_1 \oplus B) \subseteq (A_2 \oplus B)$$

$$A \oplus (B \cup C) = (A \oplus B) \cup (A \oplus C)$$



# Erózia

Minkowského rozdiel  $\ominus$

$$A \ominus B = \bigcap_{b \in B} A_{-b}$$

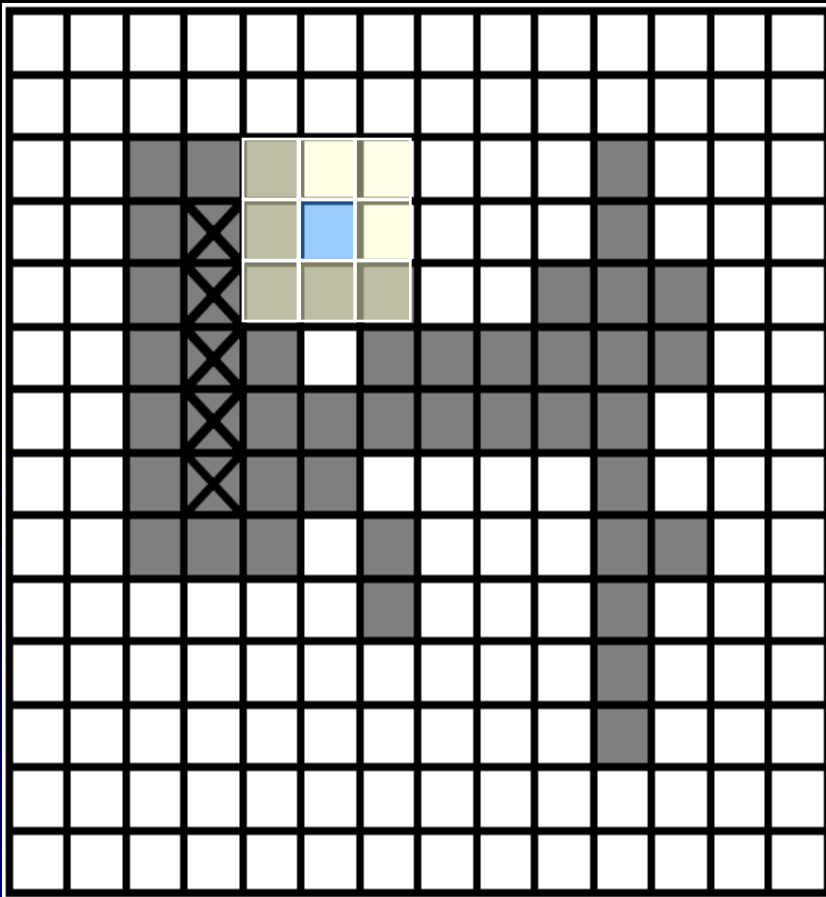
$$A \ominus B = \bigcap_{b \in B} \{a - b \mid a \in A\}$$

$$A \ominus B = \{x \mid B_x \subseteq A\}$$

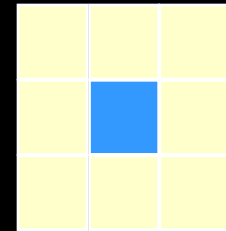
Kontraktívna operácia – znižuje množinu

$$A \ominus B = \{x \mid B_x \subseteq A\}$$

# Erózia

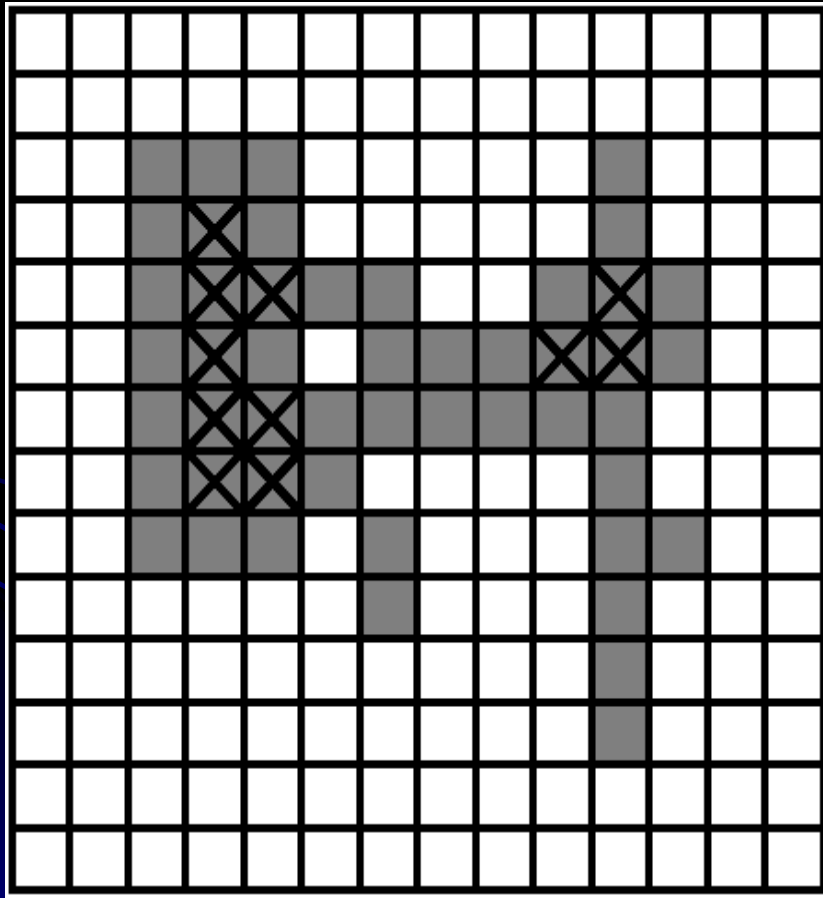


SE=

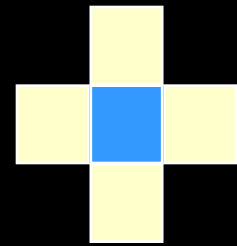


$$A \ominus B = \{x \mid B_x \subseteq A\}$$

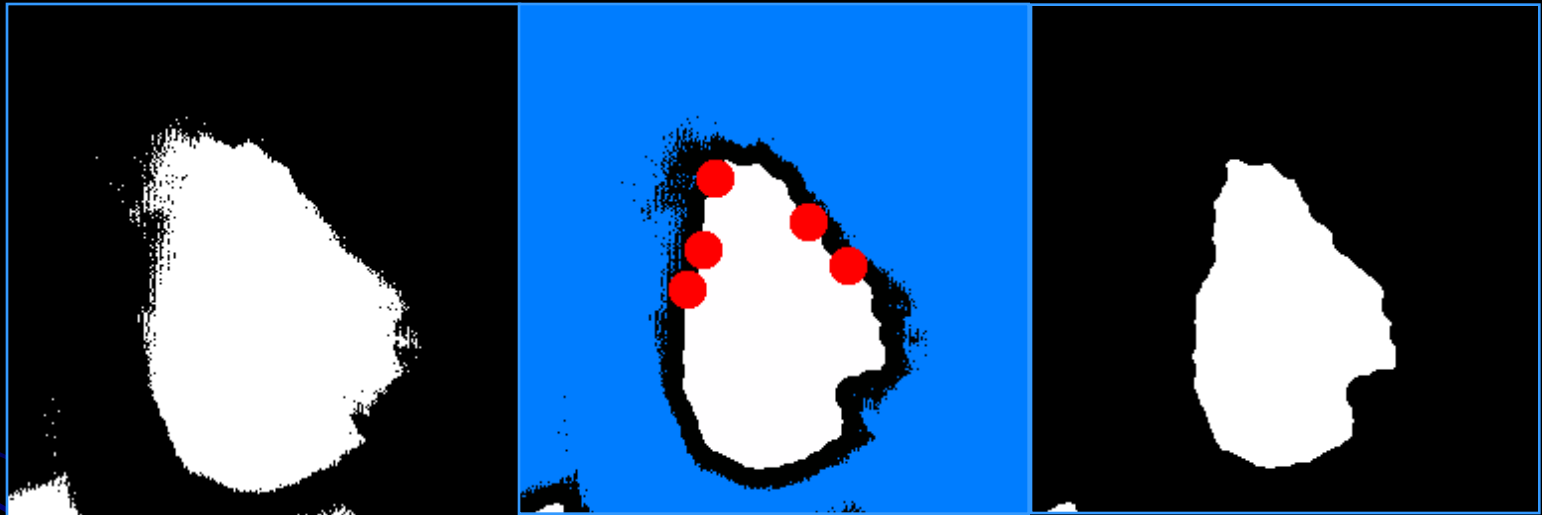
Erózia



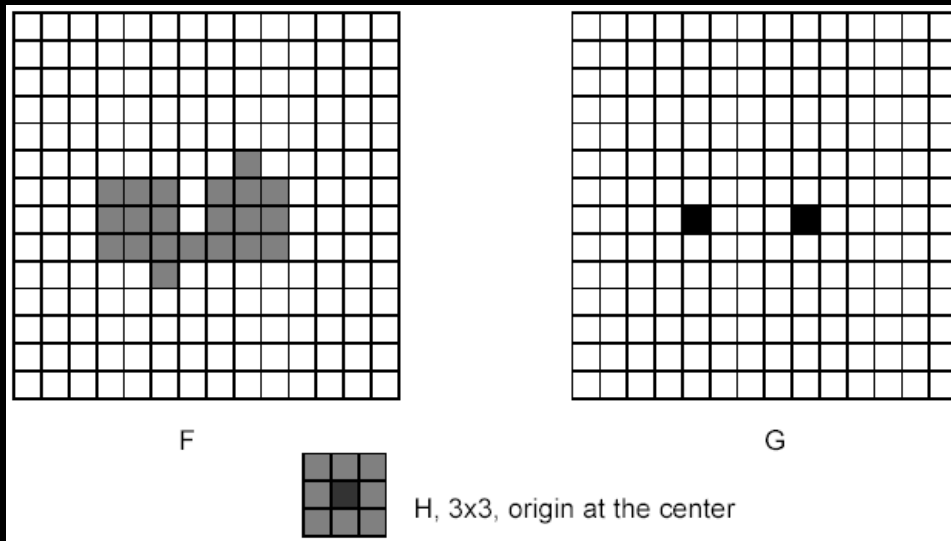
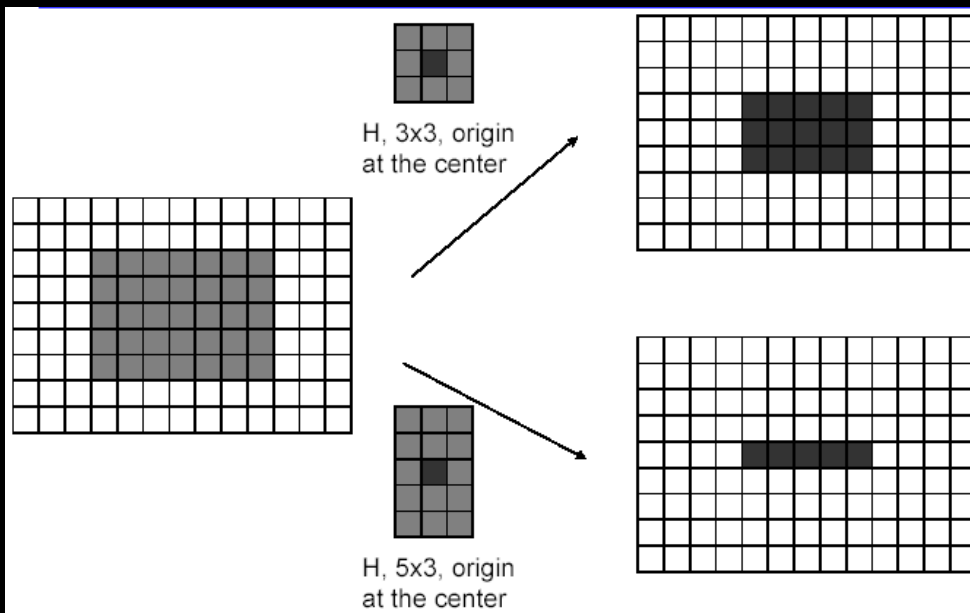
SE=



# Erózia



# Erózia



# Vlastnosti erózie

$$A \ominus B \neq B \ominus A$$

$$A_1 \subseteq A_2 \Rightarrow (A_1 \ominus B) \subseteq (A_2 \ominus B)$$

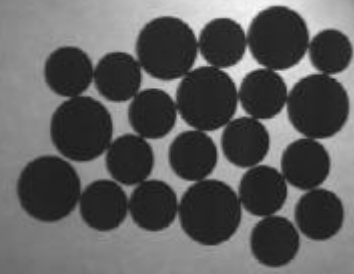
$$B_1 \subseteq B_2 \Rightarrow (A \ominus B_1) \supseteq (A \ominus B_2)$$

$$A \ominus (B \cup C) = (A \ominus B) \cap (A \ominus C)$$

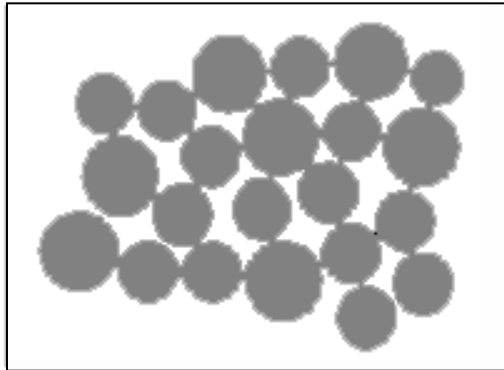
$$(A \ominus B) \ominus C = A \ominus (B \oplus C)$$

$$(A \ominus B) \oplus B \subseteq A \subseteq (A \oplus B) \ominus B$$

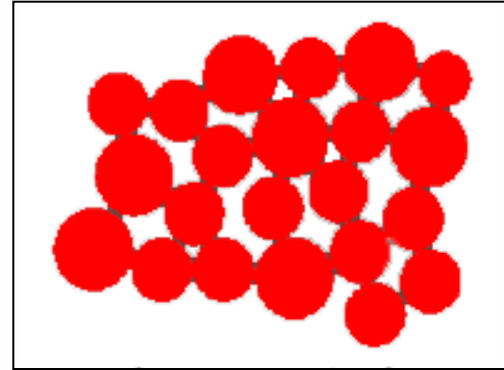
# Príklad použitia



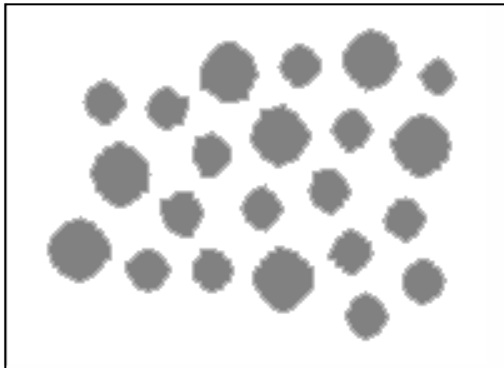
Original



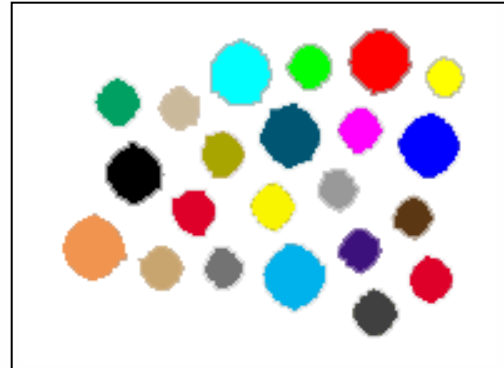
Prahovanie



1 spojitý útvar



Erózia



22 spojitých  
útvárov

# Erózia



THE  
TEST  
IMAGE

Originál



THE  
TEST  
IMAGE

Erodovaný 1x



THE  
TEST  
IMAGE

Erodovaný 2x



# Opakovanie

dilatácia

**Zväčšuje množinu**

Vypĺňa diery, zálivy určitej veľkosti a tvaru

erózia

**Zmenšuje množinu**

Odstraňuje štruktúry určitej veľkosti a tvaru

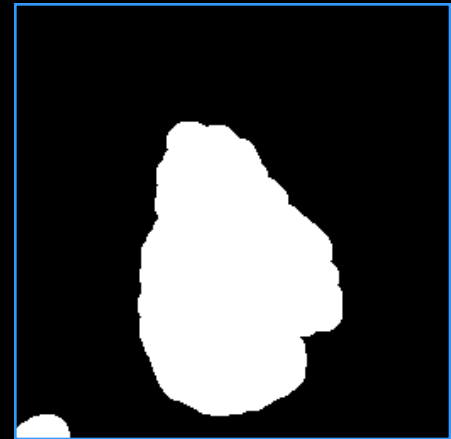
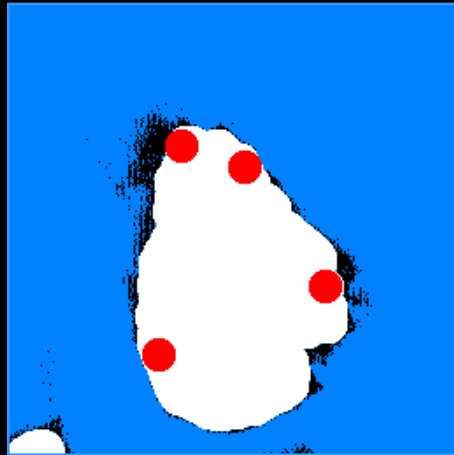
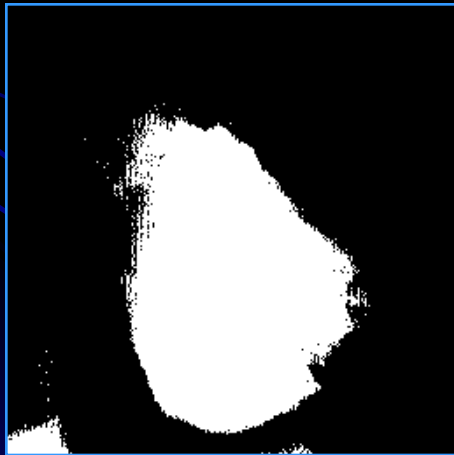
Môže rozdeliť množinu

– v závislosti na štruktúrálom prvku

Interaktívne na <http://dip.sccg.sk/>

# Otvorenie

$$A \circ B = (A \ominus B) \oplus B$$



# Vlastnosti otvorenia

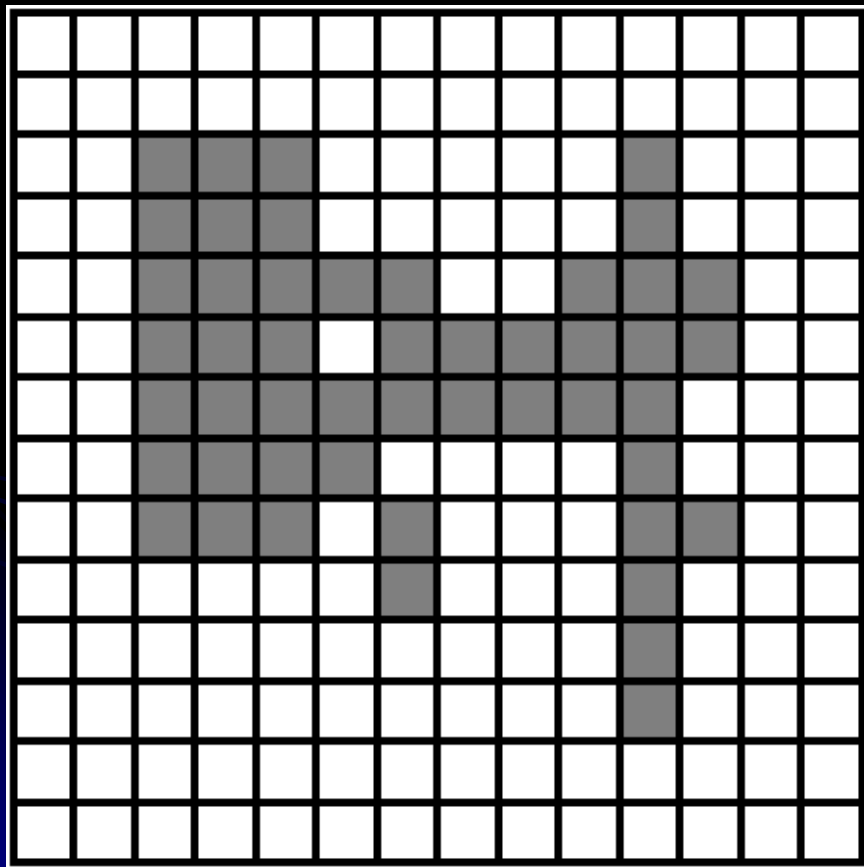
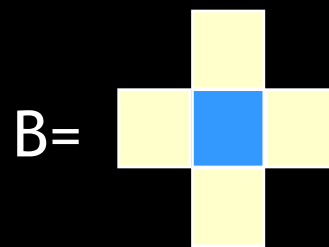
$$A \circ B \subseteq A$$

$$(A \circ B) \circ B = A \circ B$$

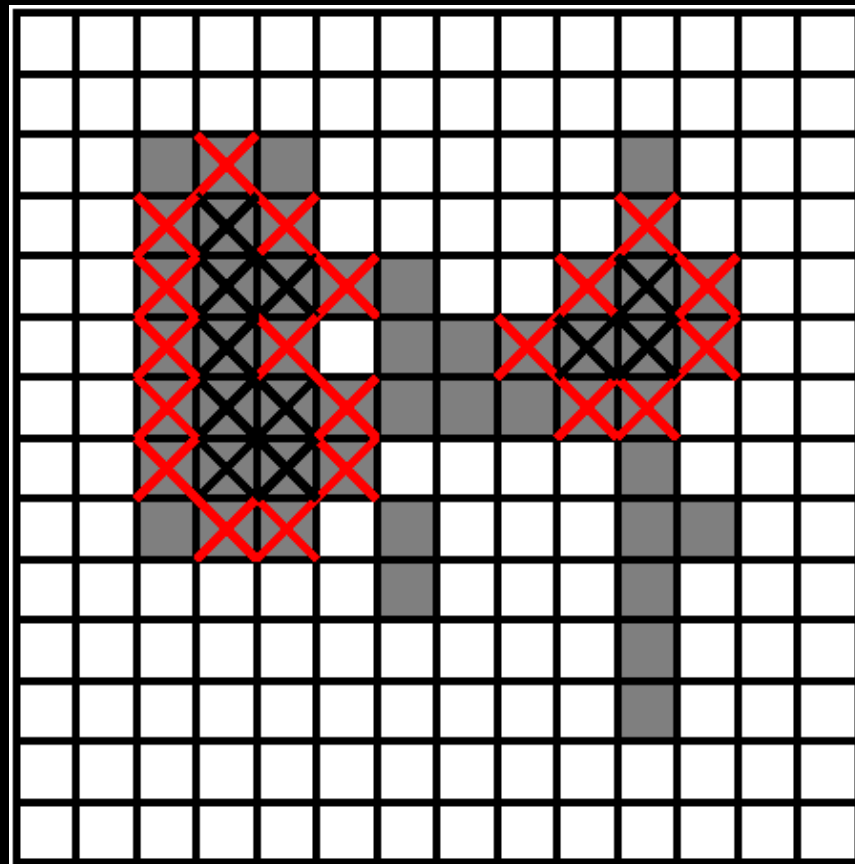


$$A \circ B = (A \ominus B) \oplus B$$

Otvorenie

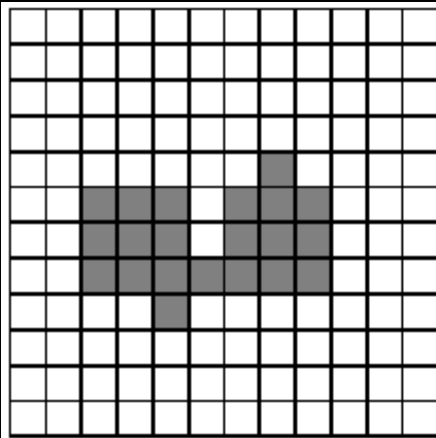


A

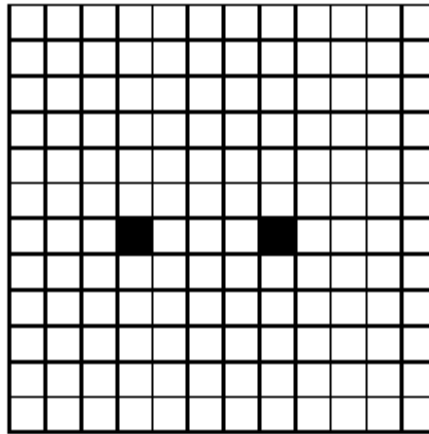


$A \ominus B$   $A \circ B$

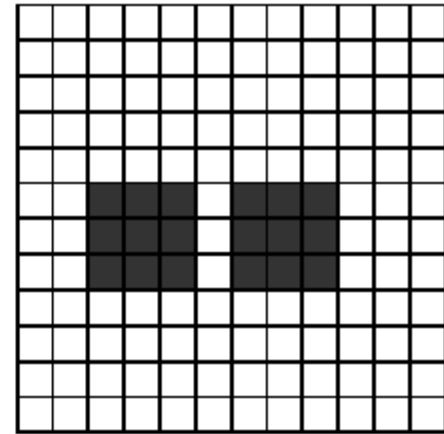
# Otvorenie



F



$F \ominus H$



$(F \ominus H) \oplus H$

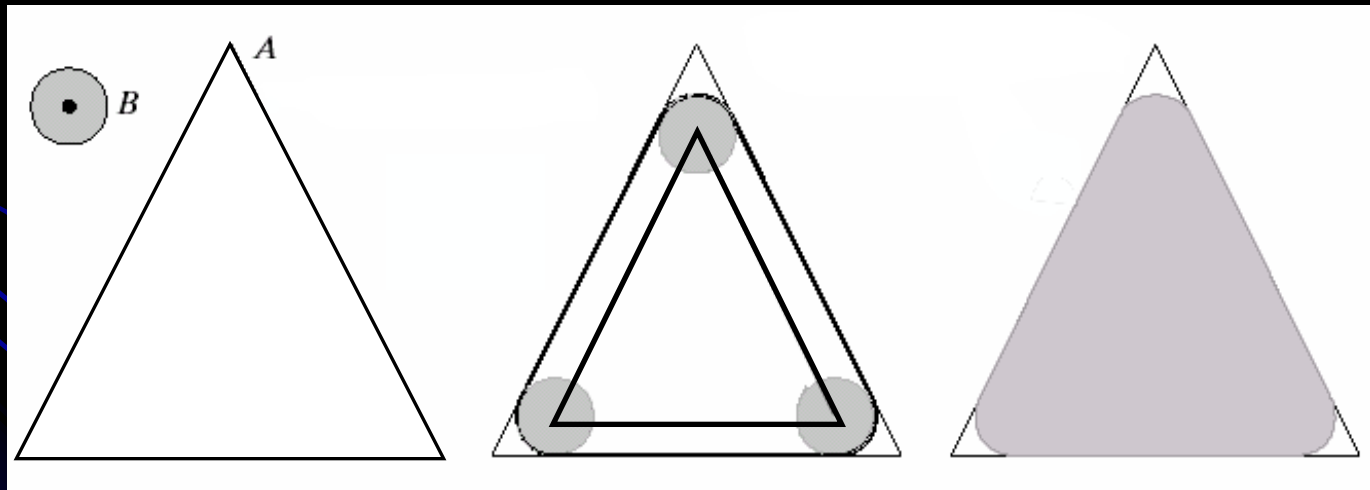


H, 3x3, origin at the center

# Otvorenie

$$A \circ B = \bigcup \{B_x \mid B_x \subseteq A\}$$

posúvame B **po vnútornej strane hranice A**



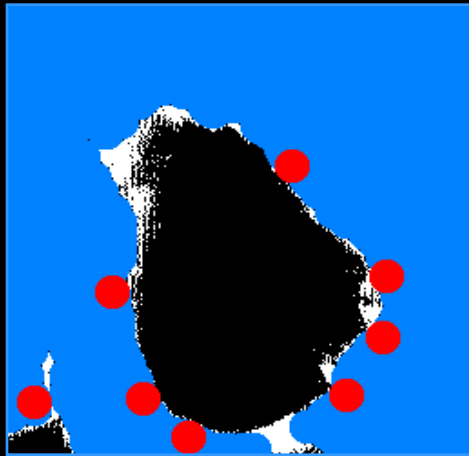
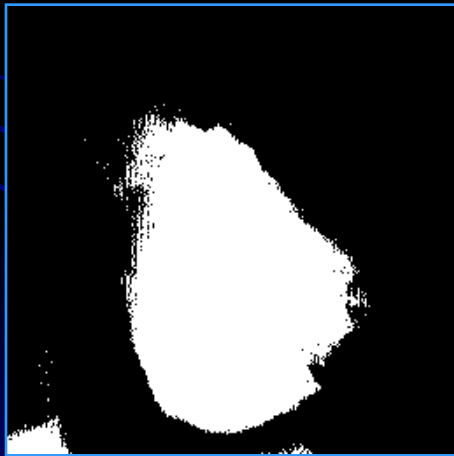
$A \ominus B$

$\oplus B$

$A \circ B$

# Uzavretie

$$A \bullet B = (A \oplus B) \ominus B$$



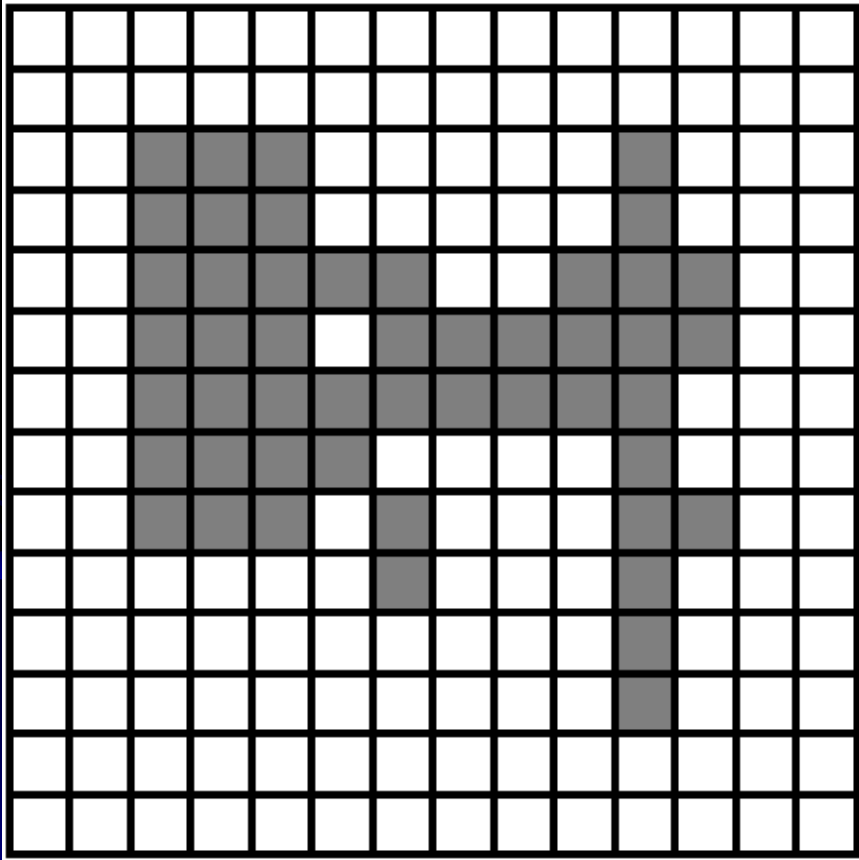
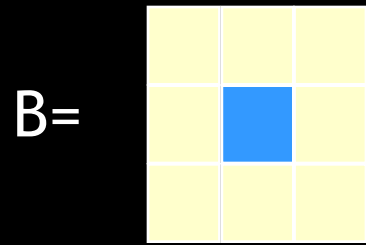


# Vlastnosti uzavretia

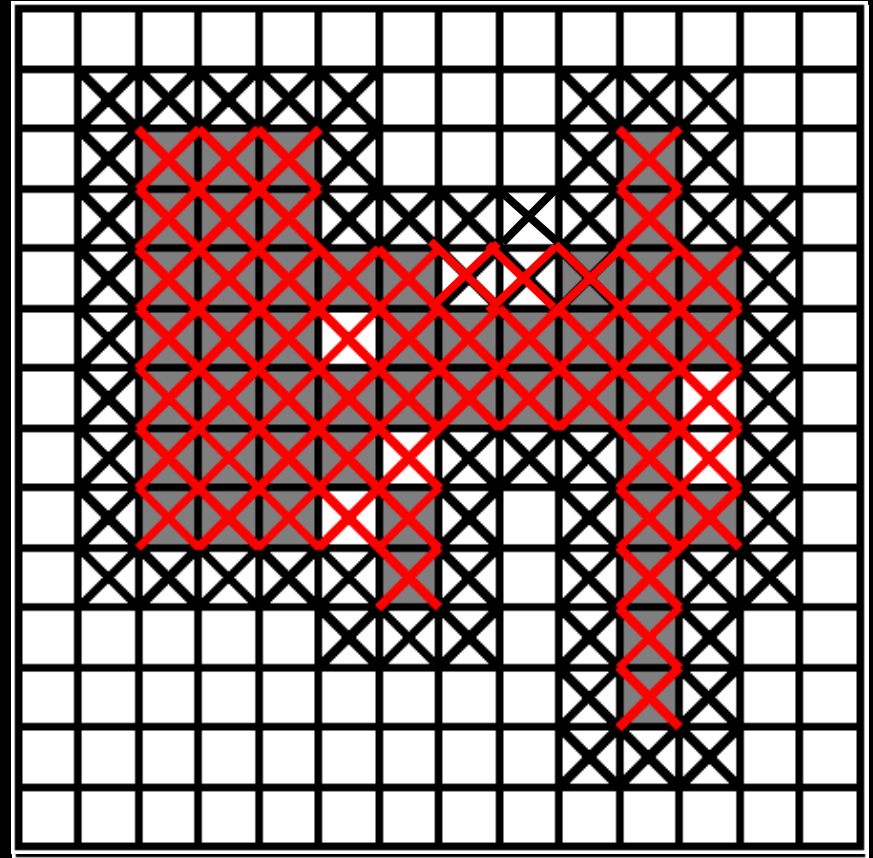
$$A \subseteq A \bullet B$$

$$(A \bullet B) \bullet B = A \bullet B$$

$$A \bullet B = (A \oplus B) \ominus B \quad \text{Uzavretie}$$

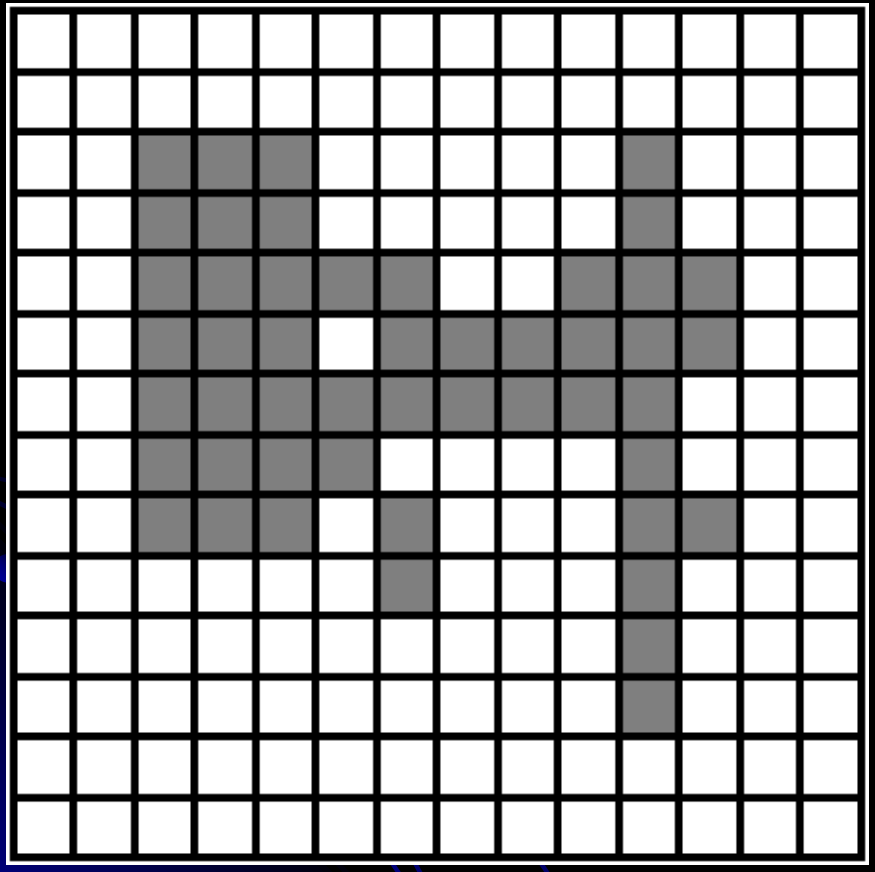
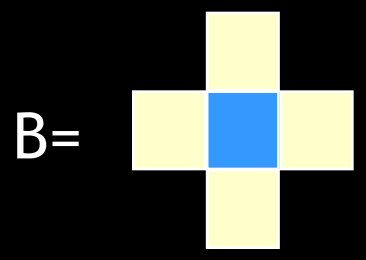


A

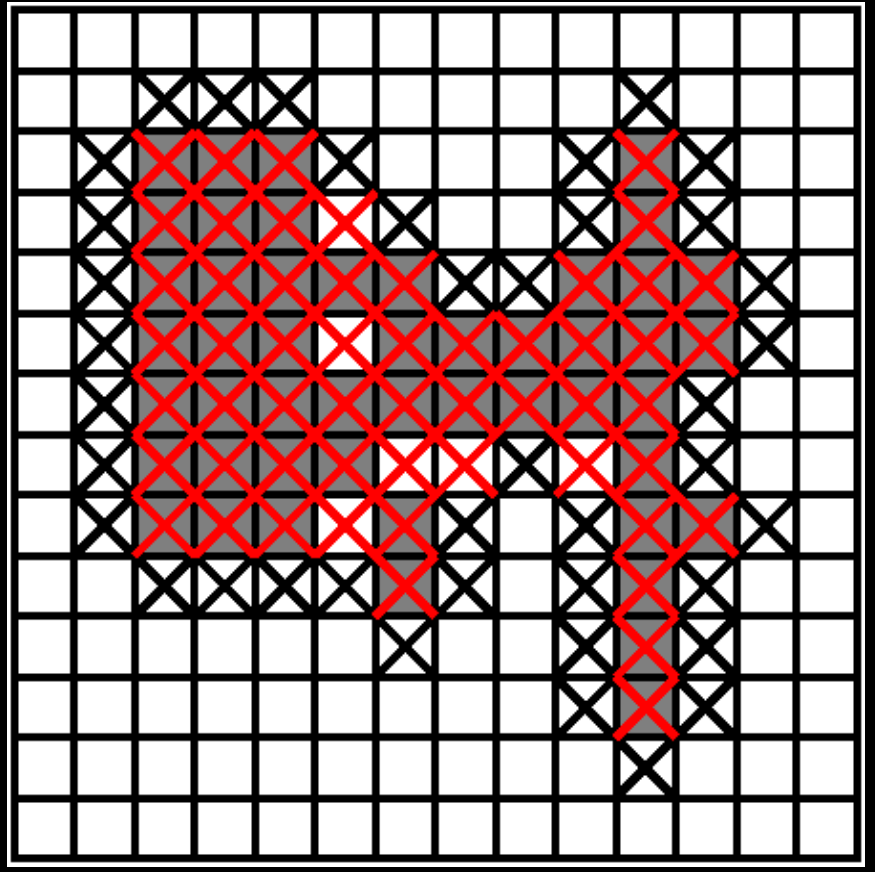


$A \oplus B$   $A \bullet B$

$$A \bullet B = (A \oplus B) \ominus B \quad \text{Uzavretie}$$

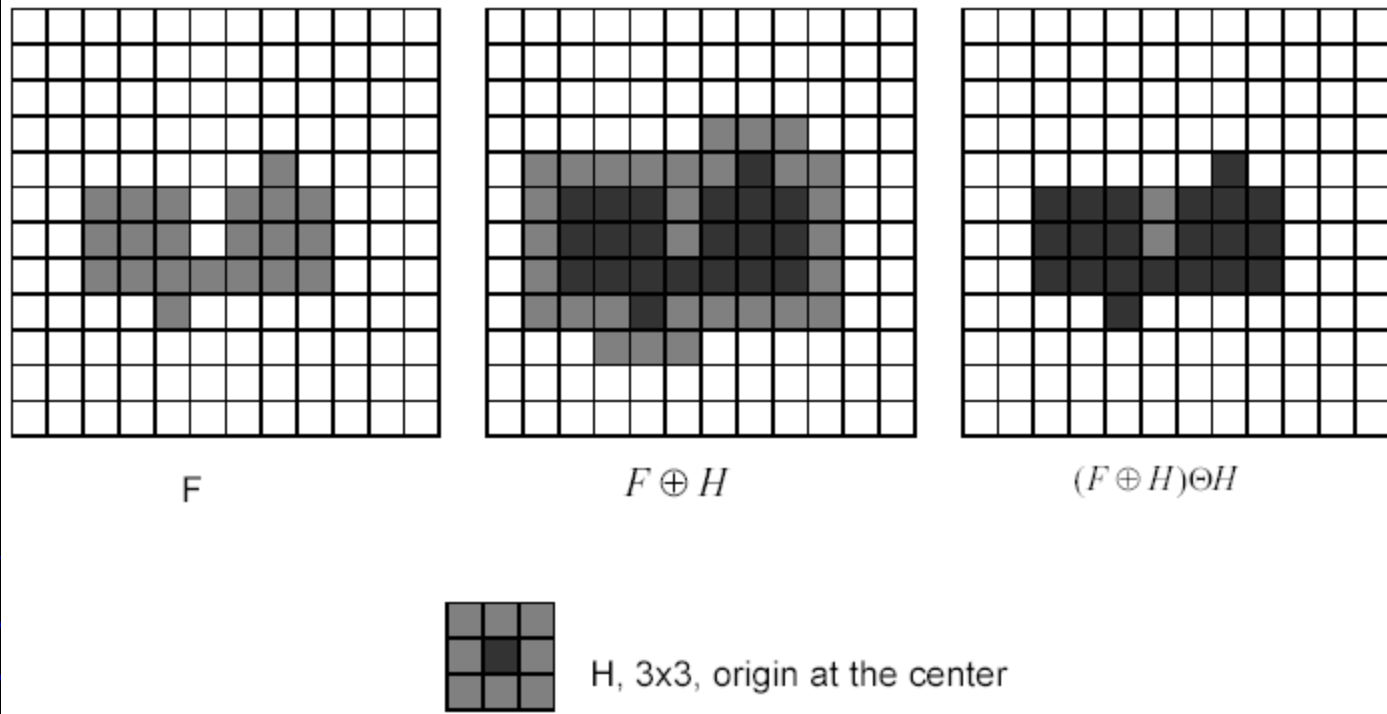


A



$A \oplus B$   $A \bullet B$

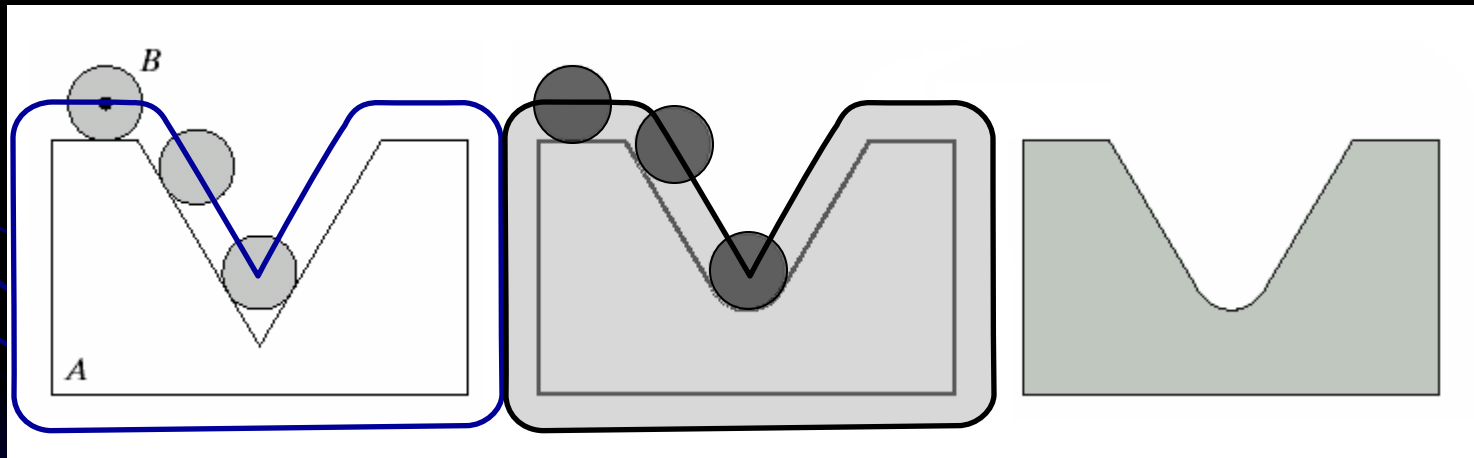
# Uzavretie



# Uzavretie

$$A \bullet B = \{w \mid w \in B_x, B_x \cap A \neq \emptyset\}$$

posúvame B **po vonkajšej strane hranice A**

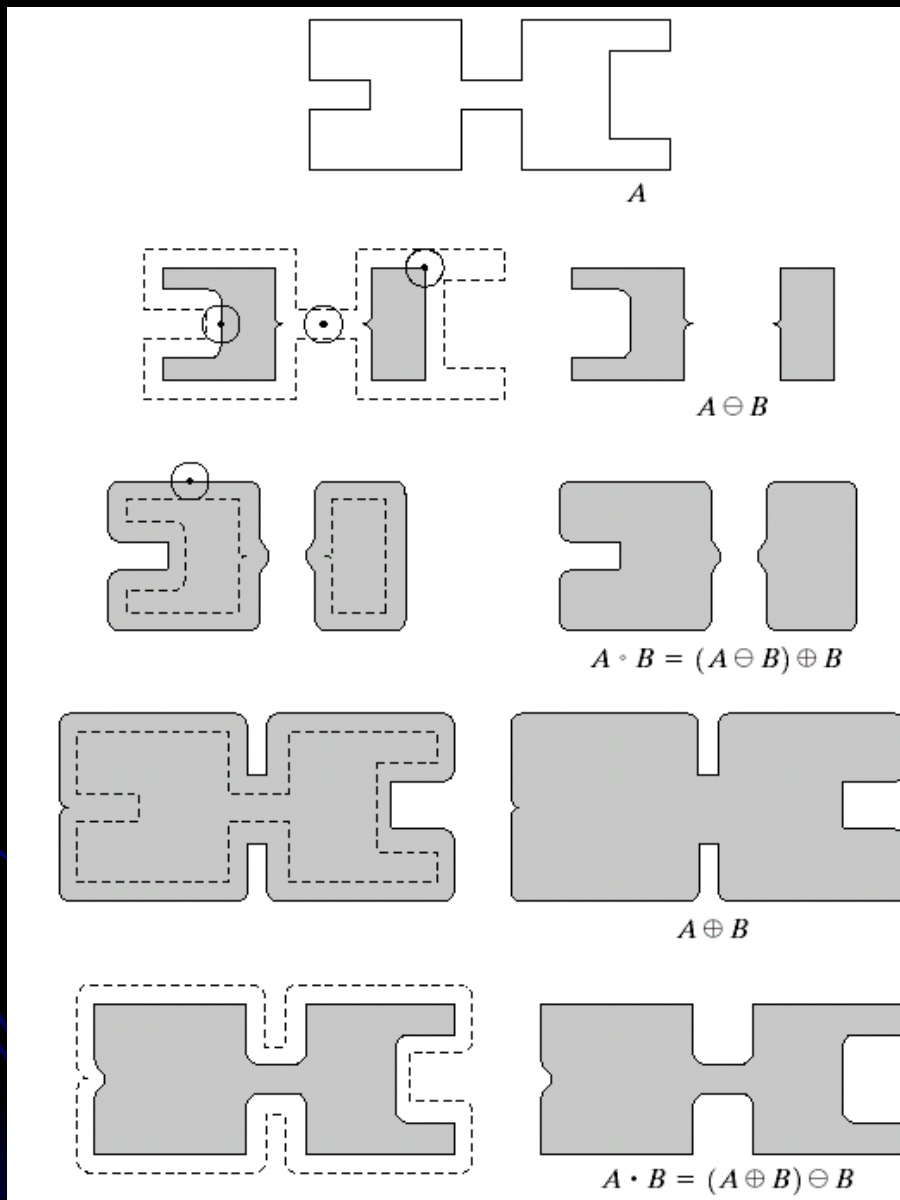


$A \oplus B$

$\ominus B$

$A \bullet B$

# Otvorenie - Uzavretie



# Otvorenie - Uzavretie

THE  
TEST  
IMAGE

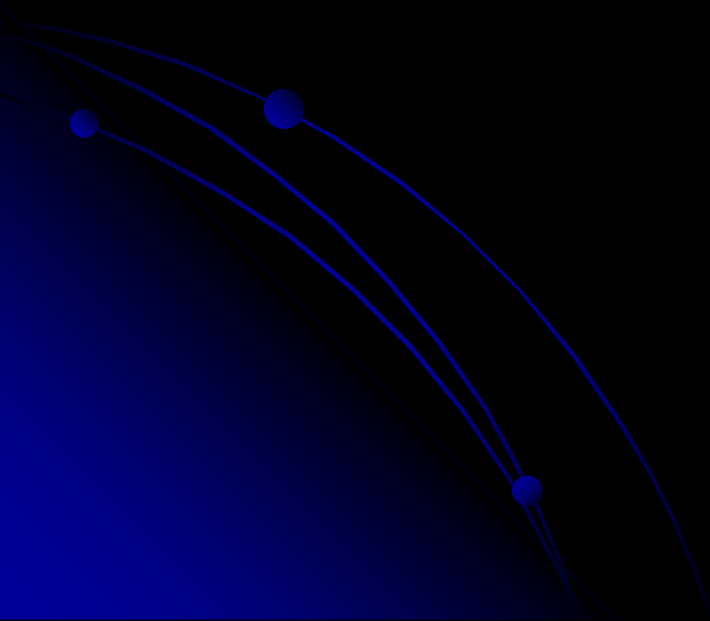
○ THE  
TEST  
IMAGE

THE  
TEST  
IMAGE

• THE  
TEST  
IMAGE

# Dualita

$$(A \bullet E)^c = A^c \circ \hat{E}$$





# Aplikácia: filtrovanie šumu



1. erózia  
 $A \ominus B$



2. dilatácia  
 $(A \ominus B) \oplus B = A \circ B$



3. dilatácia  
 $(A \circ B) \oplus B$



4. erózia  
 $((A \circ B) \oplus B) \ominus B = (A \circ B) \bullet B$

# Opakovanie

otvorenie

erózia + dilatácia

uzavretie

dilatácia + erózia

- vyhladzuje kontúry
- prerušuje tenké spojenia
- maže tenké výčnelky

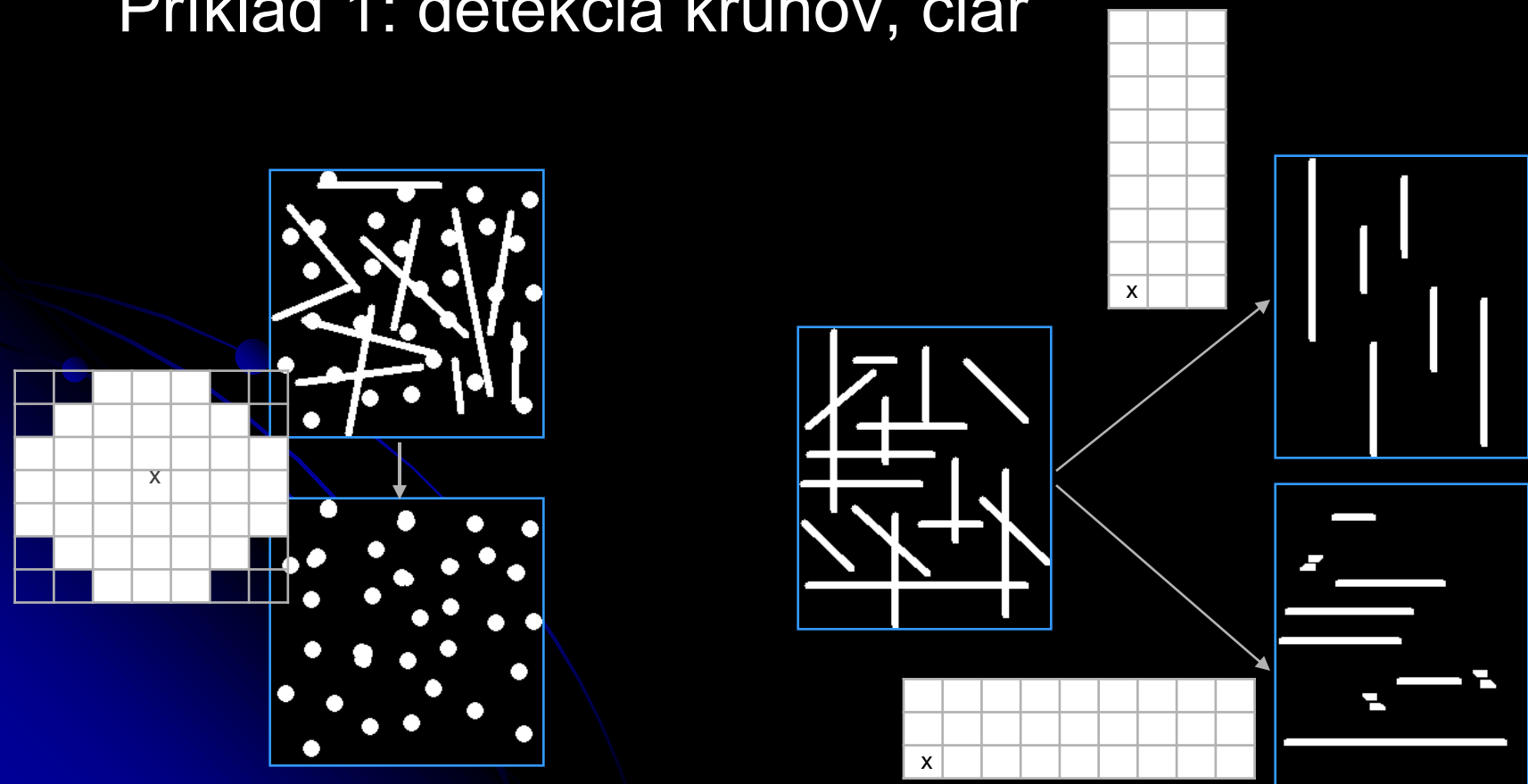
- vyhladzuje kontúry
- spája blízke oblasti
- vyplňa malé diery a tenké zálivy

Zachovávajú (približnú) veľkosť množiny

# Detekcia tvarov

Otvorenie použitím daného štruktúrného prvku

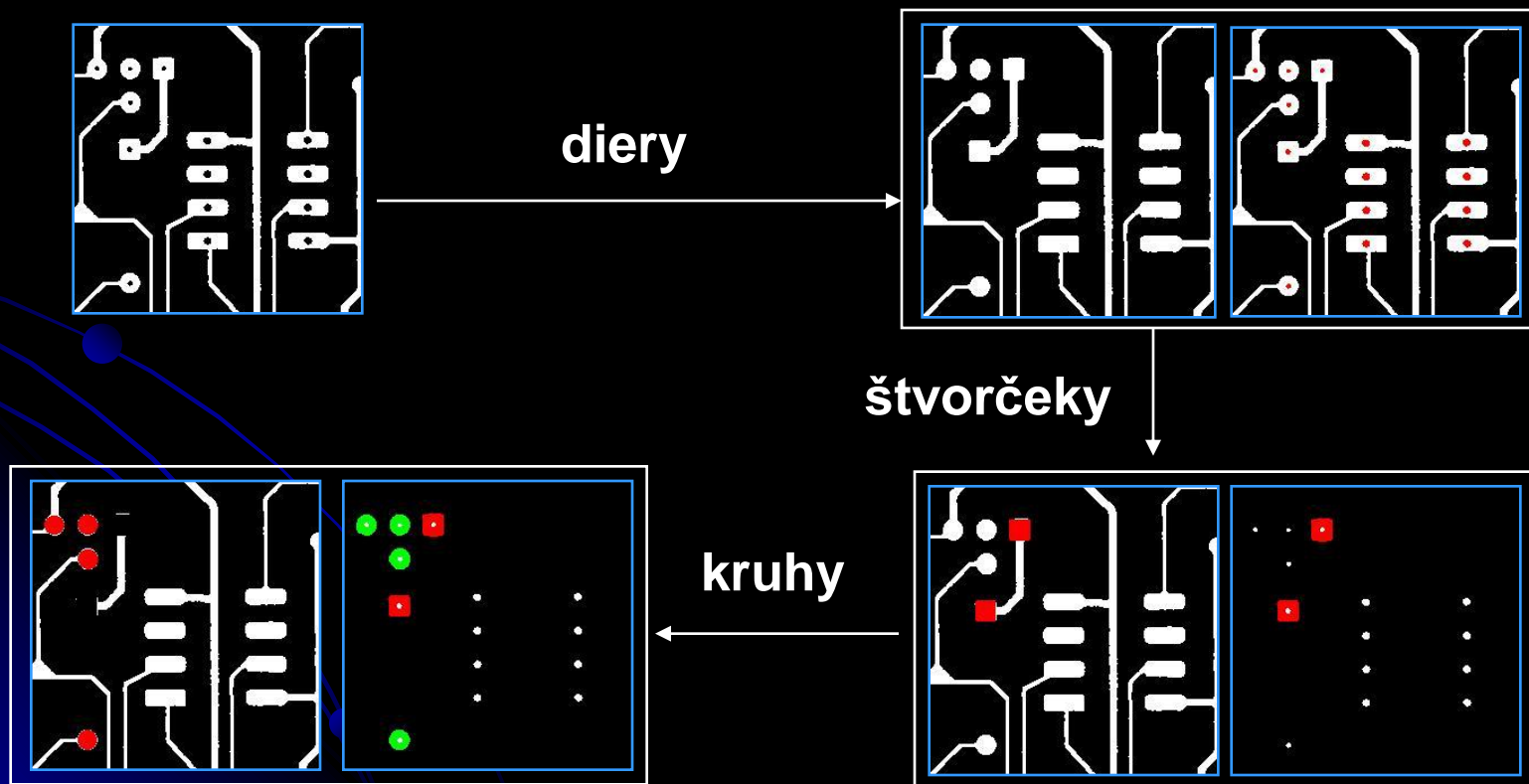
Príklad 1: detekcia kruhov, čiar



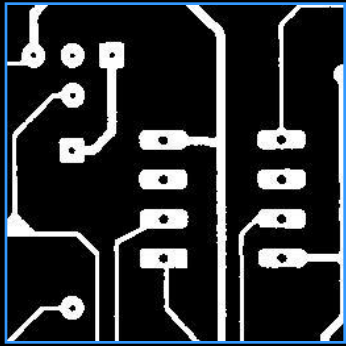
# Detekcia tvarov

Príklad 2:

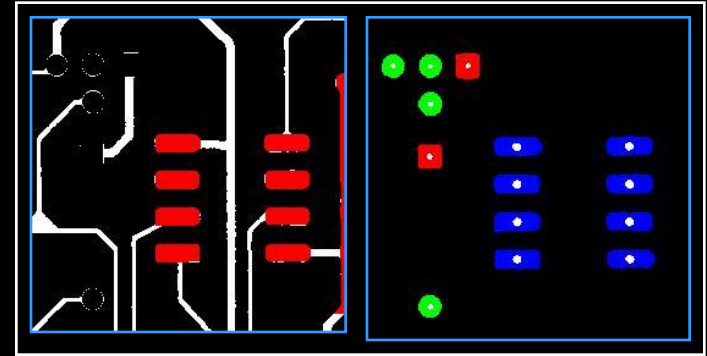
detekcia jednotlivých prvkov plošného spoja



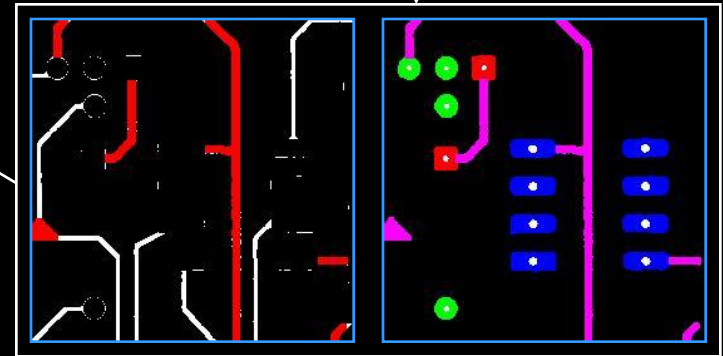
# Detekcia tvarov



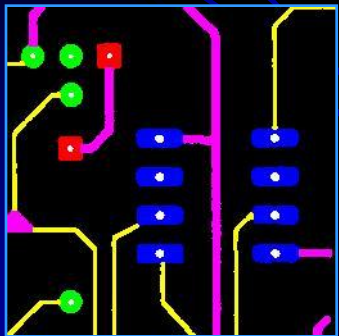
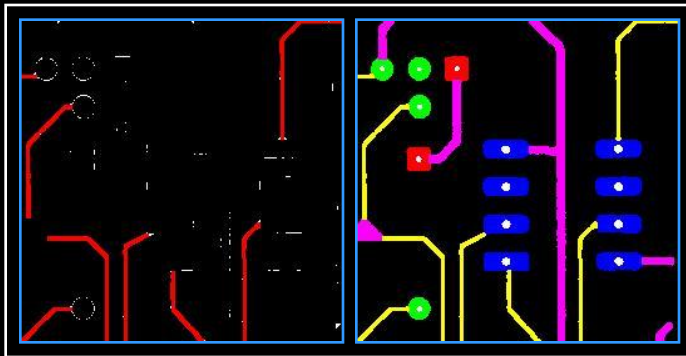
obdĺžniky



hrubé spoje



tenké spoje



# Text

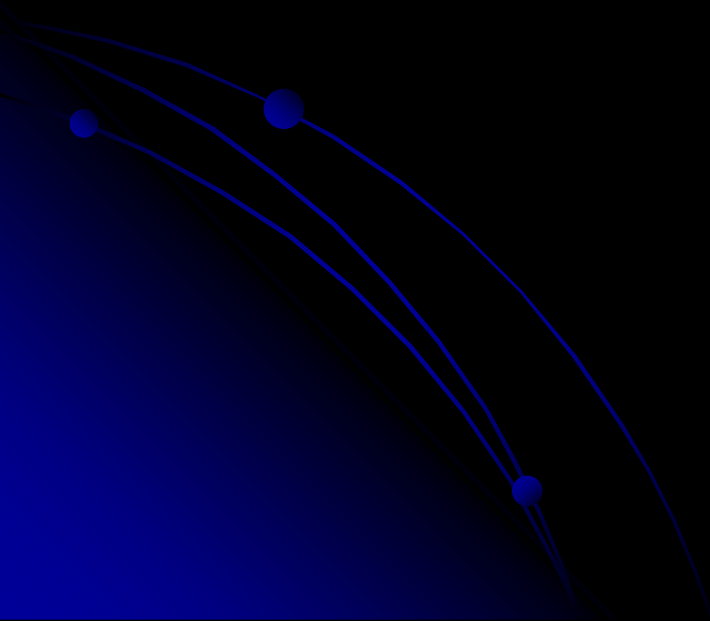


(a)

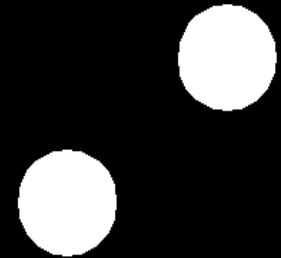
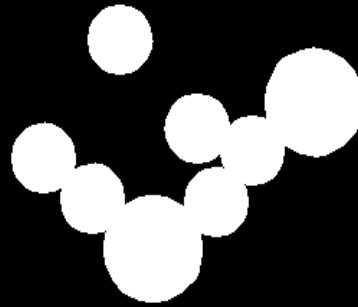
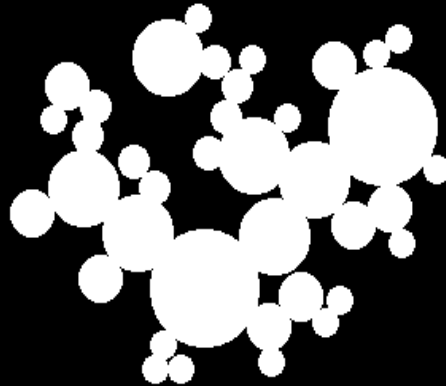
objects in the *real* e e  
object models. This i e e  
cognition effortless e e  
ask for implementa e e  
r we will discuss d e  
echniques that hav e  
We will discuss dif e

(b)

(c)



# Granulometria



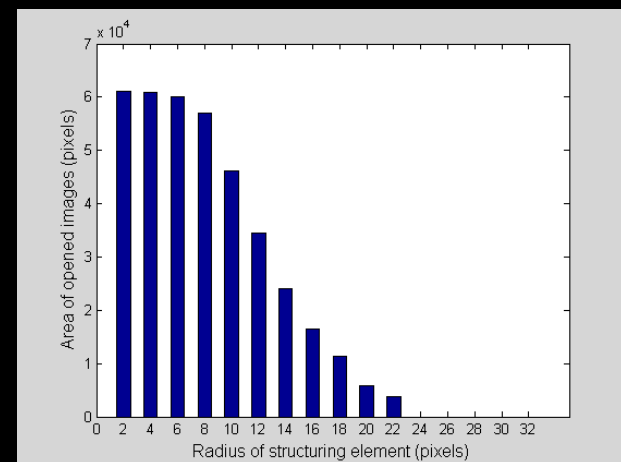
Otvorenie – kruh s priemerom 10, 15 a 25

# Granulometria

Otvorenie so zväčšujúcim sa SE:



Distribúcia veľkosti granúl →





vstup:

štvorice veľkosti

1x1, 3x3, 5x5, 7x7,

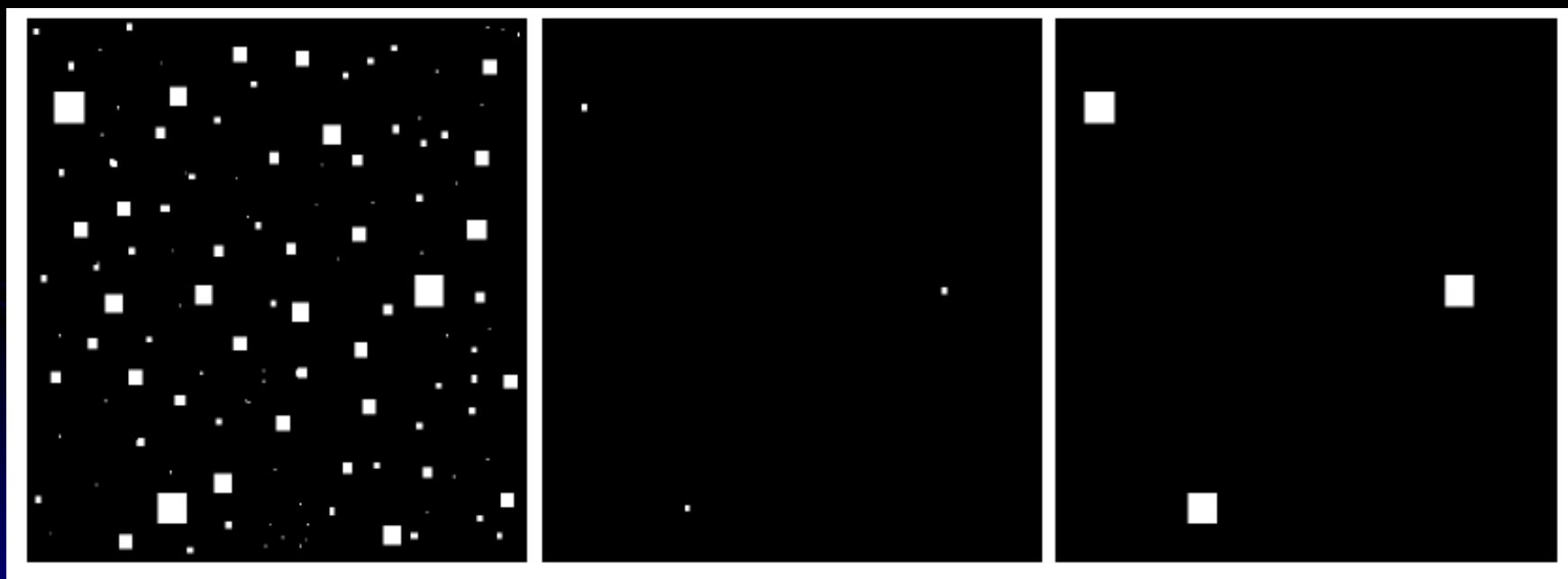
9x9 a 15x15 pixlov

erózia:

ŠP 13x13

dilatácia:

ŠP 13x13



# Hit-and-Miss

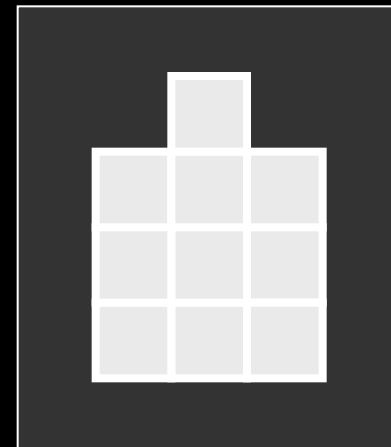
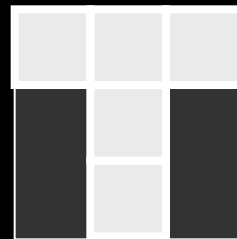
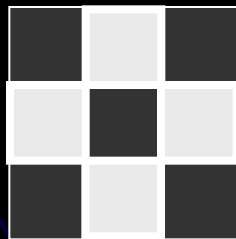
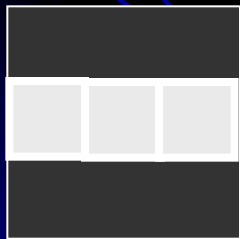
detektor tvarov

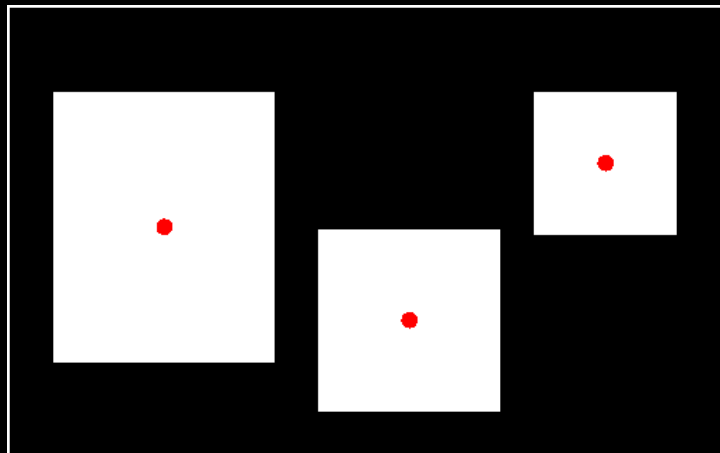
$$A \otimes B = (A \ominus B_1) \cap (A^c \ominus B_2),$$

$$B_1 \cap B_2 = \emptyset, B_1 \cup B_2 = B$$

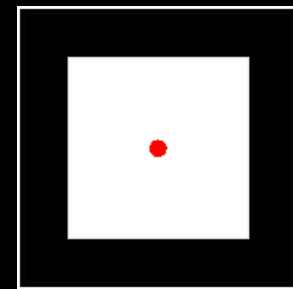
$$A \otimes B = (A \ominus B_1) - (A \oplus \hat{B}_2)$$

”template matching”

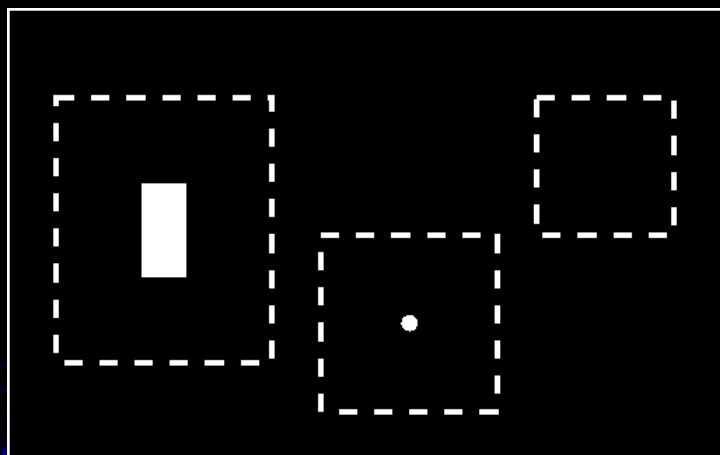




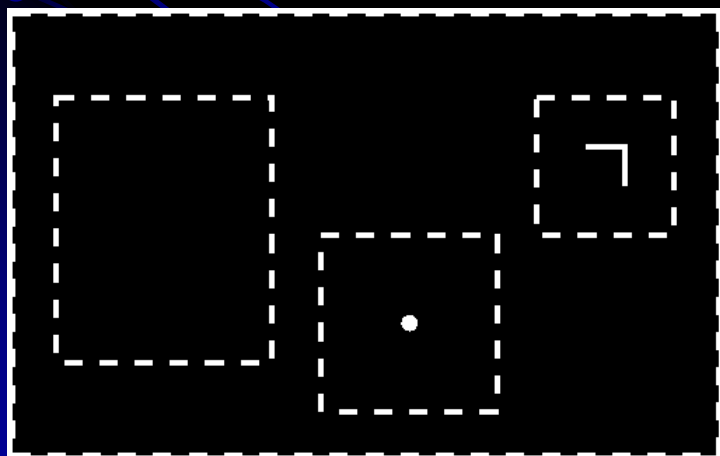
$$A = X \cup Y \cup Z$$



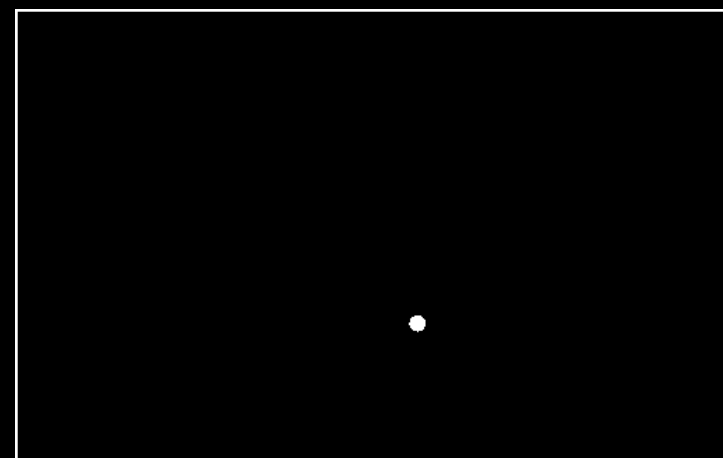
$$B_1 \cup B_2$$



$$A \ominus B_1$$

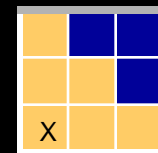
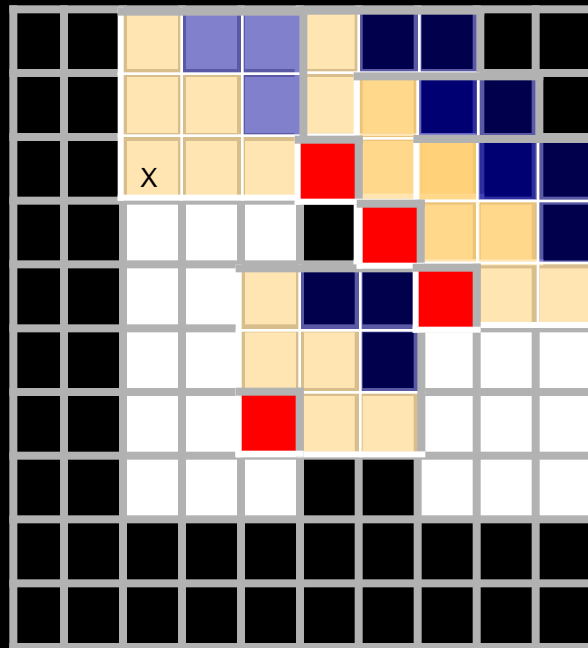


$$A^c \ominus B_2$$

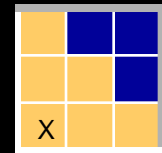
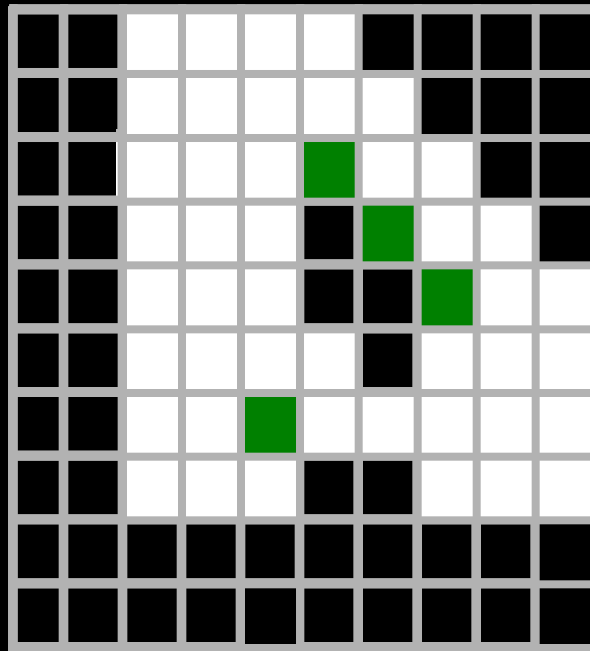


$$A \otimes X = (A \ominus B_1) \cap (A^c \ominus B_2)$$

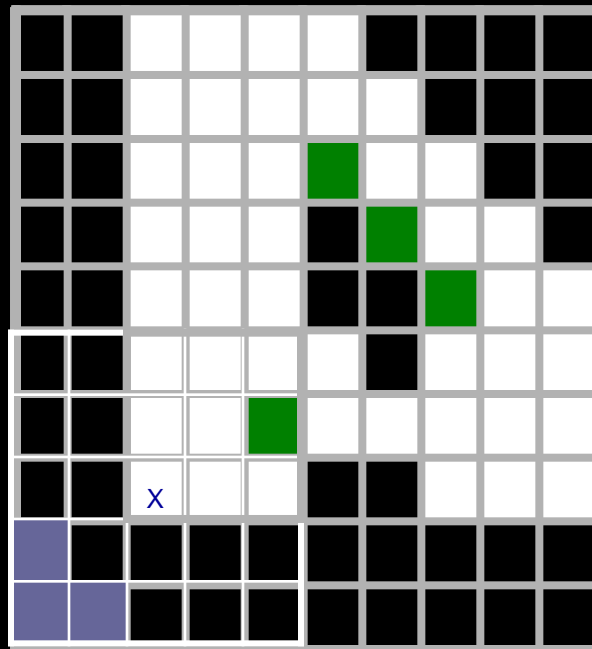
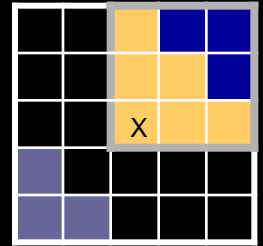
# Hit-and-Miss



# Hit-and-Miss



# Hit-and-Miss

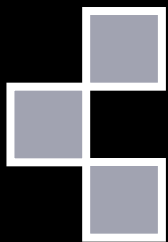


# Hit-and-Miss

koncové body



$B_1$



$B_2$



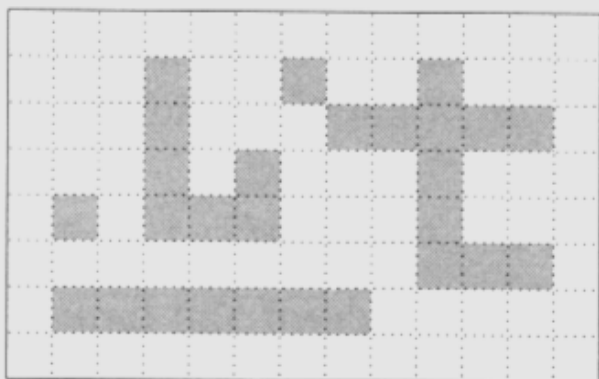
$B_2$



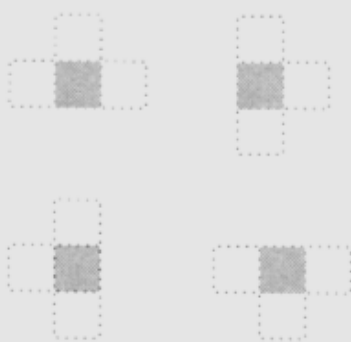
$B_2$



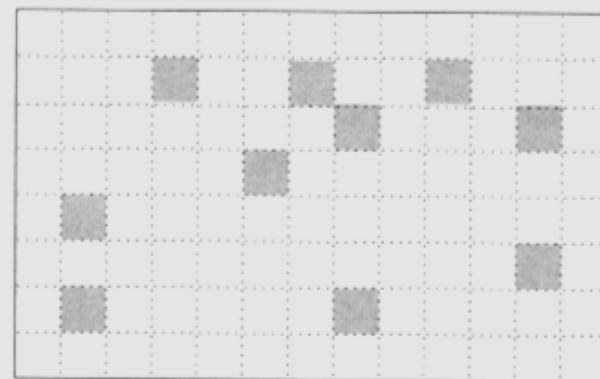
$B_2$



(a) Input image



(b) SEs for 4-connected endpoints

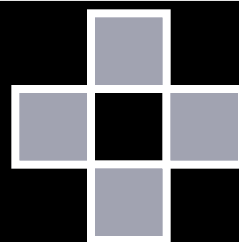


(c) Endpoints of input image

izolované body



$B_1$

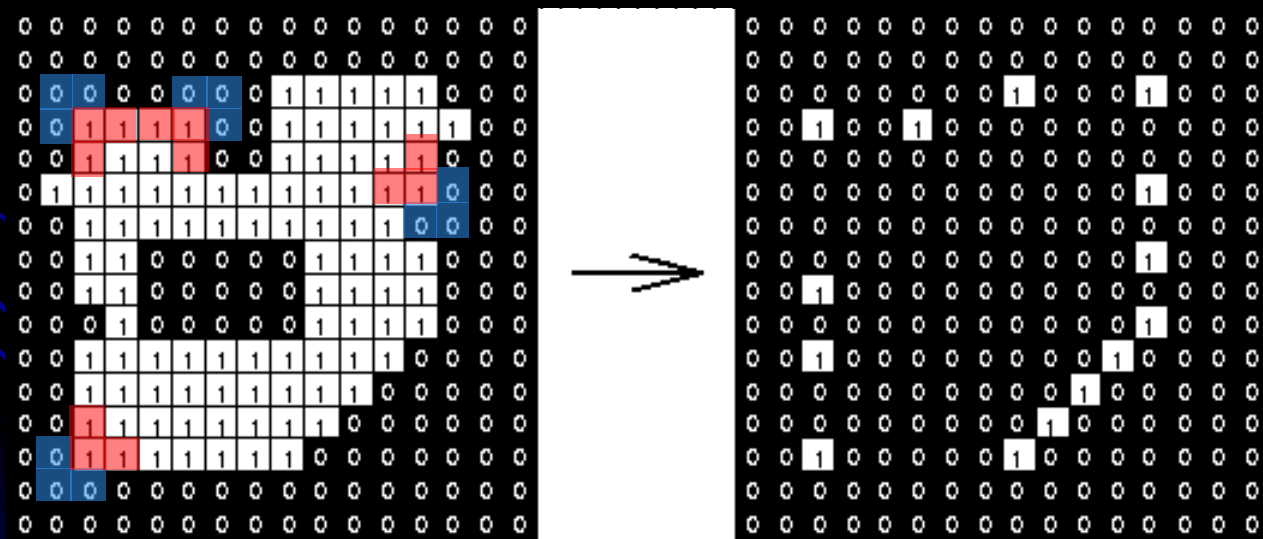


$B_2$

# Hit-and-Miss

Detekcia rohov

	1				1				0	0			0	0	
0	1	1			1	1	0		1	1	0		0	1	1
0	0					0	0			1				1	



Konvexné rohy



# Opakovanie

$\oplus$  dilatácia

$$A \oplus B = \bigcup_{b \in B} A_b$$

$\ominus$  erózia

$$A \ominus B = \bigcap_{b \in B} A_{-b}$$

◦ otvorenie

$$A \circ B = (A \ominus B) \oplus B$$

• uzavretie

$$A \bullet B = (A \oplus B) \ominus B$$

$\otimes$  hit-and-miss

$$A \otimes B = (A \ominus B_1) \cap (A^c \ominus B_2)$$

# Rekurzívna erózia

$$F \ominus^i K = \begin{cases} F & \text{if } i = 0 \\ (F \ominus^{i-1} K) \ominus K & \text{if } i \geq 1 \end{cases}$$

Postupná aplikácia  $K$  – množina sa zmenšuje...  
až zmizne

$$(A \ominus B) \ominus C = A \ominus (B \oplus C)$$

erózia – zväčšujúci sa ŠP „rovnakého“ tvaru

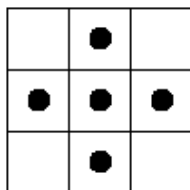
# ŠP

B

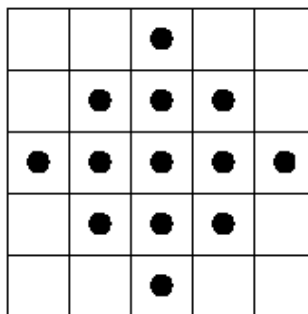
$B \oplus B$

$B \oplus B \oplus B$

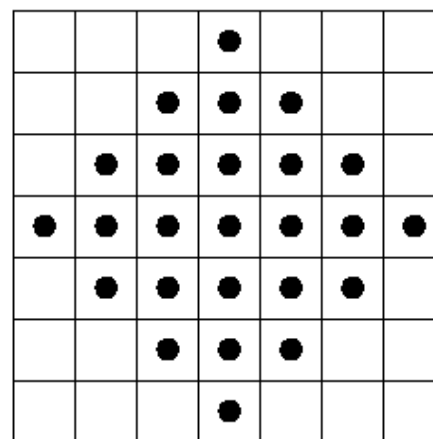
1



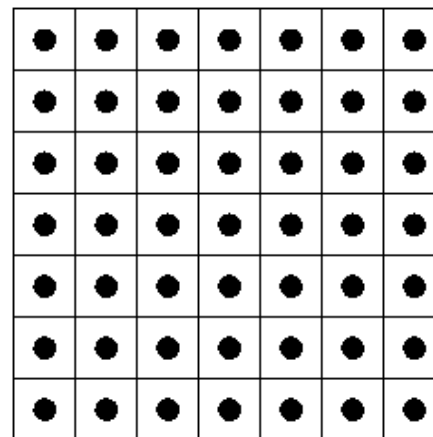
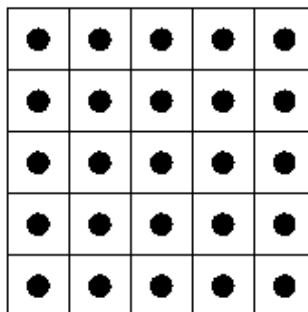
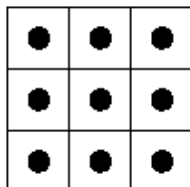
2



3

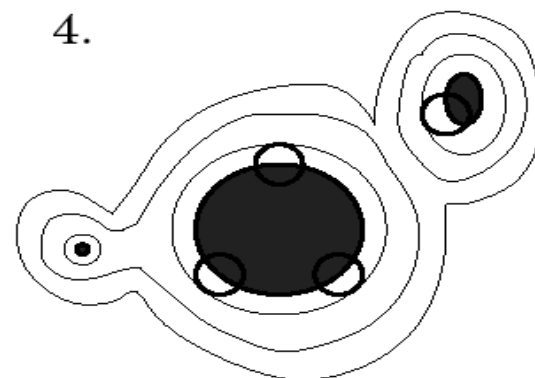
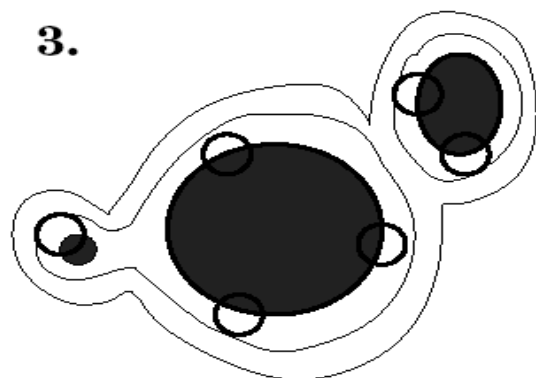
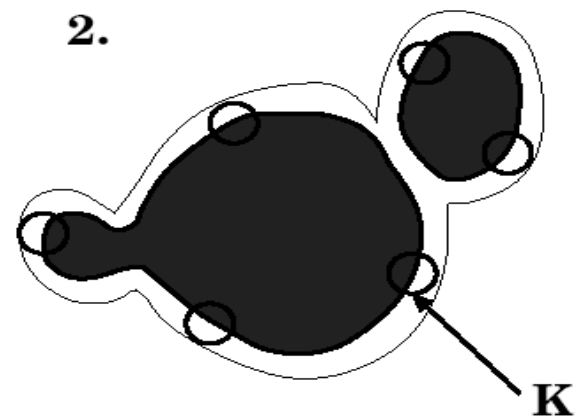
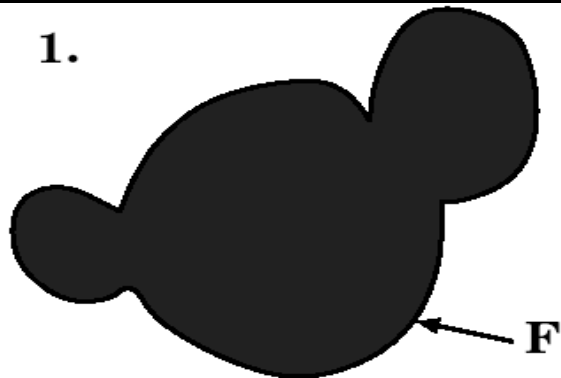


...



...

# Rekurzívna erózia

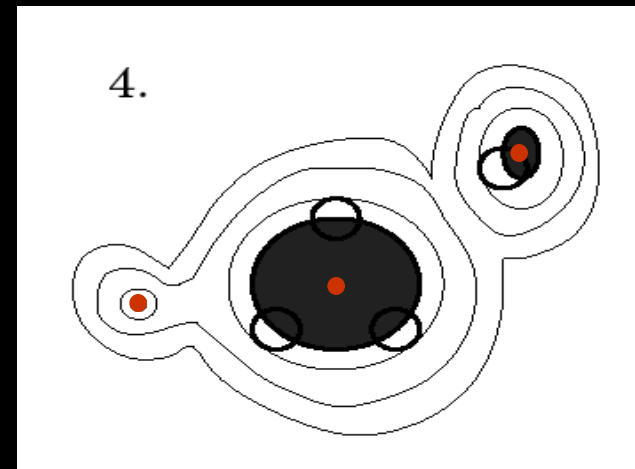


# Ultimatívna erózia

Ultimate Erosion (UE) =

Rekurzívna erózia

Zachováme objekty tesne pred zmiznutím



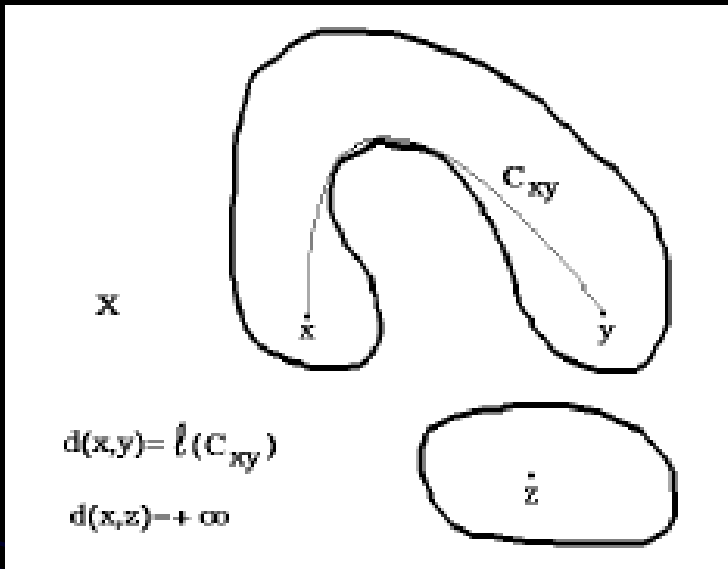
# Rekurzívna dilatácia

$$F \oplus^i K = \begin{cases} F & \text{if } i = 0 \\ (F \oplus^{i-1} K) \oplus K & \text{if } i \geq 1 \end{cases}$$

$$(A \oplus B) \oplus C = A \oplus (B \oplus C)$$

dilatácia – zväčšujúci sa ŠP „rovnakého“ tvaru

# Geodetické transformácie

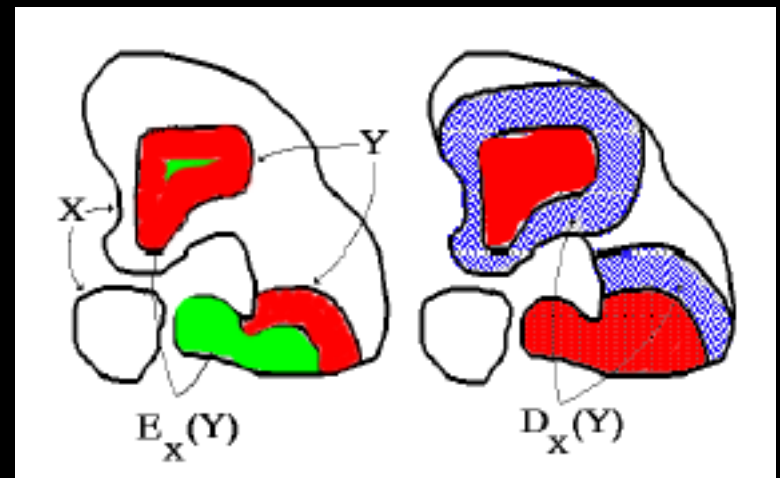


geodetická vzdialenosť  
 $d_X(x,y)$

geodetická (podmienená)  
 dilatácia  
 erózia

$$Y \oplus_X B = (Y \oplus B) \cap X$$

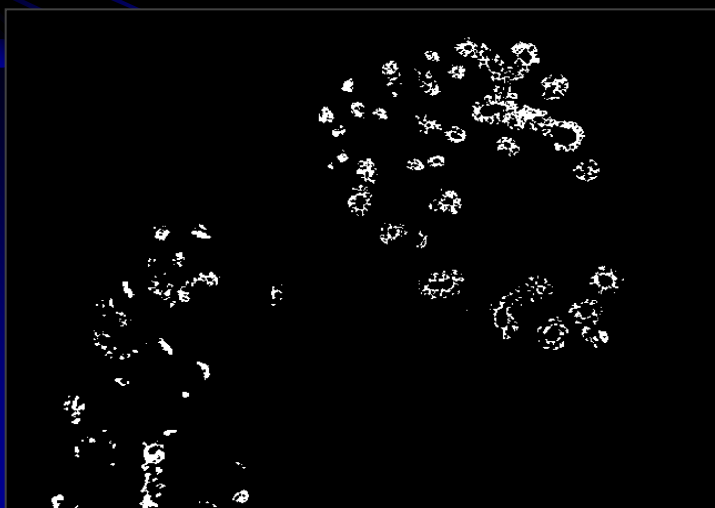
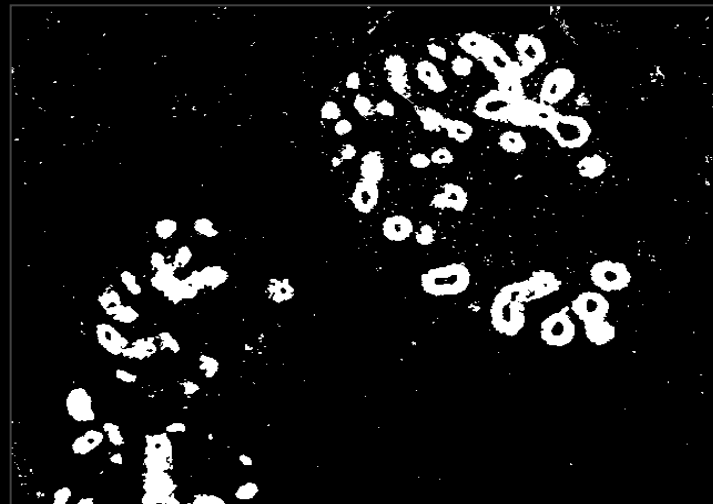
$$Y \ominus_X B = (Y \ominus B) \cap X$$



# Podmienenená dilatácia

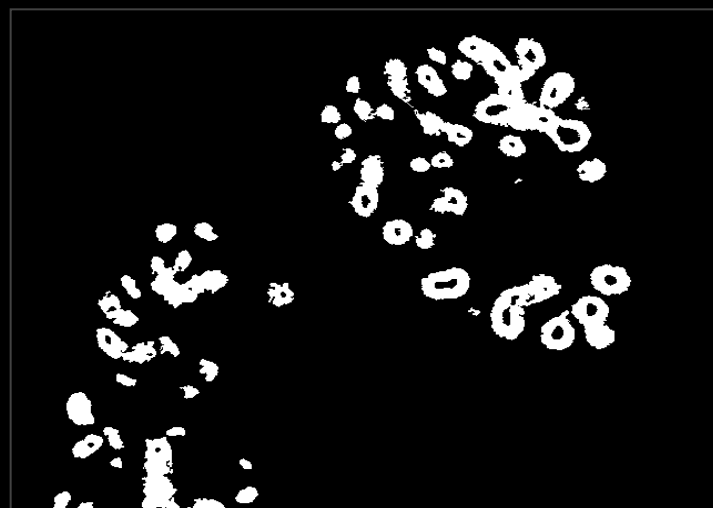


C



A

$$(A \oplus B) \cap C$$

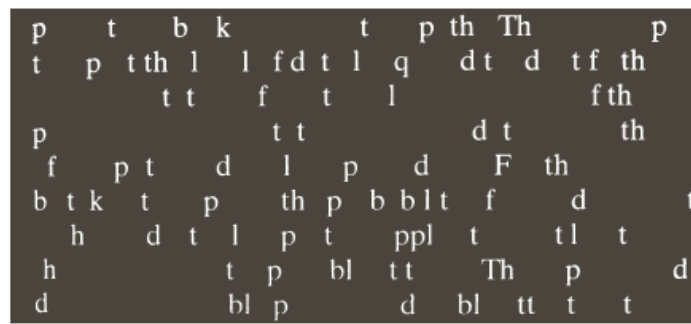
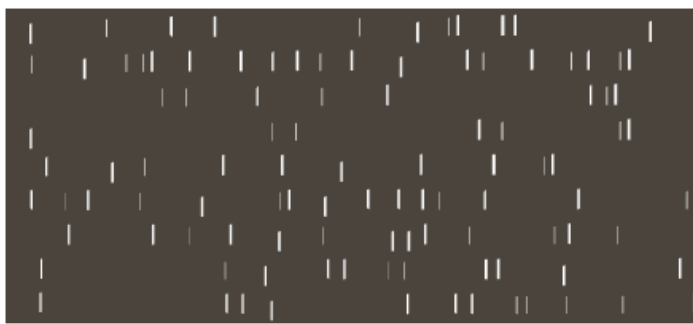
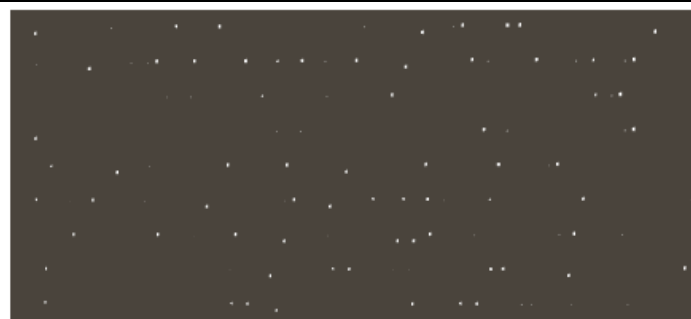




# Podmienená dilatácia

ponents or broken connection paths. There is no point past the level of detail required to identify those

Segmentation of nontrivial images is one of the most difficult tasks in image processing. Segmentation accuracy determines the effectiveness of computerized analysis procedures. For this reason, considerable attention should be taken to improve the probability of rugged segmentation. In applications such as industrial inspection applications, at least some degree of segmentation accuracy in the environment is possible at times. The experienced image processing designer invariably pays considerable attention to such



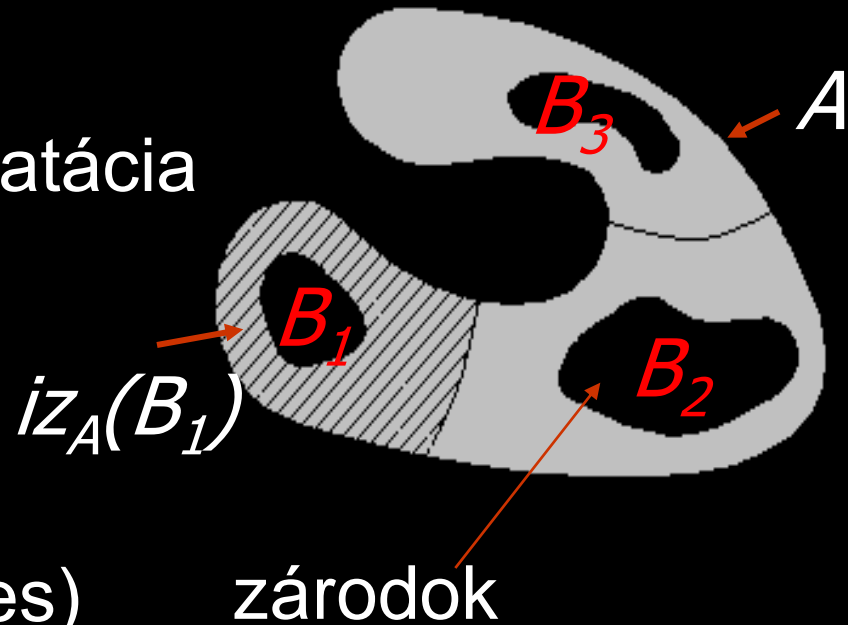
a	b
c	d

**FIGURE 9.29** (a) Text image of size  $918 \times 2018$  pixels. The approximate average height of the tall characters is 50 pixels. (b) Erosion of (a) with a structuring element of size  $51 \times 1$  pixels. (c) Opening of (a) with the same structuring element, shown for reference. (d) Result of opening by reconstruction.

# Geodetický vplyv

Geodesic Influence (GI) =  
Rekurzívna podmienená dilatácia

– rozdelí množinu



Zóny vplyvu (influence zones)

zárodok

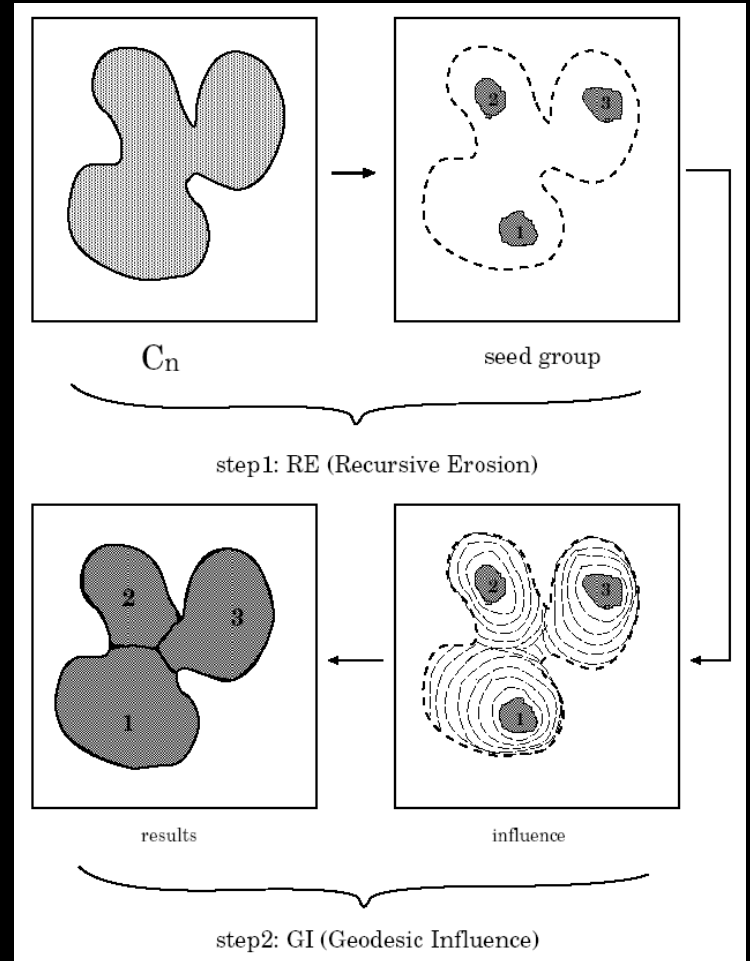
$$iz_A(B_i) = \{p \in A, \forall j \neq i \ d_A(p, B_i) < d_A(p, B_j)\}$$

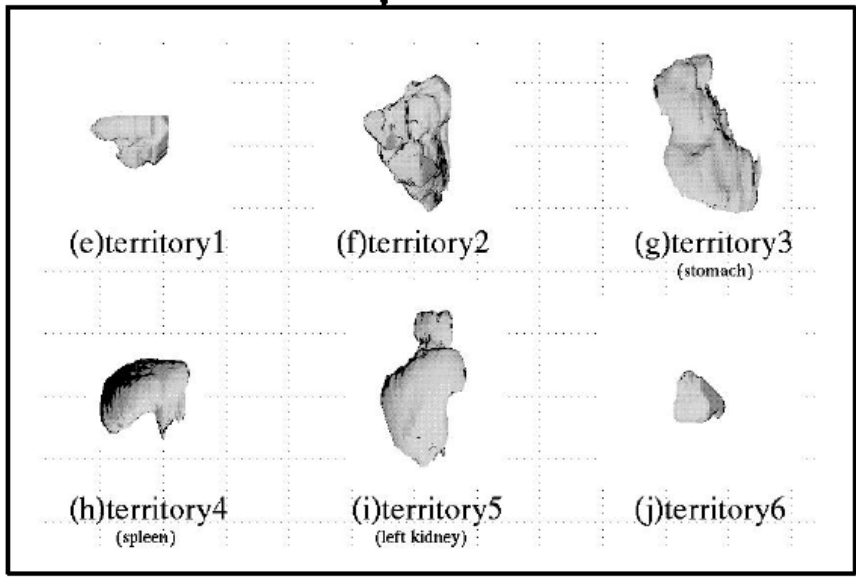
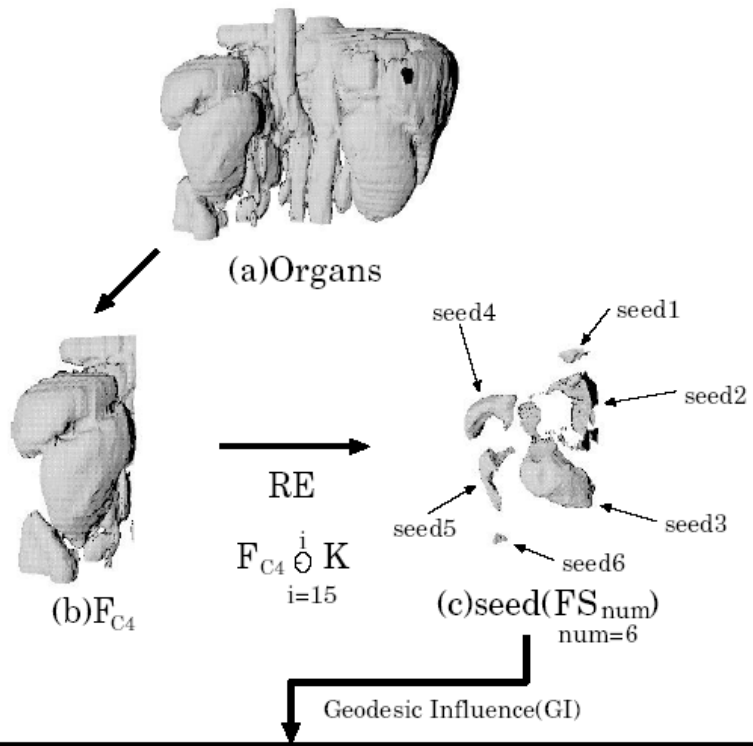
Voronoi diagram

# UE a GI

**UE:** rozdelí región, zachová zárodky

**GI:** zo zárodkov rekonštruuje objekt

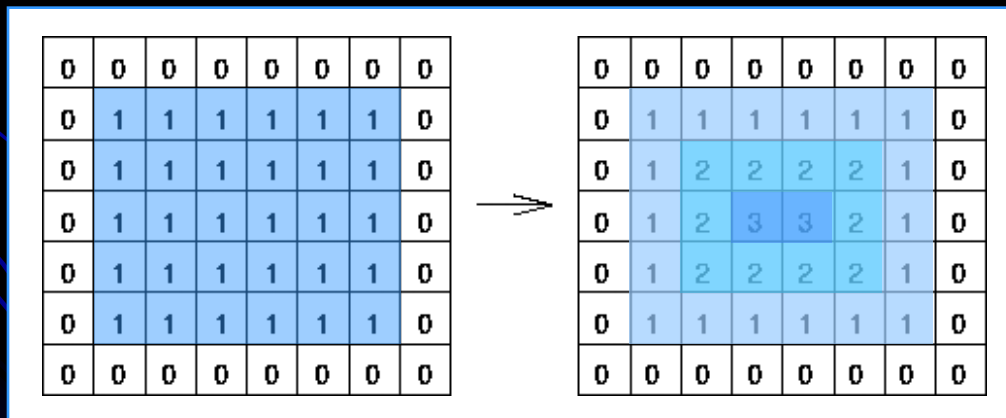




# Distance Transform

Operátor aplikovaný na binárne obrázky

Úrovne šedej = vzdialenosť od najbližšieho okraja



# Distance Transform

Rekurzívna erózia – kým útvar nezmizne

Vzdialenosť – číslo iterácie pri zmiznutí bodu

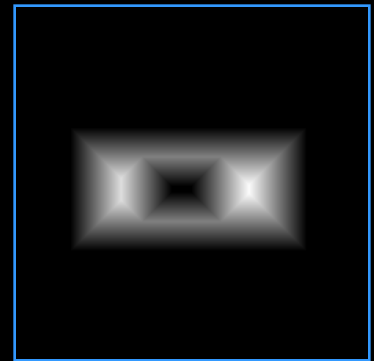
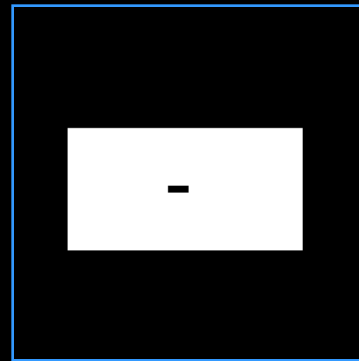
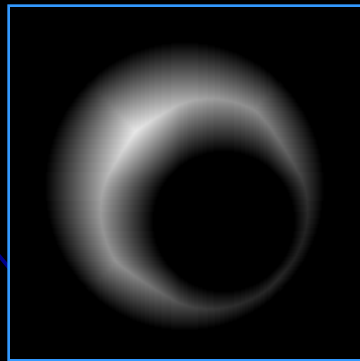
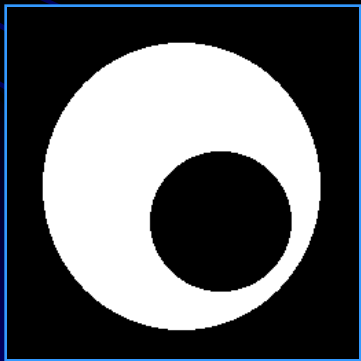
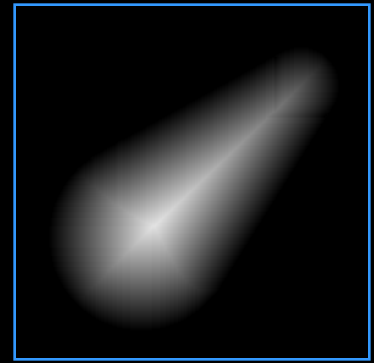
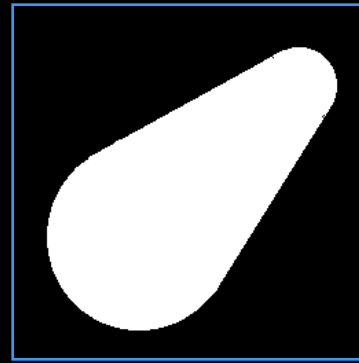
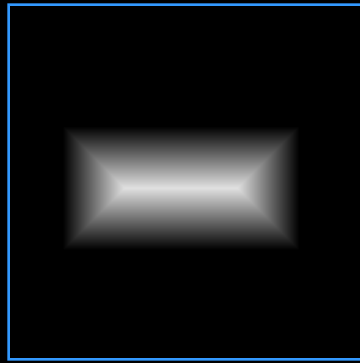
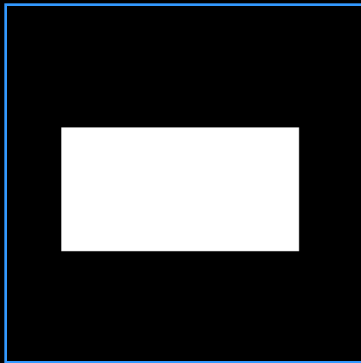
Vhodné ŠP:

štvorcový – chessboard

křížový – city block

kruhový – Euklidovská

# Distance Transform



# Hľadanie hranice

dilatácia – erózia

Algoritmy:

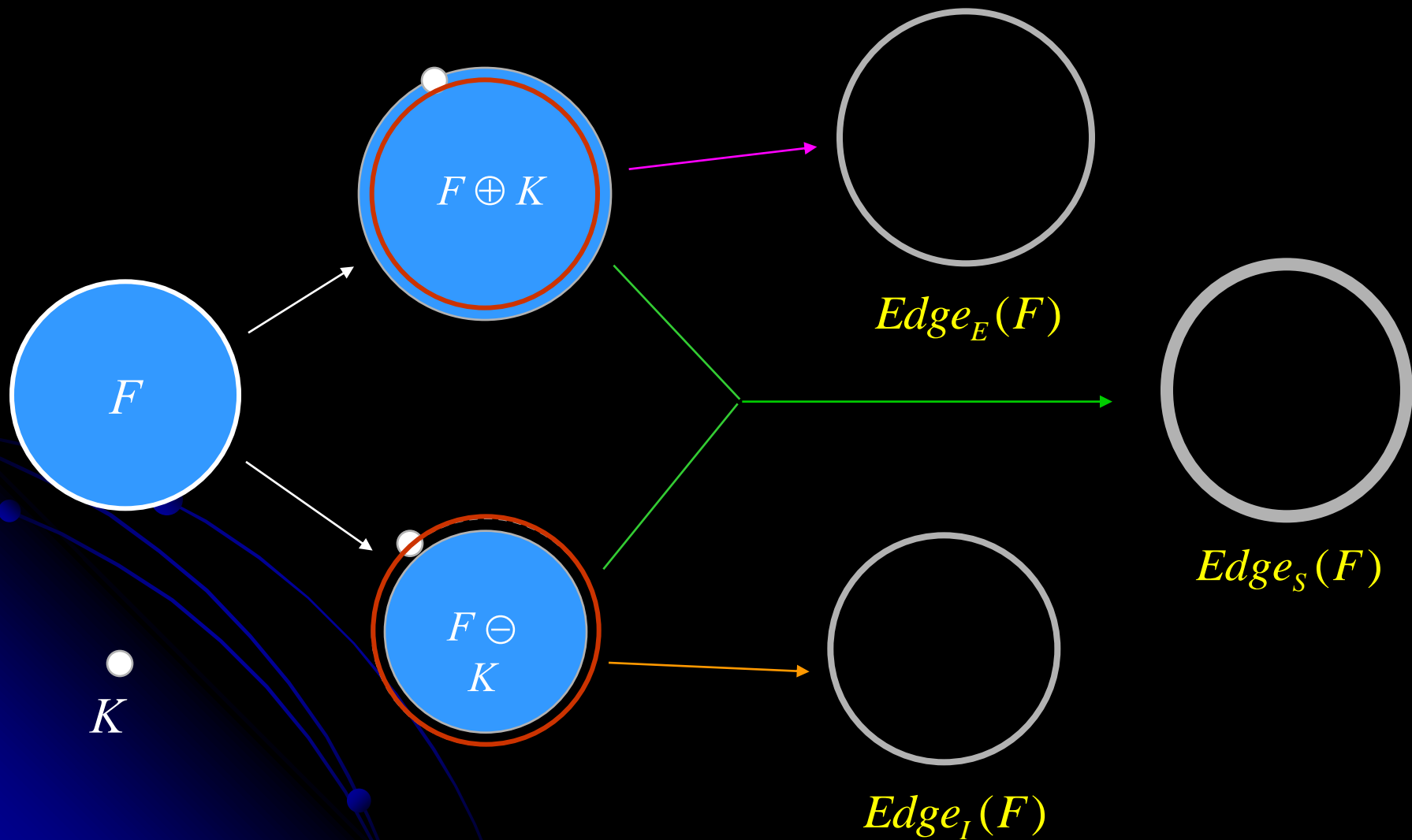
Štandard:  $Edge_s(F) = (F \oplus K) - (F \ominus K)$

Externé:  $Edge_E(F) = (F \oplus K) - F$

Interné:  $Edge_I(F) = F - (F \ominus K)$



# Hľadanie hranice



# Hľadanie hranice



$F$



$Edge_s(F)$

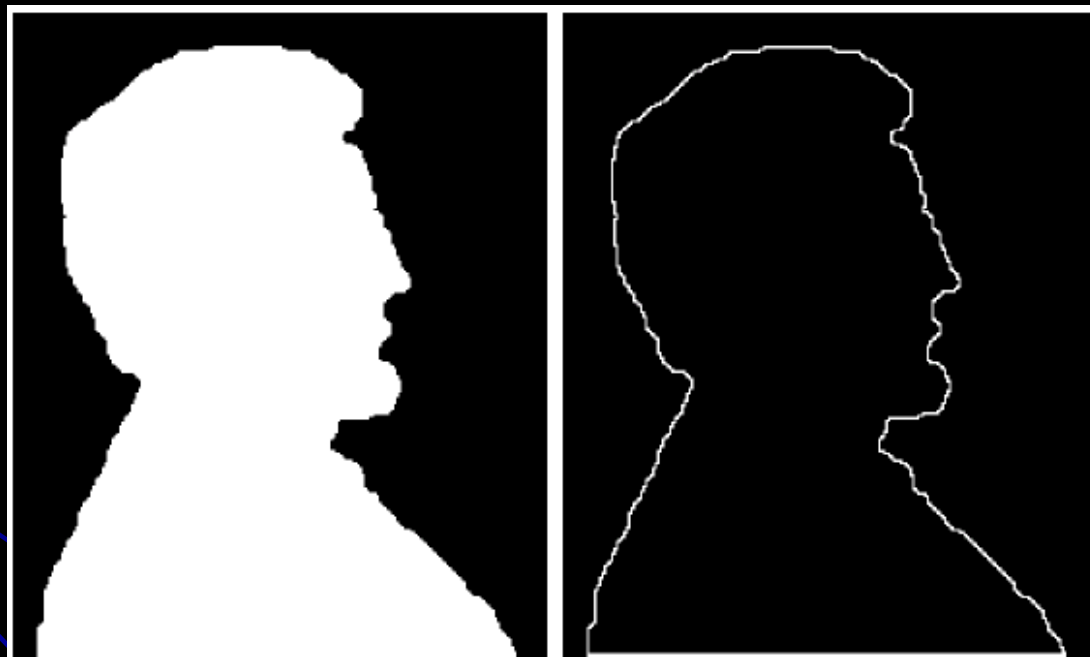


$Edge_E(F)$



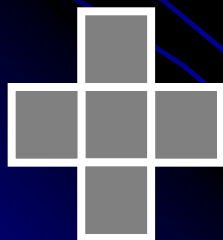
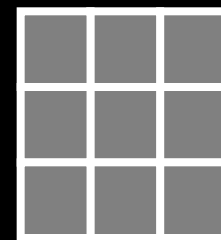
$Edge_I(F)$

# Hľadanie hranice



# Hľadanie hranice

$$\beta(A) = A - (A \ominus B)$$



8-súvislá hranica

4-súvislá hranica

# Opakovanie

otvorenie

erózia + dilatácia

uzavretie

dilatácia + erózia

- vyhladzuje kontúry
- prerušuje tenké spojenia
- maže tenké výčnelky

- vyhladzuje kontúry
- spája blízke oblasti
- vyplňa malé diery a tenké zálivy

Zachovávajú (približnú) veľkosť množiny

# Opakovanie

$\oplus$  dilatácia

$$A \oplus B = \bigcup_{b \in B} A_b$$

$\ominus$  erózia

$$A \ominus B = \bigcap_{b \in B} A_{-b}$$

◦ otvorenie

$$A \circ B = (A \ominus B) \oplus B$$

• uzavretie

$$A \bullet B = (A \oplus B) \ominus B$$

$\otimes$  hit-and-miss

$$A \otimes B = (A \ominus B_1) \cap (A^c \ominus B_2)$$

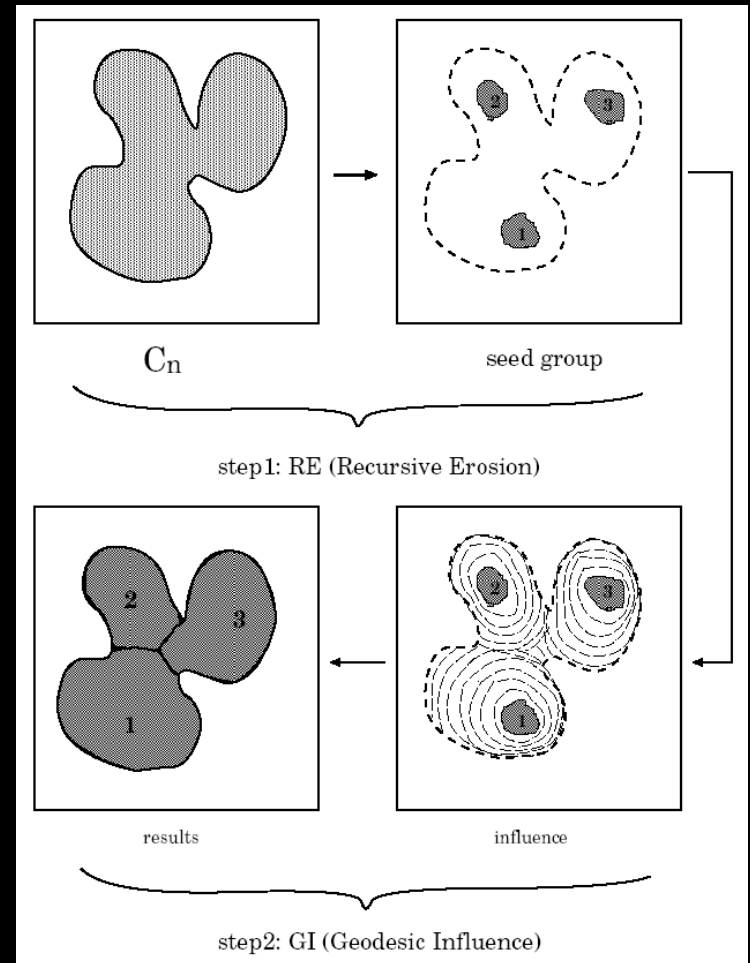
# UE a GI

Ultimatívna erózia (UE):  
rozdelí región, zachová  
zárodky

Geodesic Influence (GI)

Rekurzívna podmienená  
dilatácia

: zo zárodkov rekonštruuje  
objekt



# Hľadanie hranice

dilatácia – erózia

Algoritmy:

Štandard:  $Edge_s(F) = (F \oplus K) - (F \ominus K)$

Externé:  $Edge_E(F) = (F \oplus K) - F$

Interné:  $Edge_I(F) = F - (F \ominus K)$



# Šedotónová morfológia



# Obráz

$$X = \{ (\mathbf{a}; f_X(\mathbf{a})) \mid \mathbf{a} \in E^{n-1}, f_X(\mathbf{a}) \in R \cup \{\infty\} \cup \{-\infty\} \}$$

= n-dim graf

Nosič (support):  $\text{supp}(X) = \{ \mathbf{a} \in E^{n-1}, f(\mathbf{a}) \in R \}$

mimo:  $\infty$  alebo  $-\infty$

Pre nás  $n=3$

# Obraz

Binárny obraz

$f(\mathbf{x}) = \text{konštanta}$

Množinové operácie

Šedotónový obraz

$f(\mathbf{x})$  – úrovne intenzity

min/max

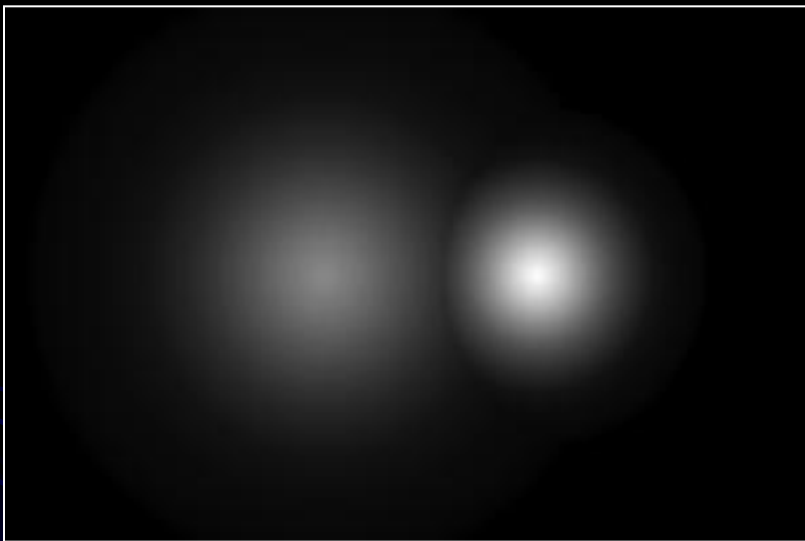
sup/inf

$X \subseteq Y$ :

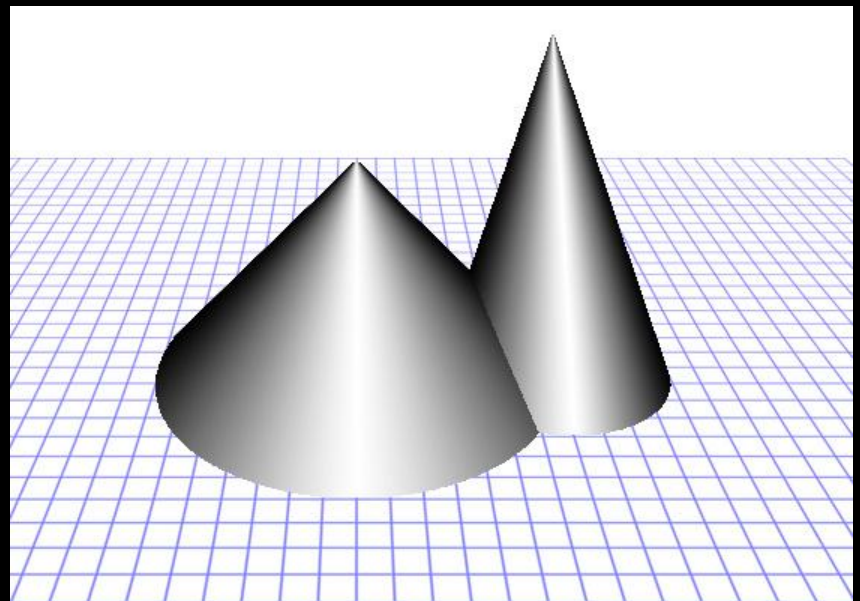
$\text{supp}(X) \subseteq \text{supp}(Y)$

$f_X(\mathbf{a}) \leq f_Y(\mathbf{a})$  pre  $\mathbf{a} \in \text{supp}(X)$

# Obraz

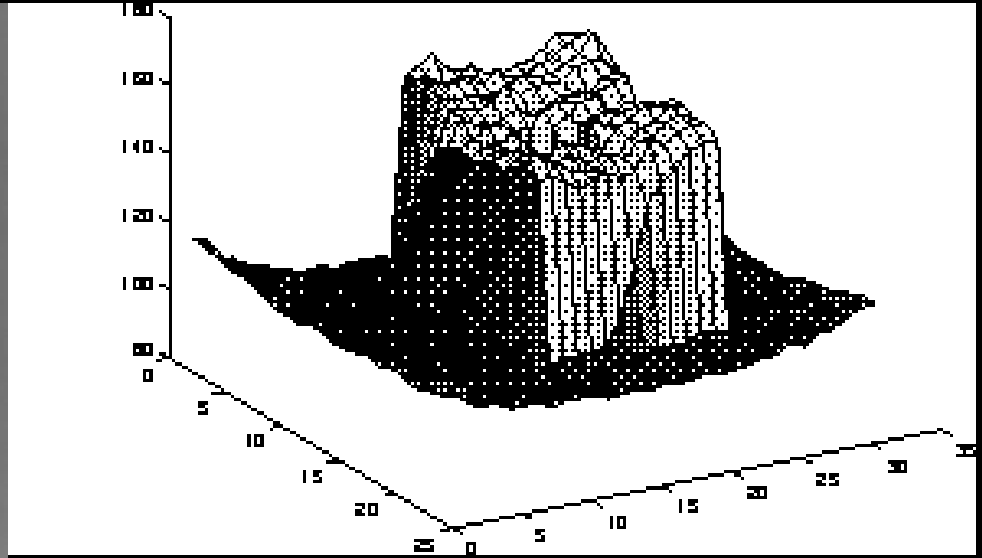
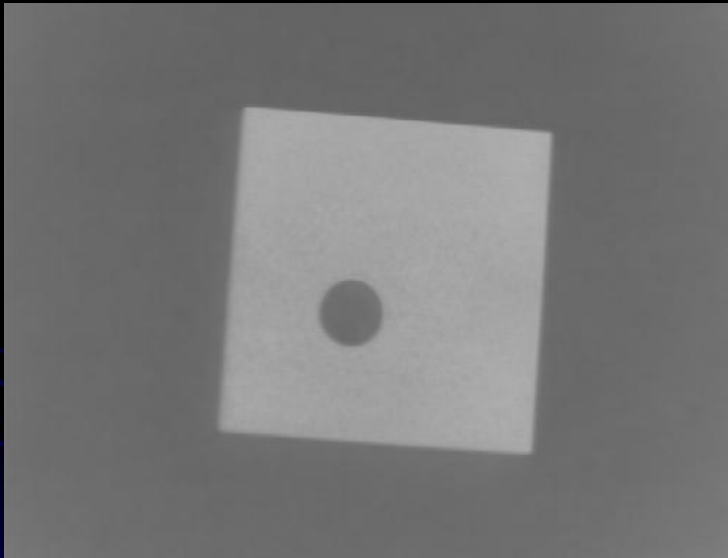


obraz



3D reprezentácia

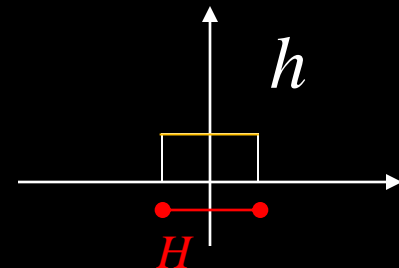
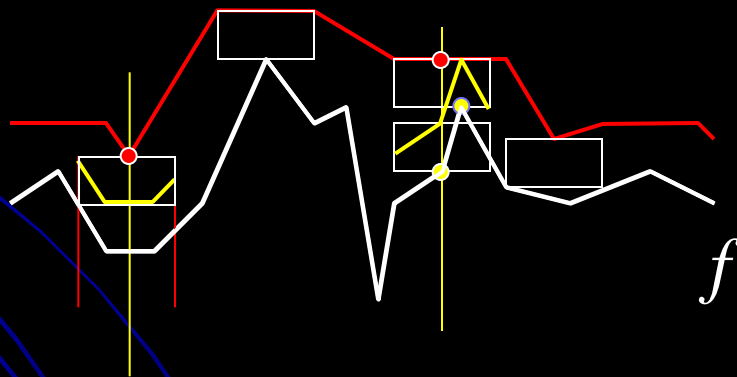
# Obraz



# Dilatácia

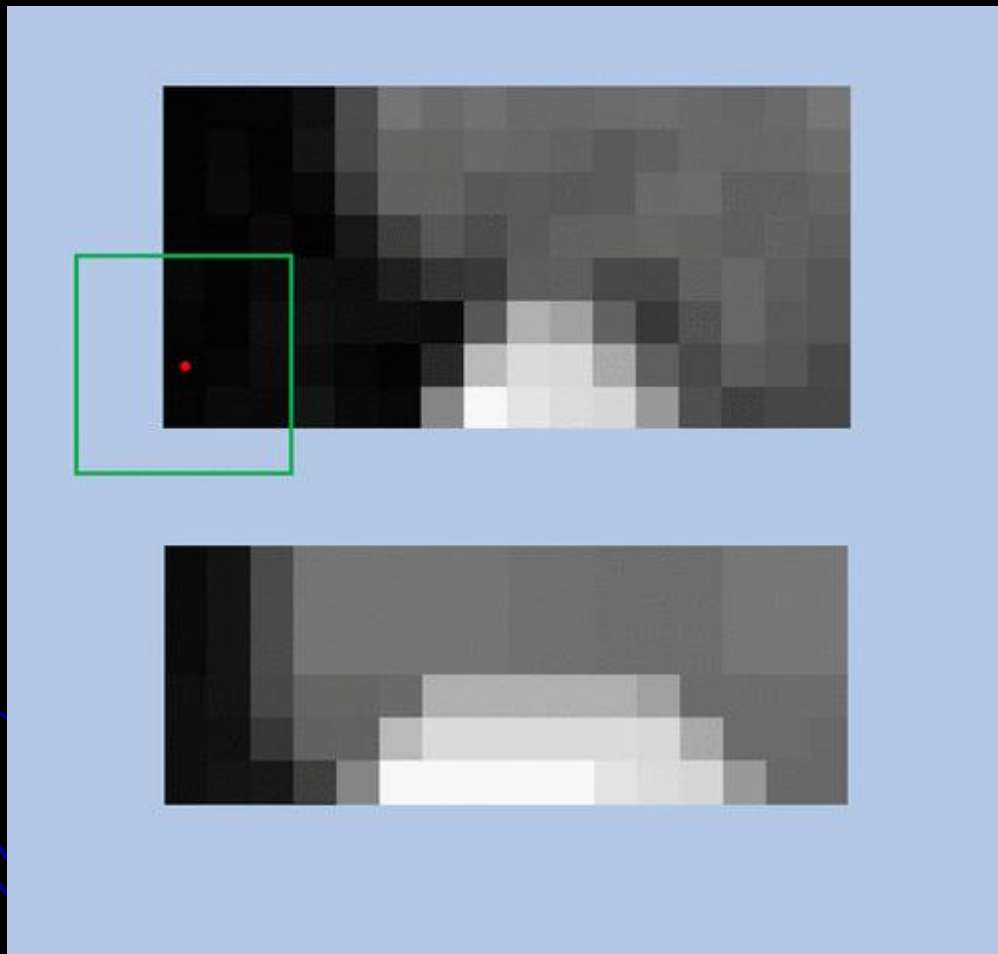
$$(f \oplus h)(x, y) = \max_{(r,s) \in H} \{f(x-r, y-s) + h(r,s)\}$$

$$(f \oplus h)(x) = \max_{r \in H} \{f(x-r) + h(r)\}$$



$H(x)$  - "structuring functions"

# Dilatácia



# Dilatácia



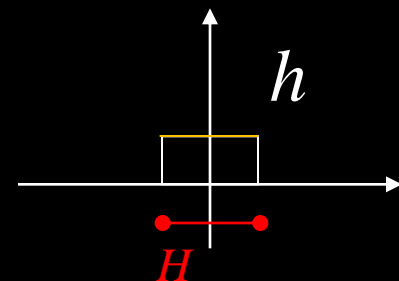
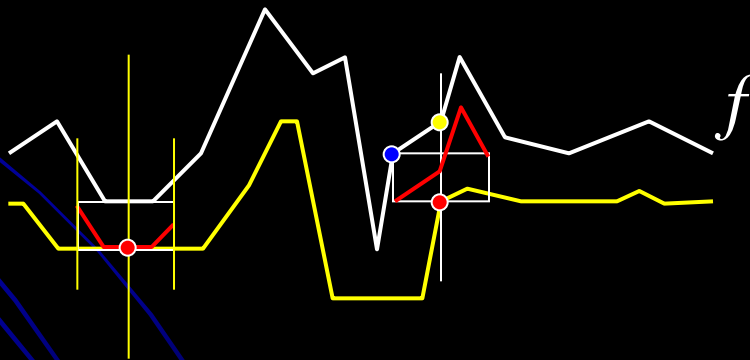
Zjasňuje obrázok – zvyšuje intenzitu



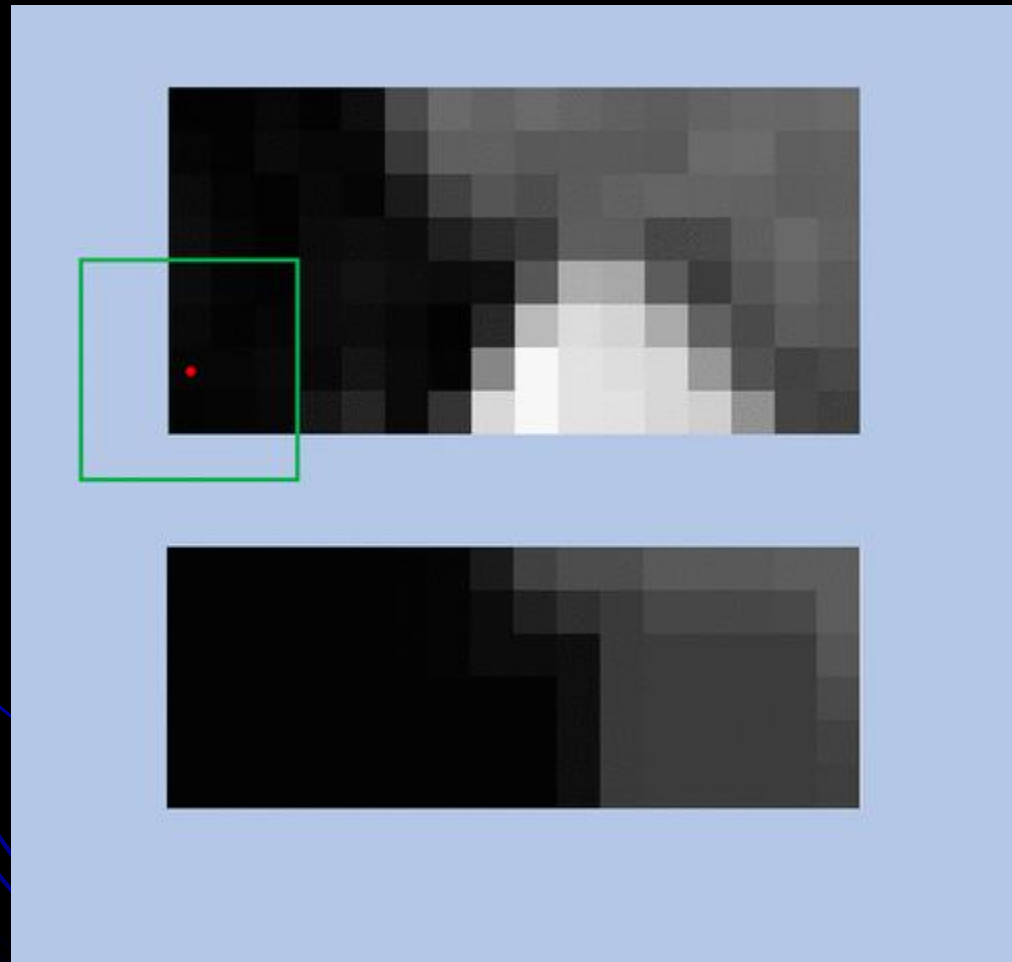
# Erózia

$$(f \ominus h)(x, y) = \min_{(r,s) \in H} \{f(x+r, y+s) - h(r,s)\}$$

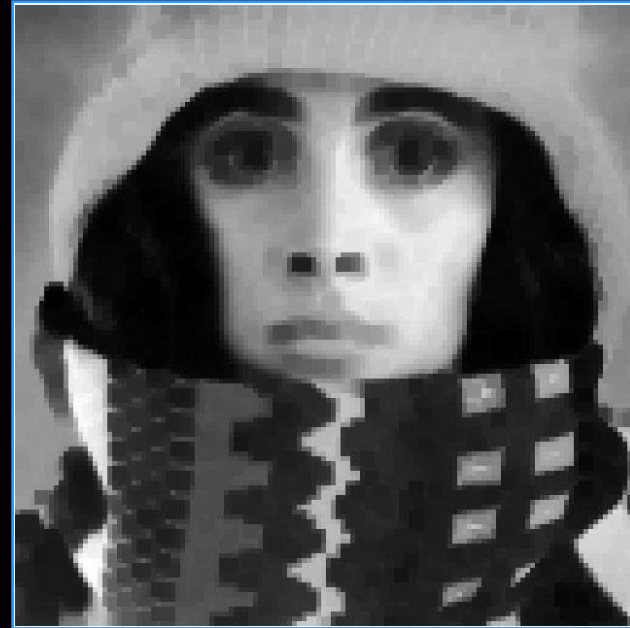
$$(f \ominus h)(x) = \min_{r \in H} \{f(x+r) - h(r)\}$$



# Erózia



# Erózia



Ztmavuje obrázok – znižuje intenzitu

# DE zhrnutie

D:

Jasnejší obrázok

Redukuje (odstraňuje)  
tmavé detaily



E:

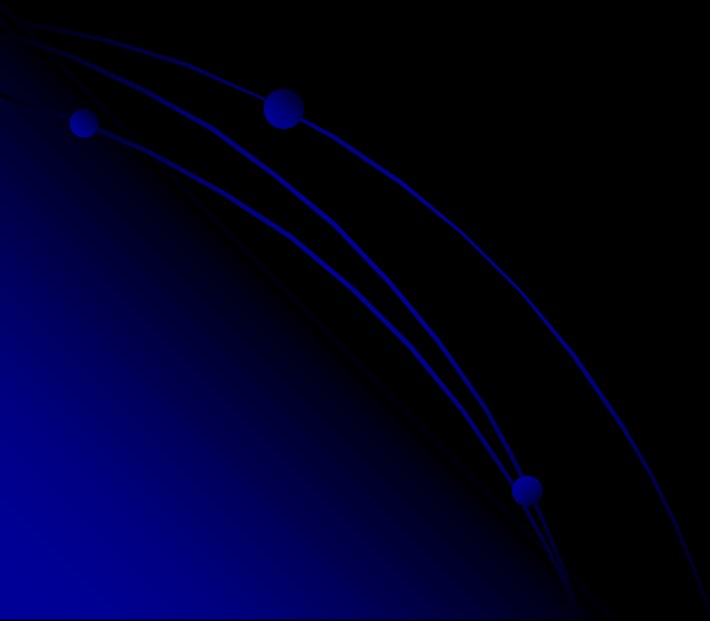
Tmavší obrázok

- Redukuje (odstraňuje)  
svetlé detaily

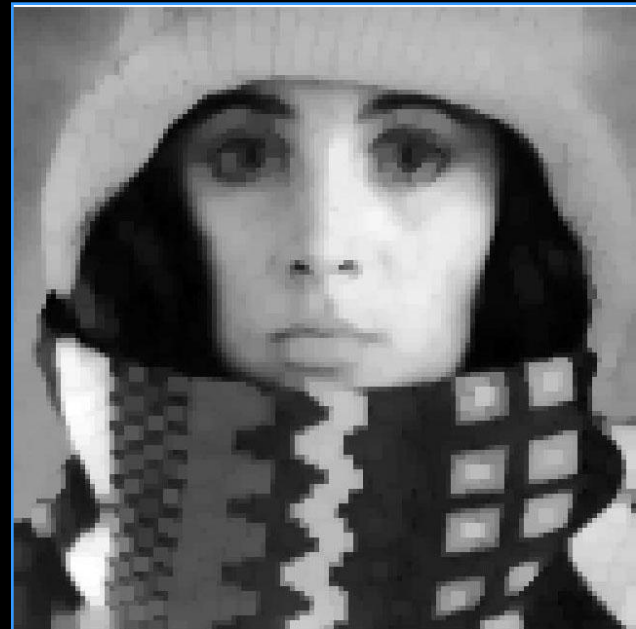


# Otvorenie

$$A \circ B = (A \ominus B) \oplus B$$

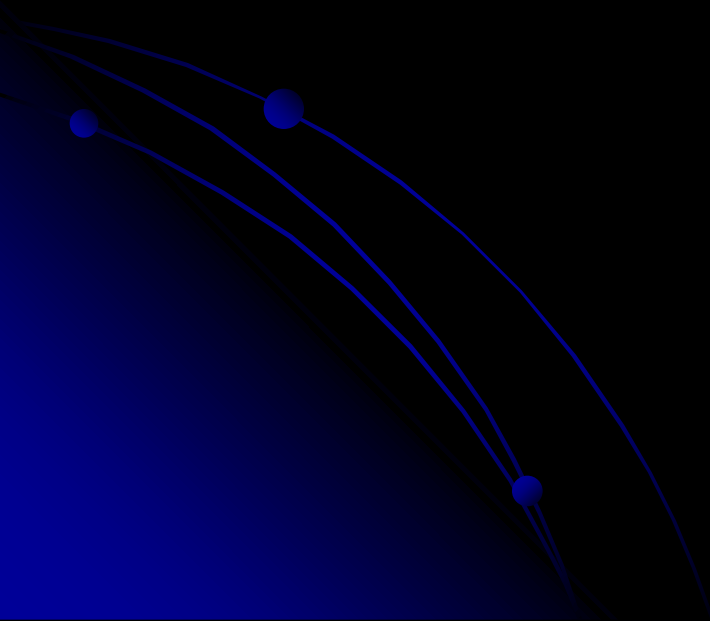


# Otvorenie



# Uzavretie

$$A \bullet B = (A \oplus B) \ominus B$$



# Uzavretie



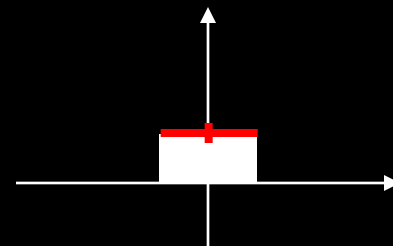
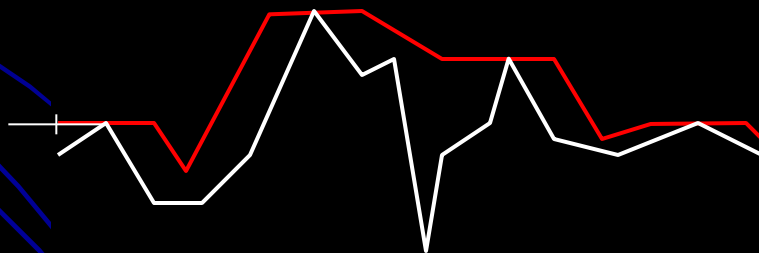
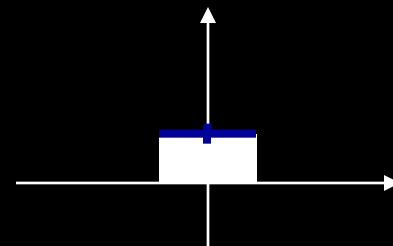
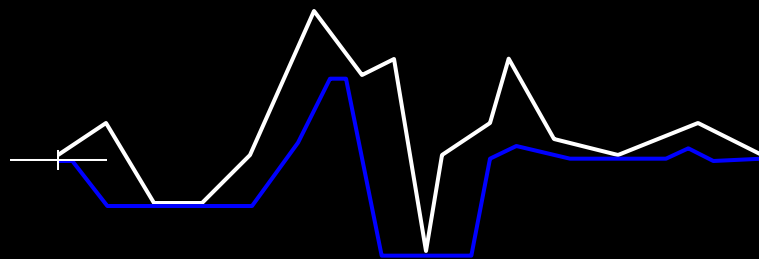


$$A \circ B = (A \ominus B) \oplus B$$

OU

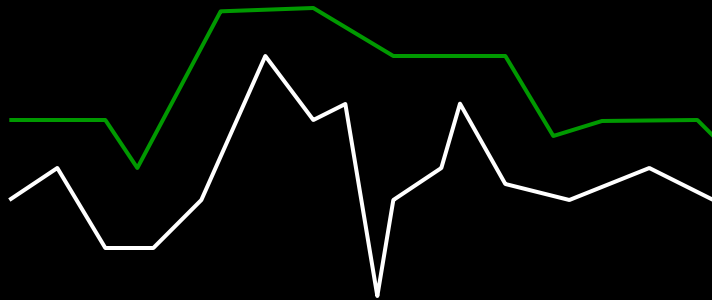
$$A \bullet B = (A \oplus B) \ominus B$$

otvorenie

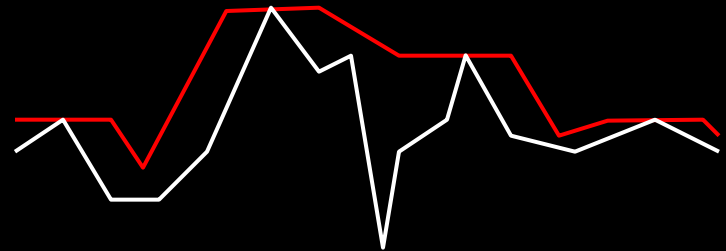


uzavretie

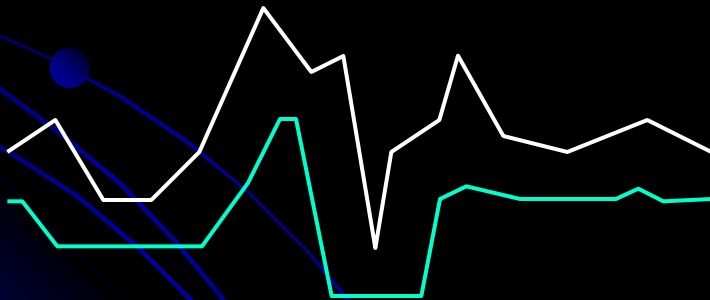
# Zhrnutie



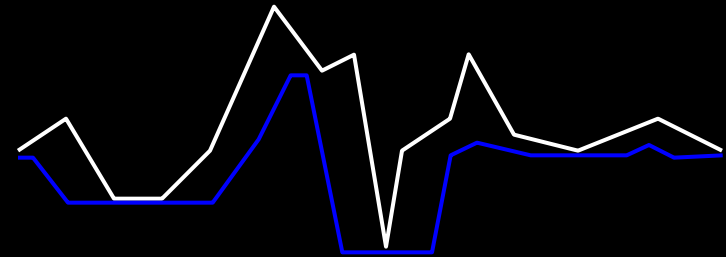
D



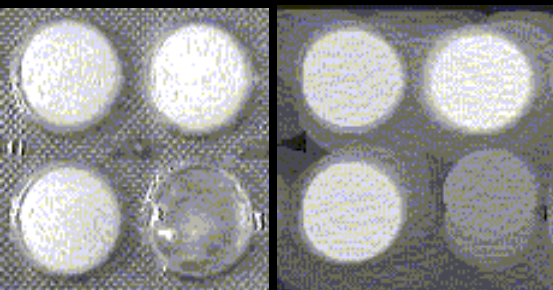
U



E



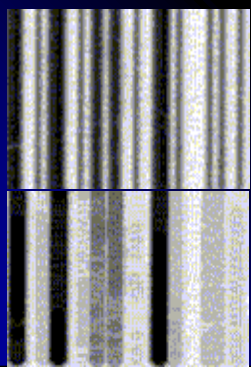
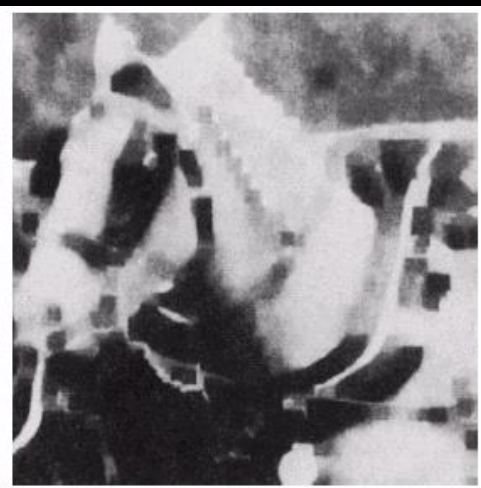
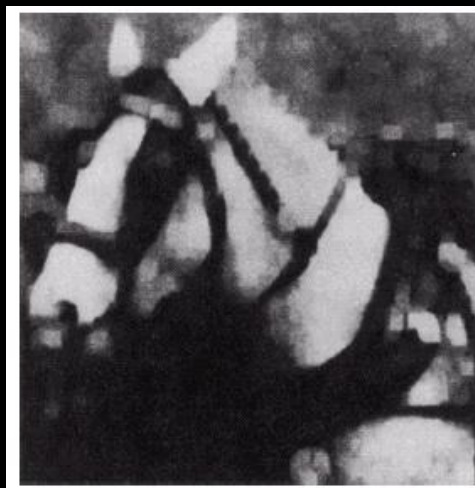
O



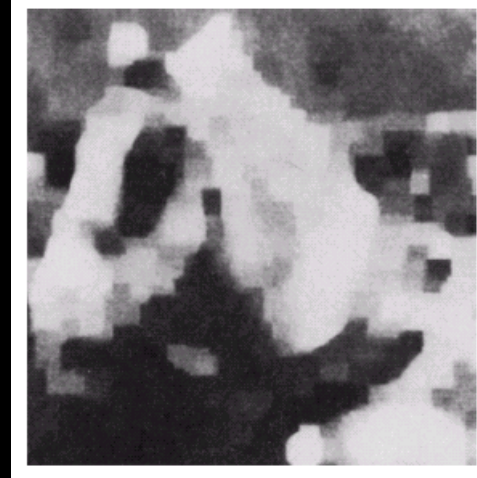
# OU zhrnutie

O: odstraňuje malé svetlé objekty  
odstraňuje šum

U: spája svetlé objekty  
redukuje malé tmavé  
oblasti



# Príklad použitia



$(A \circ B) \bullet B$  – filtrácia obrazu

# Morfologický gradient

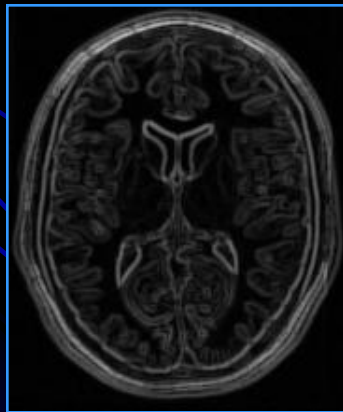
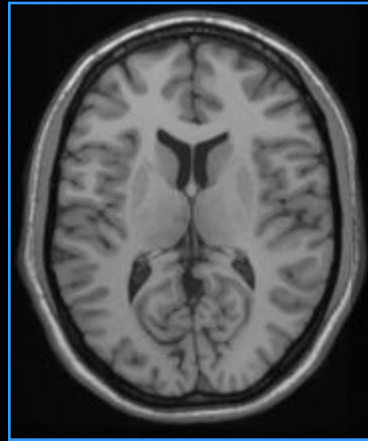
Šedotónové obrazy

$$\text{grad}(F) = \frac{1}{2}(A \oplus B) - (A \ominus B)$$

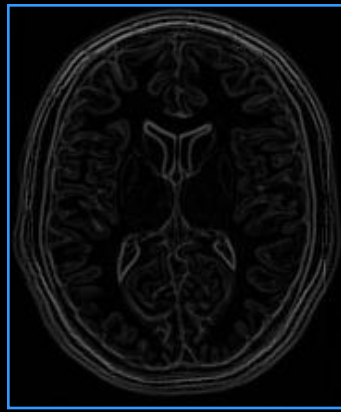
tiež externý a interný gradient



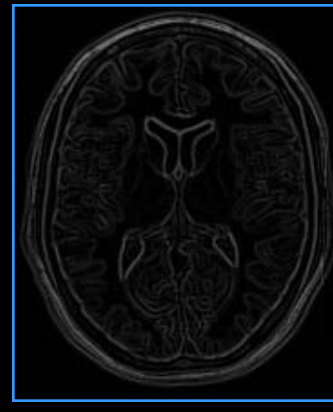
# Morfologický gradient



Štandard

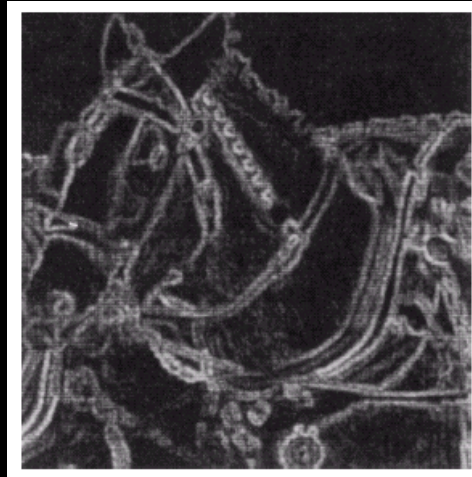


Externý



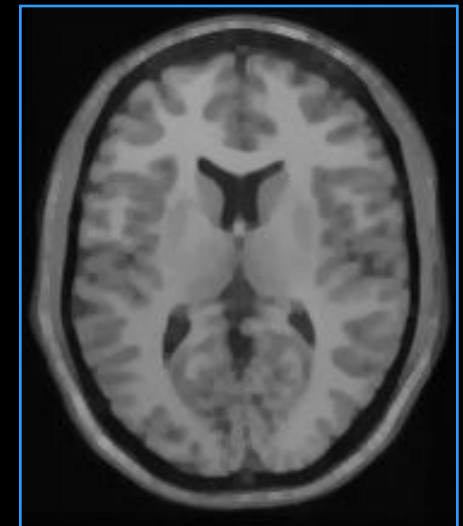
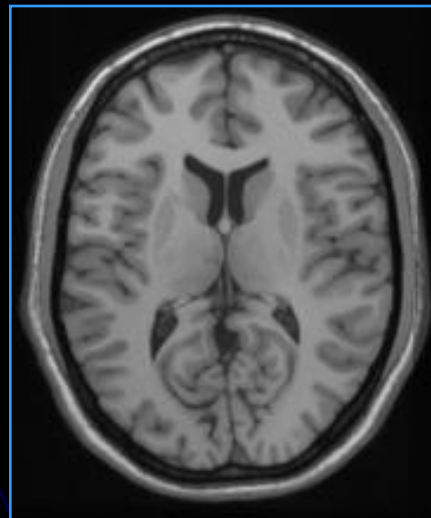
Interný

# Morfologický gradient



# Morfologické vyhladzovanie

$$(A \circ B) \bullet B$$





# Top-hat transformácia

Nástroj na segmentáciu –  
výber svetlých (tmavých) objektov  
z nekonštantného pozadia

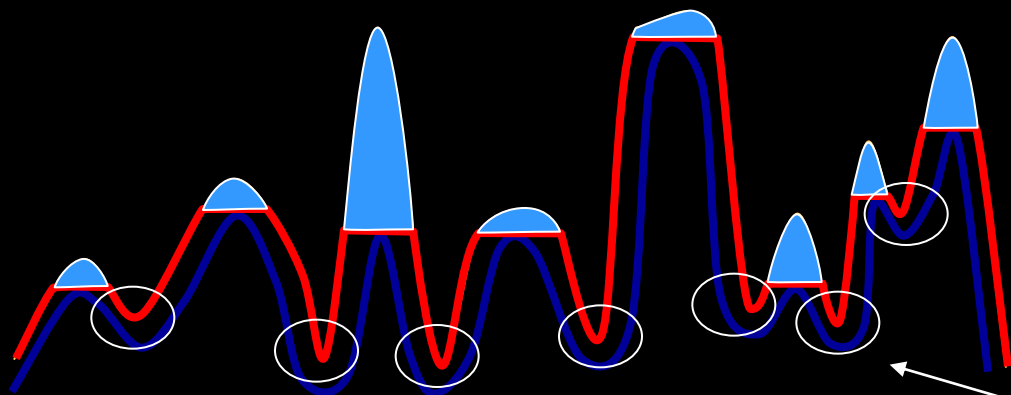
White Top-hat Transform (WTT):

$$A - (A \circ B)$$

Black Top-hat Transform (BTT):

$$(A \bullet B) - A$$

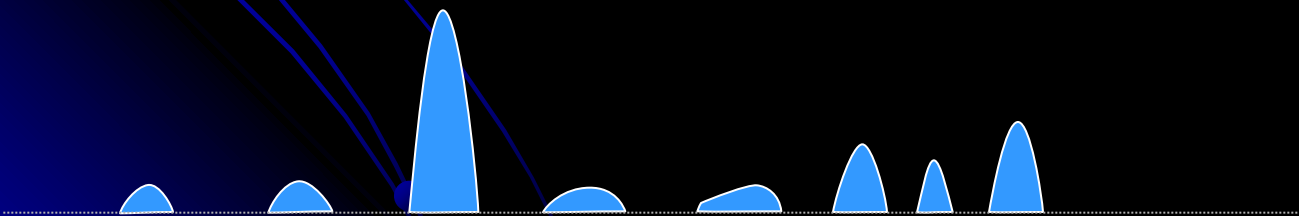
# Top-hat



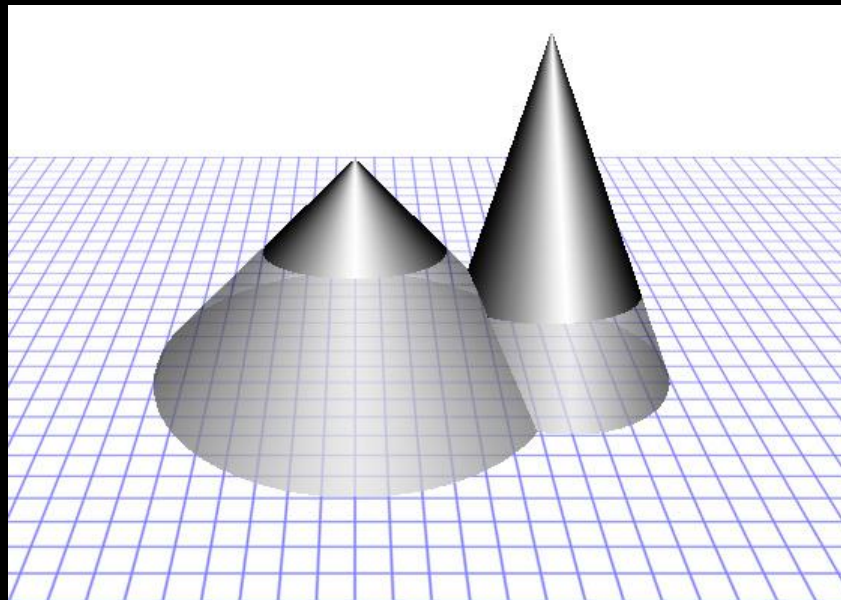
BTT



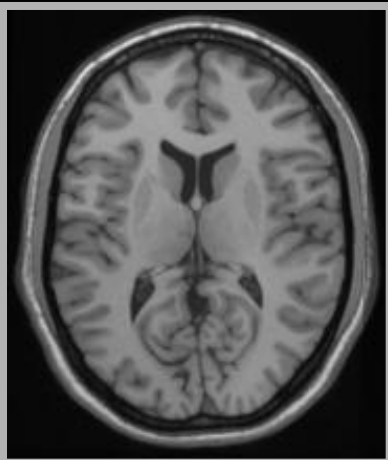
WTT



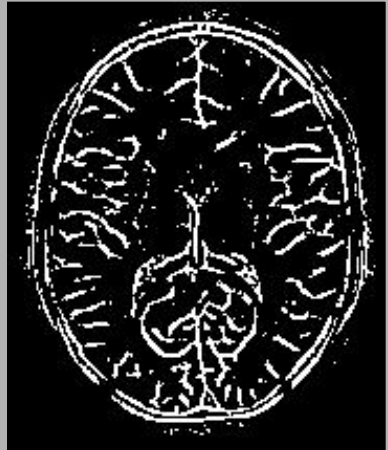
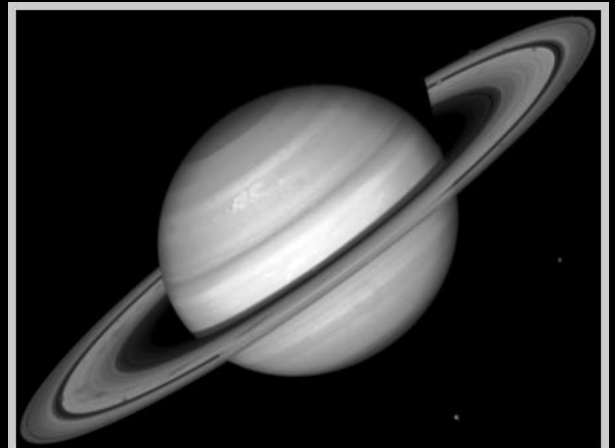
# Top-hat



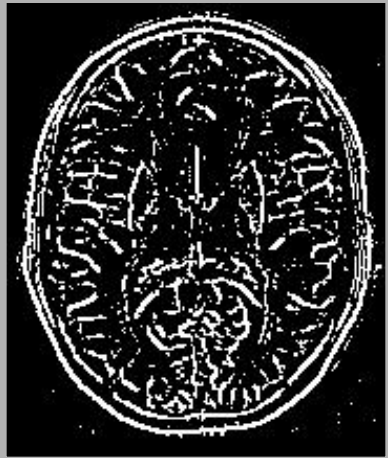
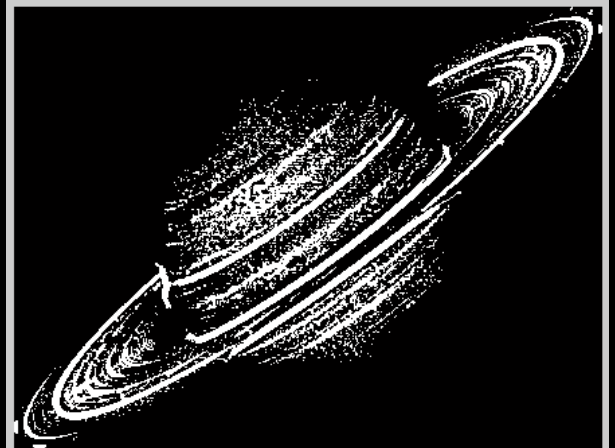
tophat + otvorenie = originál



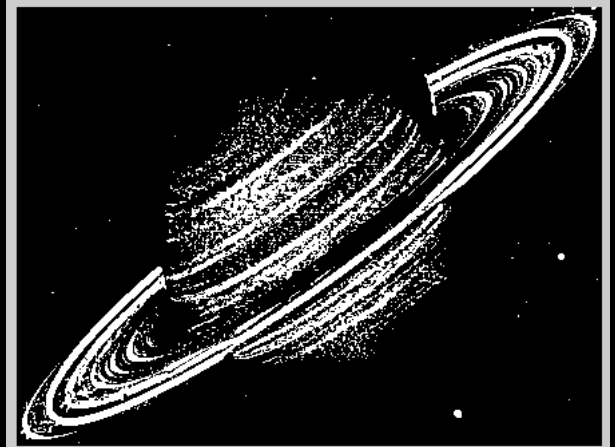
Top-hat



BTT

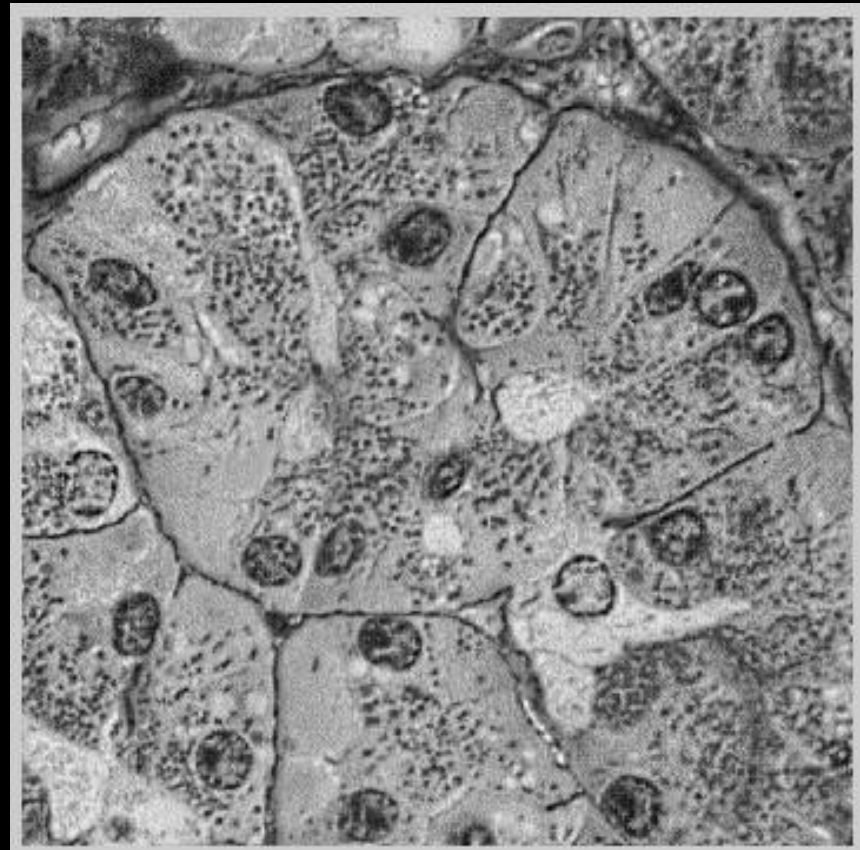
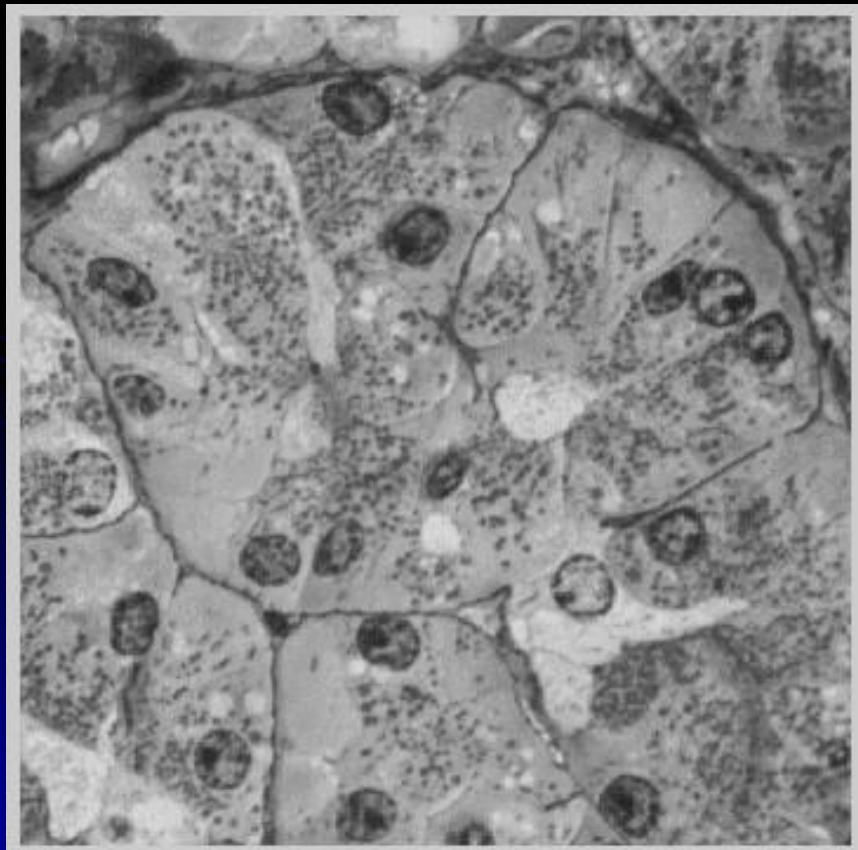


WTT



# Zlepšenie kontrastu

(A + WTT) – BTT



# White top hat



StructuringElement size 3 x 3

# White top hat



StructuringElement size 3 x 3

# Black top hat



COLOR2GRAY

StructuringElement size 3 x 3



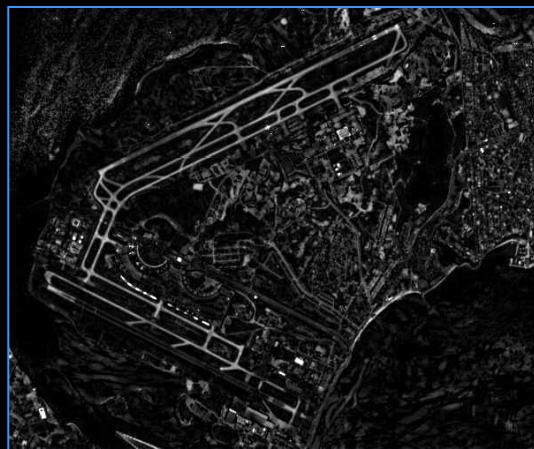
# Black top hat



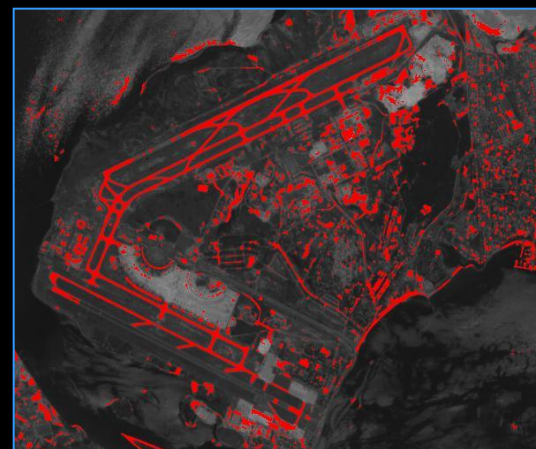
# Aplikácia: hľadanie ranvejí



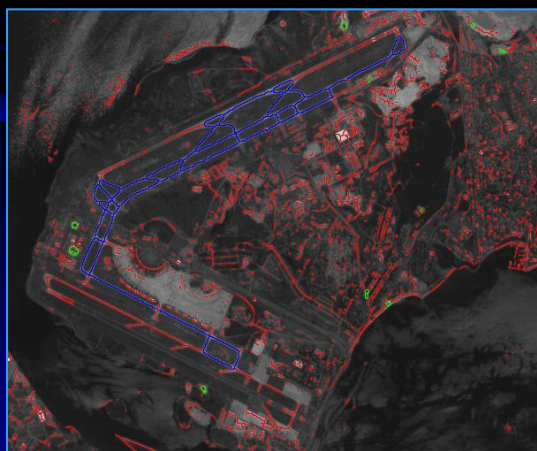
*Originál*



*WTT*



*Prahovanie*



*Nájdeme dlhé  
objekty*

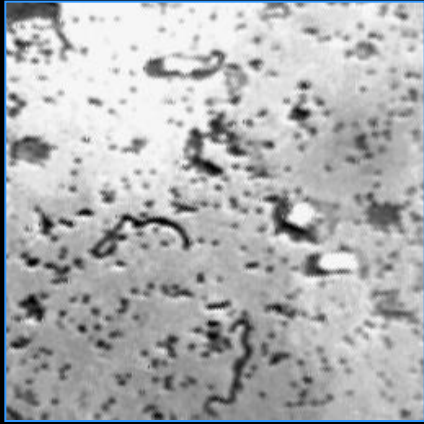


*Rekonštrukcia*

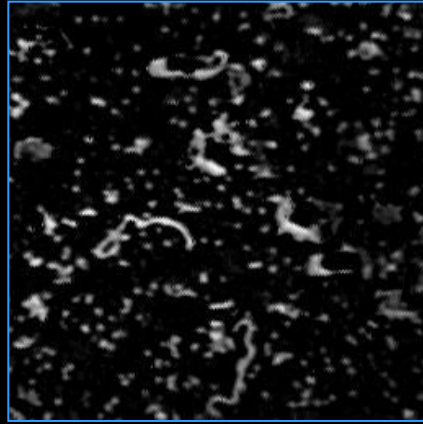


*Výsledok*

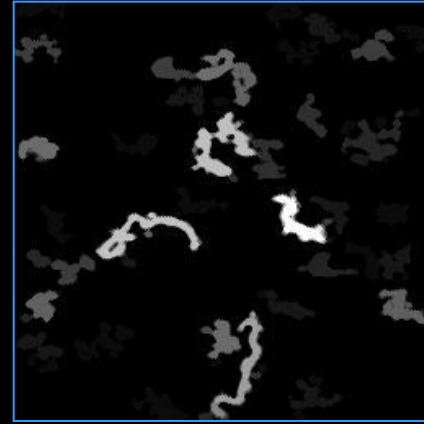
# Aplikácia 2: hľadanie filariálnych červov



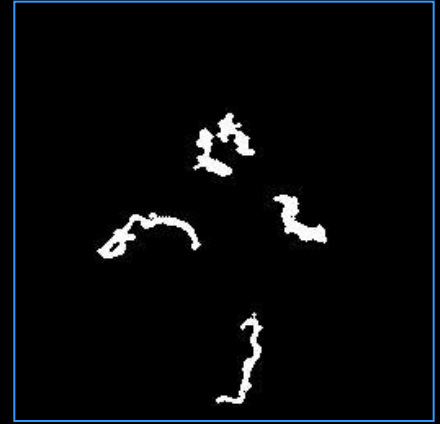
*Originál*



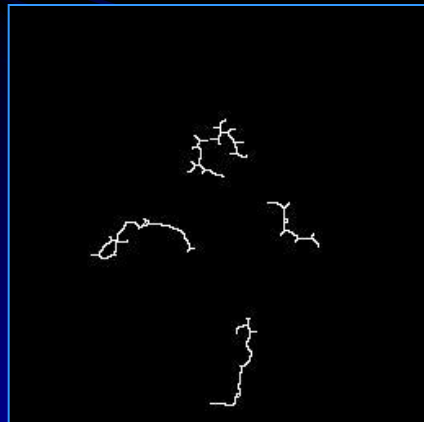
*BTT*



*Odstránenie šumu*



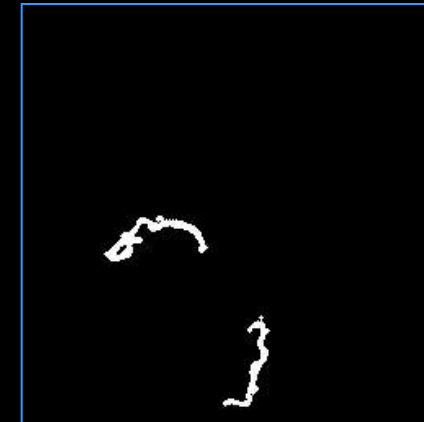
*Prahovanie*



*Kostra*



*Zmazanie  
krátkych objektov*



*Rekonštrukcia*

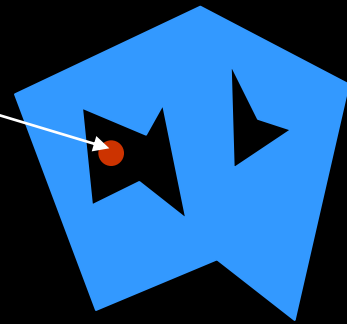


*Výsledok*

# Vypíňanie oblastí

$x=X_0$  vnútorný štartovací bod

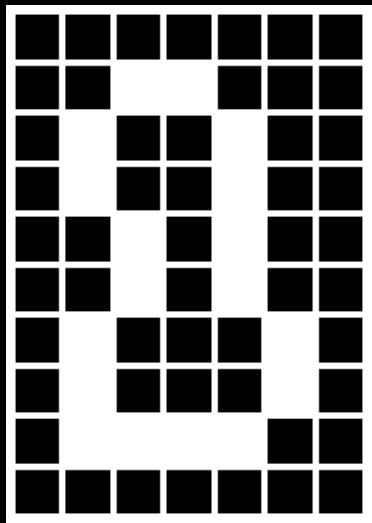
$$X_k = (X_{k-1} \oplus B) \cap A^c, k = 1, 2, 3, \dots$$



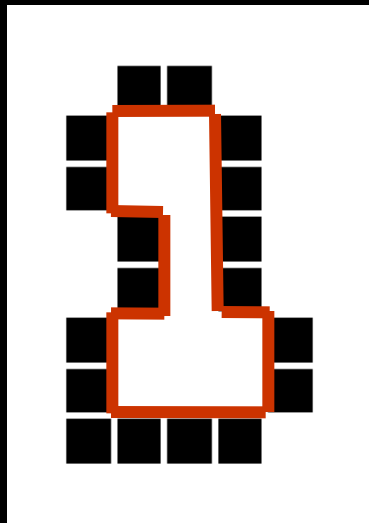
kým  $X_k = X_{k-1}$

Vyplnená oblasť  $A \cup X_k$

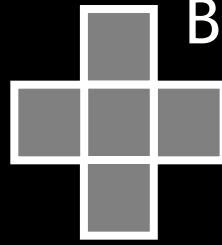
Podmienená dilatácia



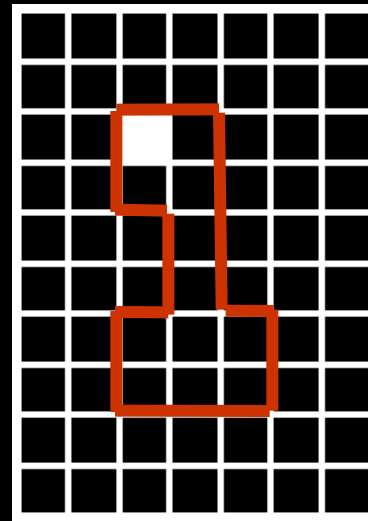
A



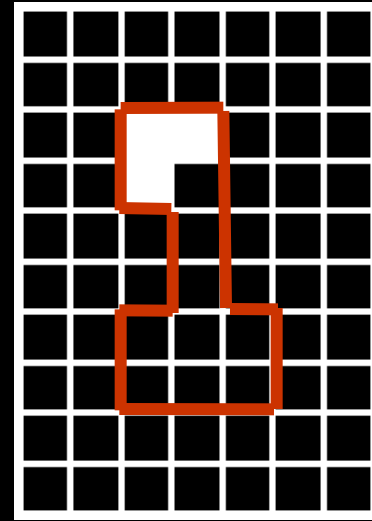
$A^c$



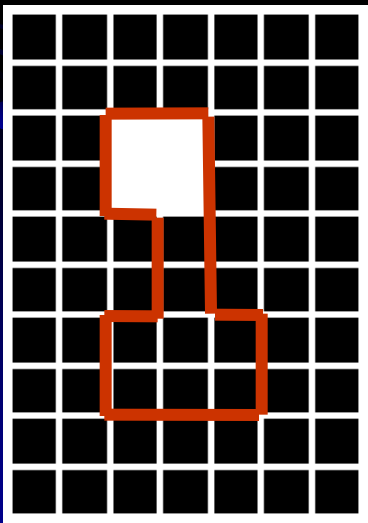
B: ŠP - závisí od susednosti



$X_0$

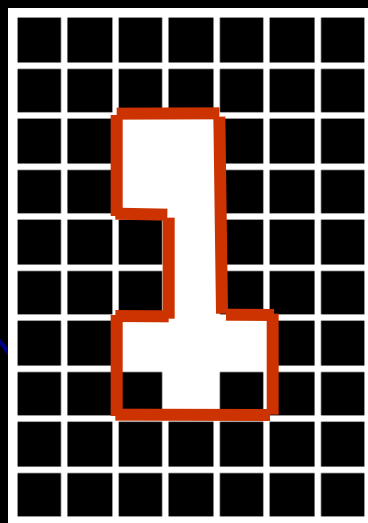


$X_1$

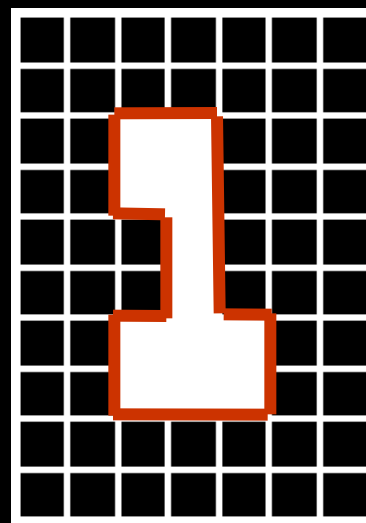


$X_2$

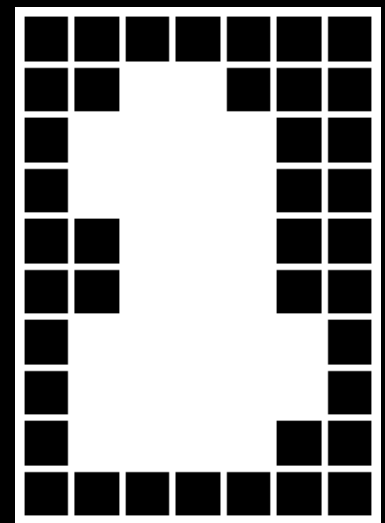
...



$X_6$

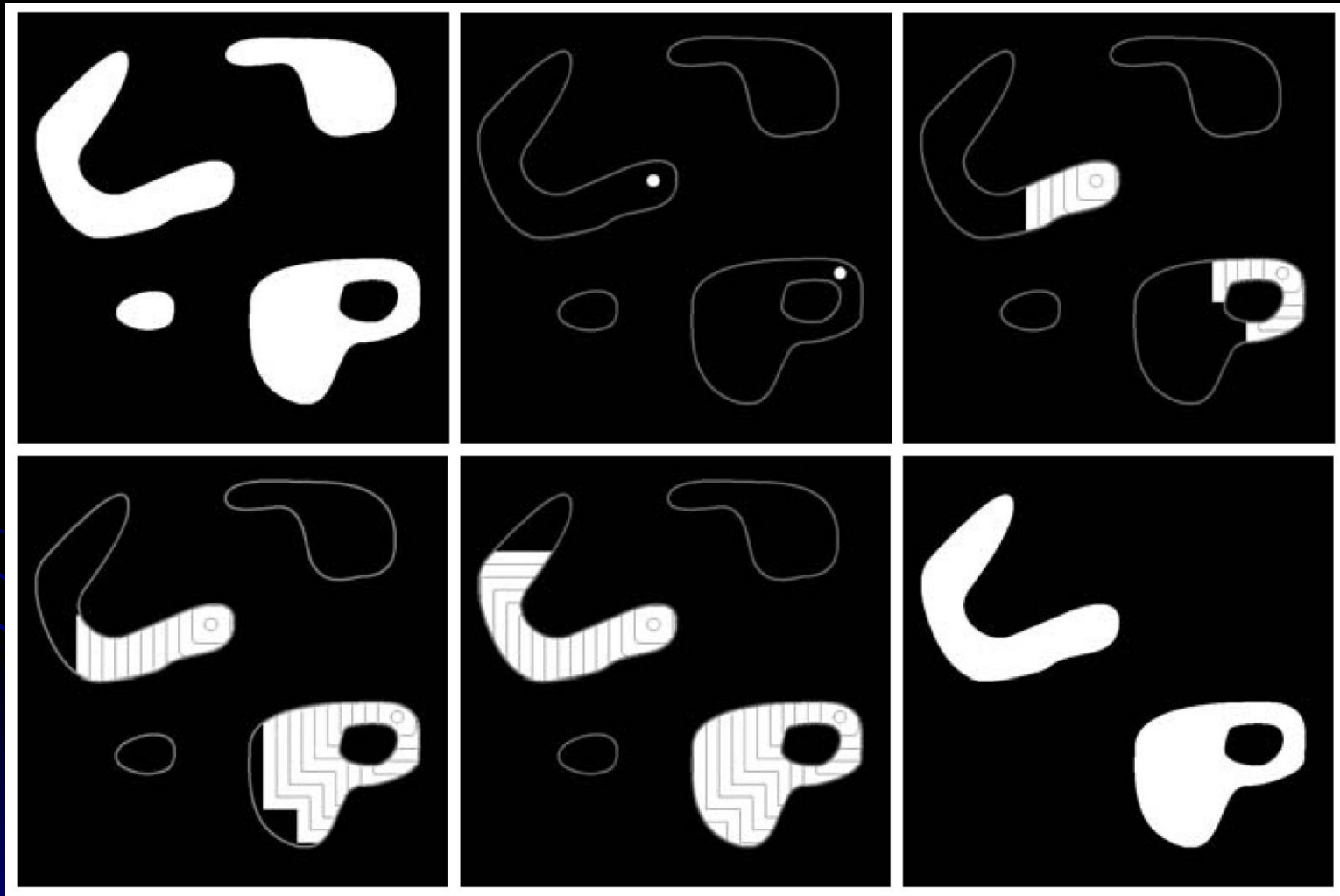


$X_7$



$X_7 \cup A$

# Rekonštrukcia



# Výber spojitých částí

$Y$  - spojitý komponent v množině  $A$

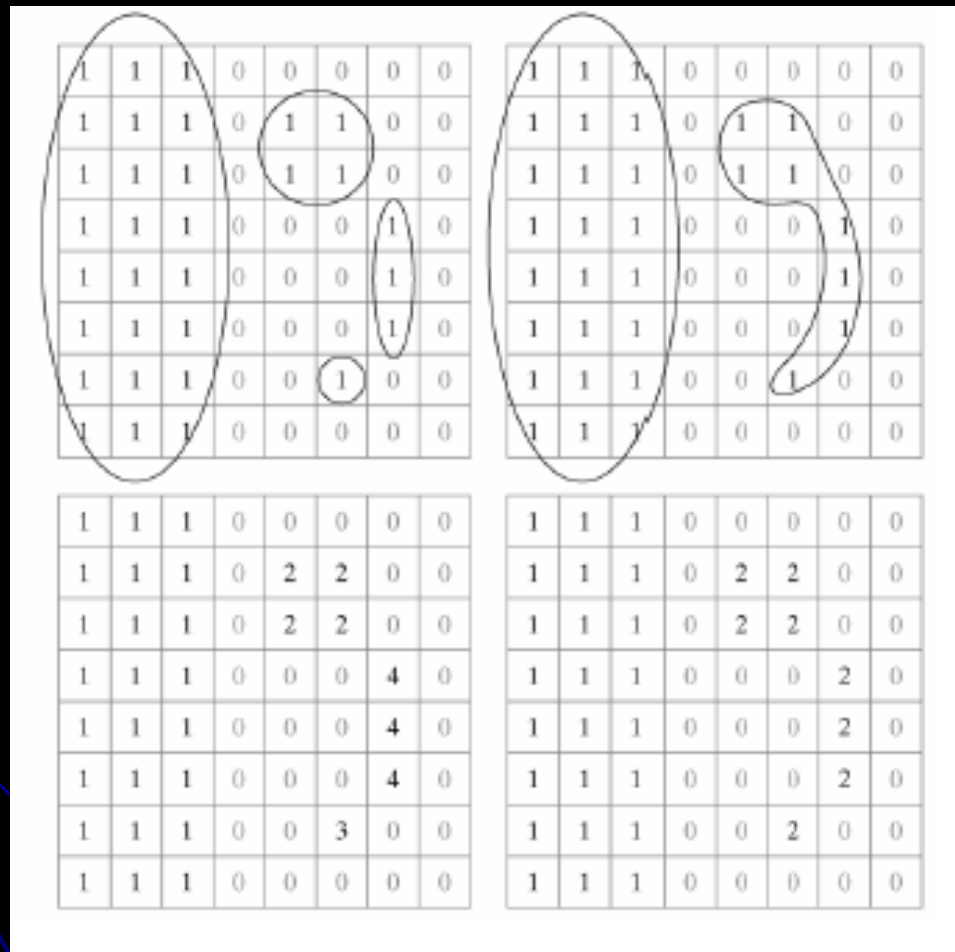
Počiatočný bod  $X_0 \in Y$

$$X_k = (X_{k-1} \oplus B) \cap A, k = 1, 2, 3, \dots$$

$$X_k = X_{k-1} \rightarrow Y = X_k$$

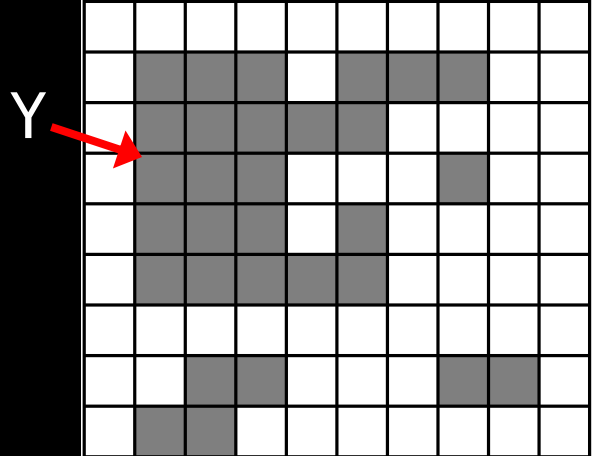
$B$ : ŠP - závisí od susednosti

# Výber spojených částí



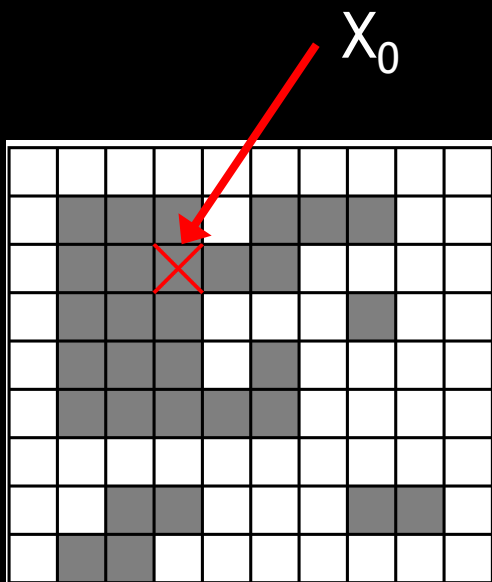
B: ŠP - závisí od susednosti



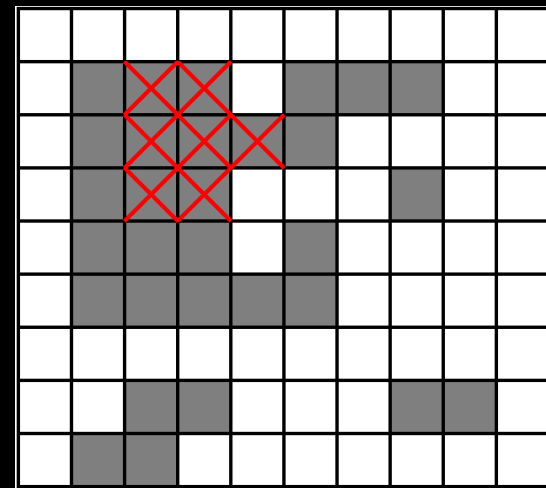


A

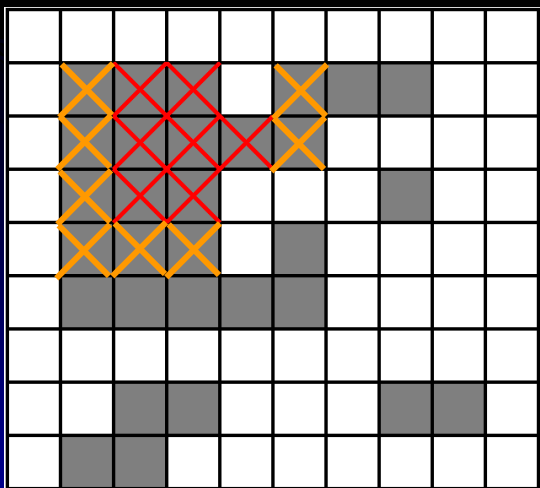
B



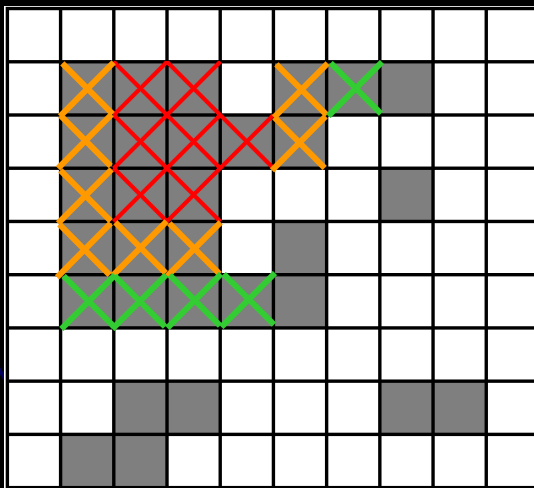
$$X_1 = X$$



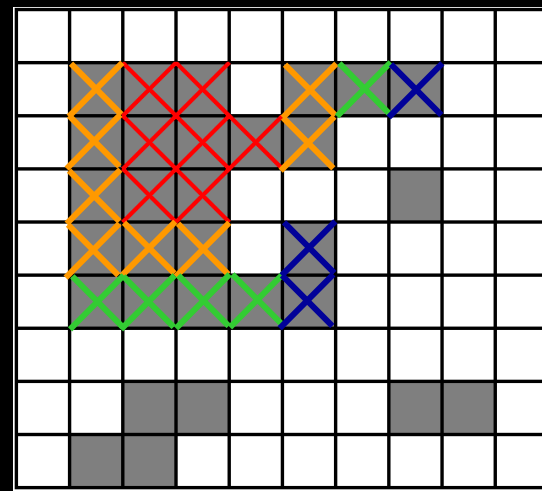
$$X_2 = XX$$



$$X_3 = XXX$$



$$X_4 = XXXX$$



# Zužovanie

Použitie HMT

$$A \oslash B = A - (A \otimes B)$$

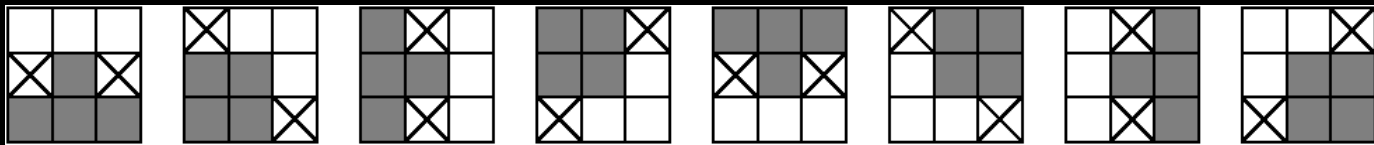
Sekvenčné zužovanie

$$((A \oslash B^1) \oslash B^2) \dots \oslash B^n$$

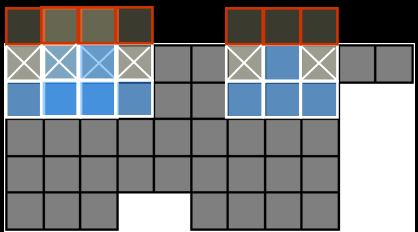
$\{B^1, B^2, \dots, B^n\}$

**Golay**ova abeceda = typ L, E, M, D, C

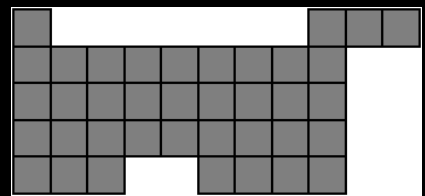
L



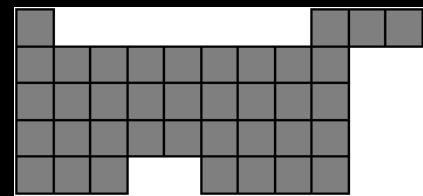
$B^1$     $B^2$     $B^3$     $B^4$     $B^5$     $B^6$     $B^7$     $B^8$



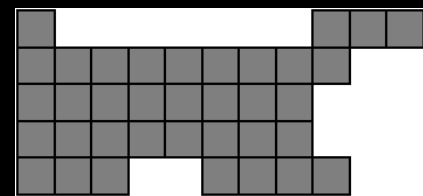
A



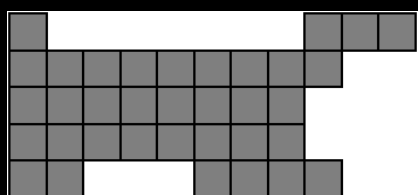
$A \ominus B^1$



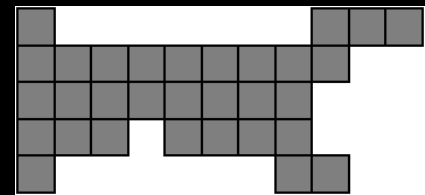
$\dots \ominus B^2$



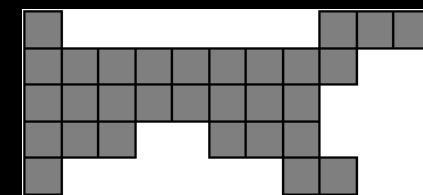
$\dots \ominus B^3$



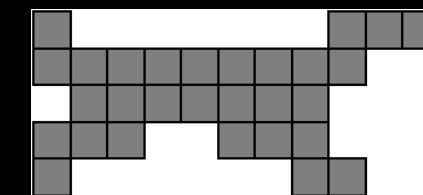
$\dots \ominus B^4$



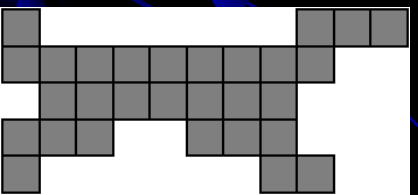
$\dots \ominus B^5$



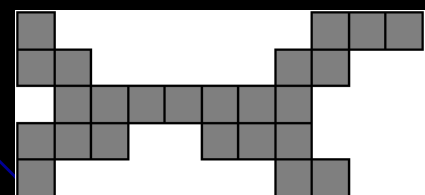
$\dots \ominus B^6$



$\dots \ominus B^7$

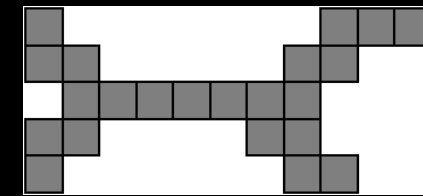


$\dots \ominus B^8$

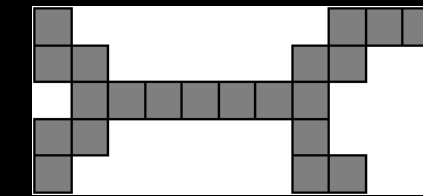


$\dots \ominus B^1$

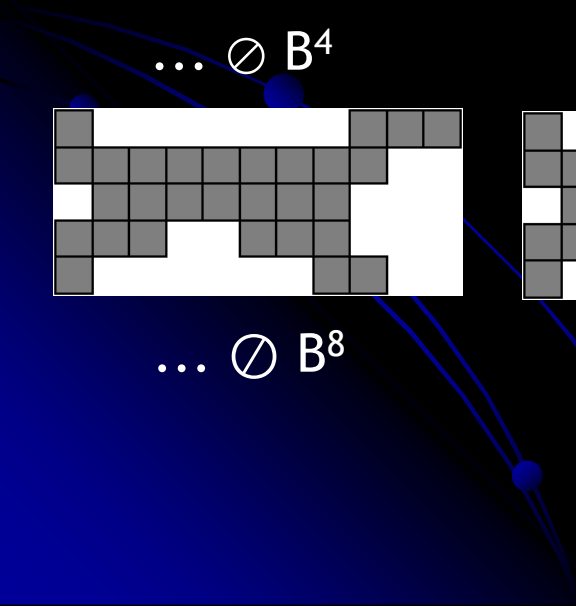
...



$\dots \ominus B^5$

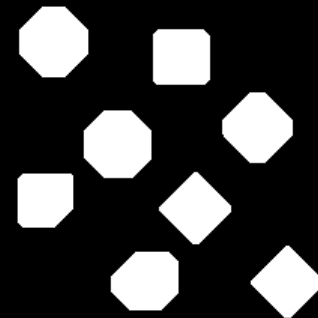
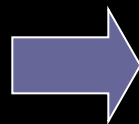
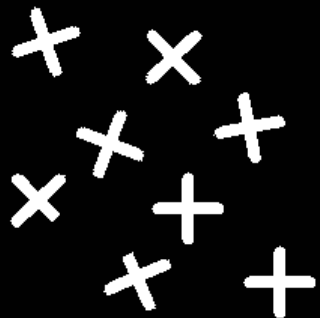


$\dots \ominus B^6$



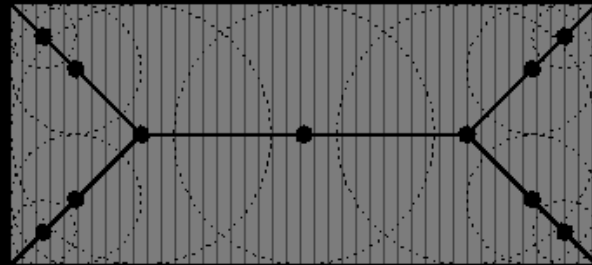
# Rozširovanie

$$A \odot B = A \cup (A \otimes B)$$



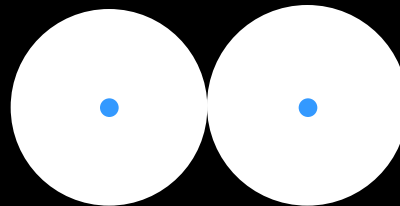
# Skeleton – kostra

Kostra – redukcia bodov objektu  
Zachováva topológiu

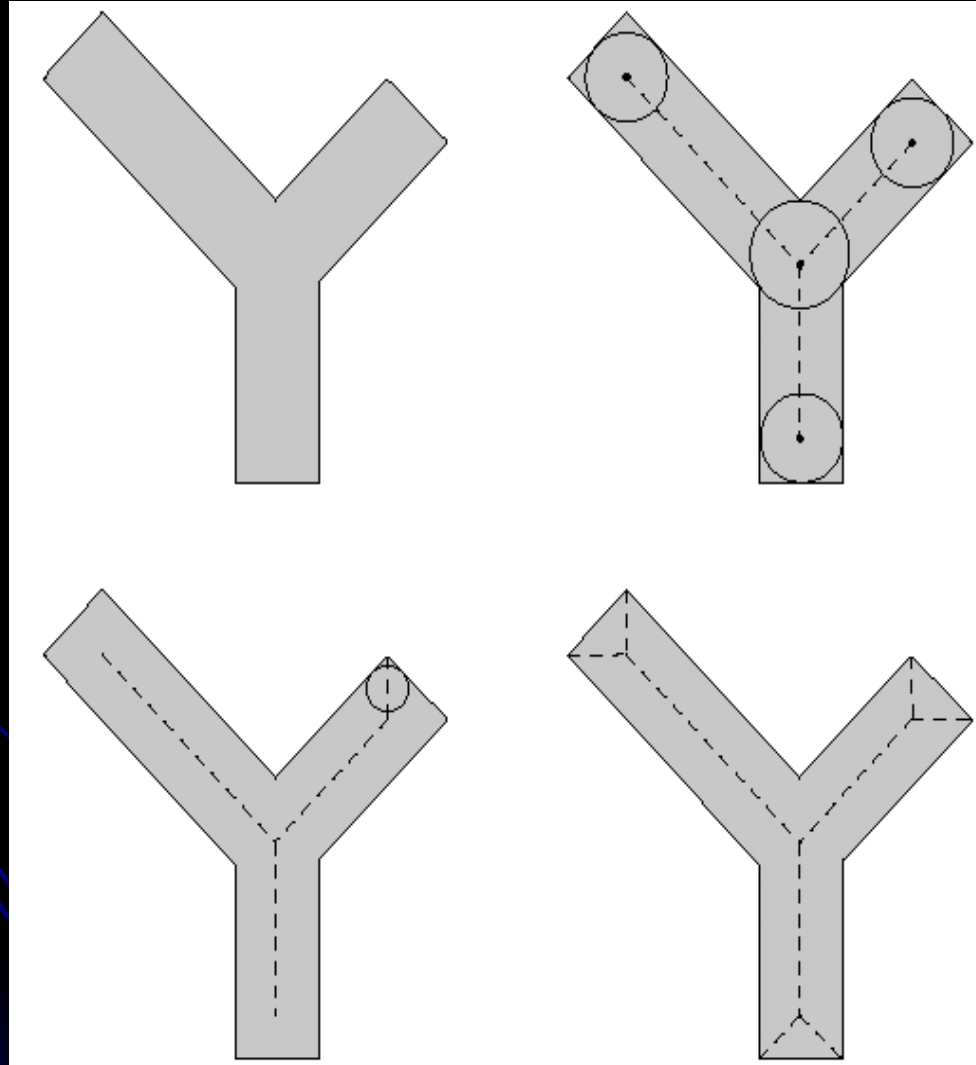


*Stredy vpísaných kruhov*  
 $\geq 2$  dotykové body

Problém?



# Kostra



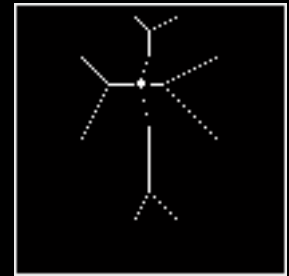
# Kostra

Podmnožina kostry:

$$S_i(F) = (F \ominus^i B) - ((F \ominus^i B) \circ B), \quad i=1, \dots, n$$

$n$  – posledná iterácia ( $S_{n+1}(F) = \emptyset$ )

$B$  kruhový ŠP



Kostra:

$$S(F) = \bigcup_{i=0}^n S_i(F)$$

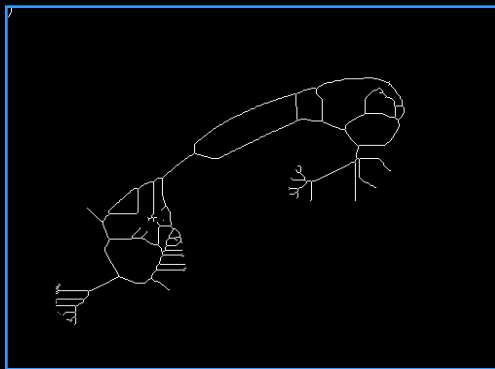
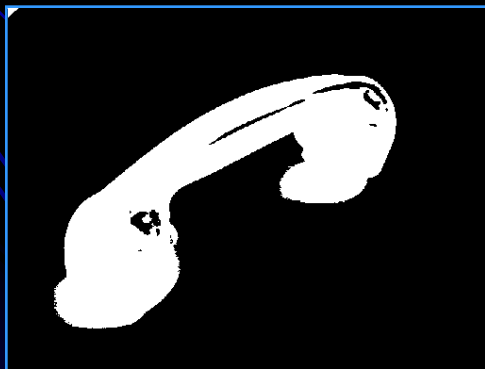
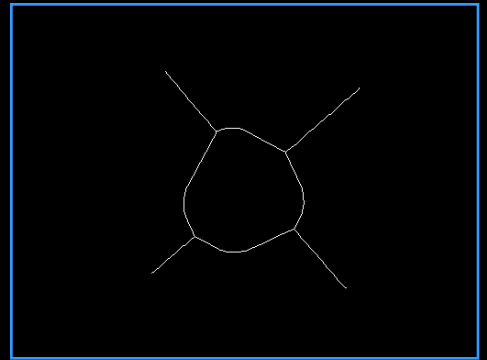
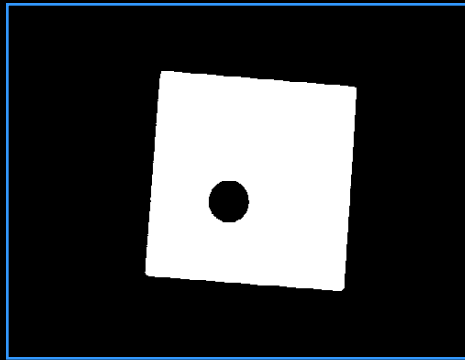
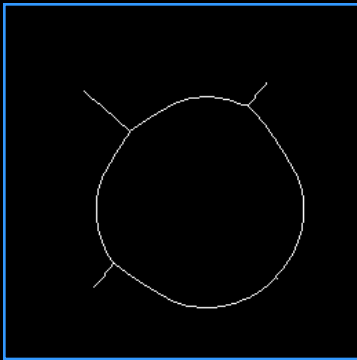
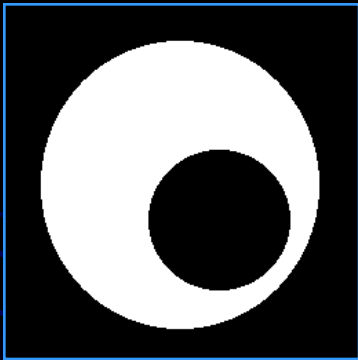
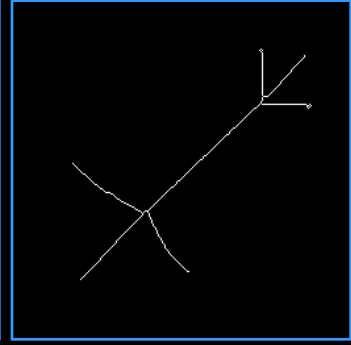
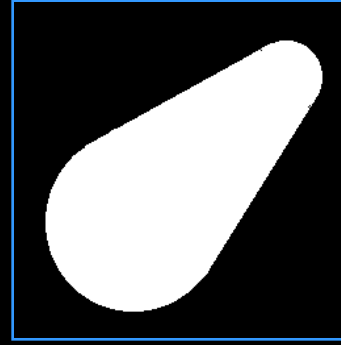
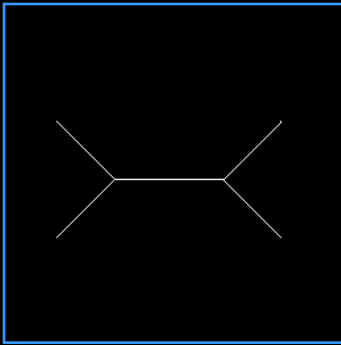
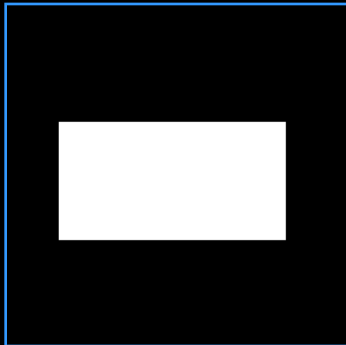
# Kostra

*Rekonštrukcia:* ak poznáme  $S_i(F)$ , ŠP  $B$  a  $n$ :

$$F = \prod_{i=0}^n \left( S_i(F) \oplus^i B \right)$$



# Kostra



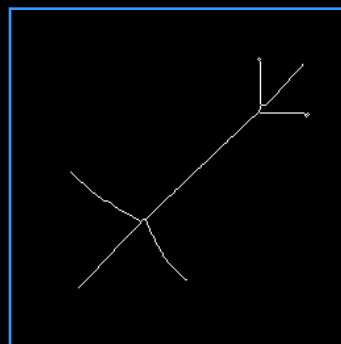
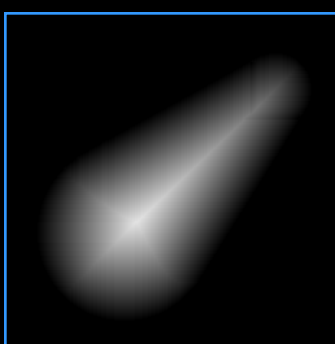
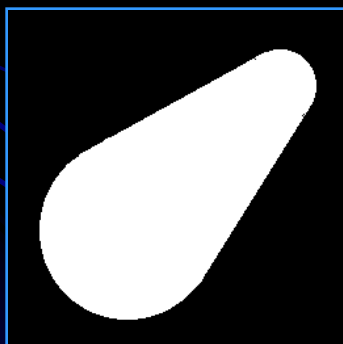
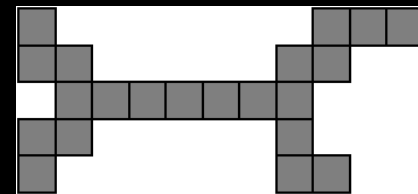
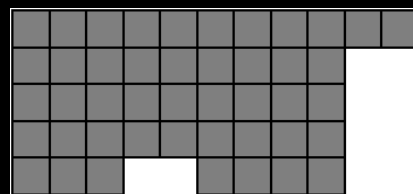
# Kostra - iné algoritmy

Zužovanie

Postupné zužovanie

Zachováame koncové body a spojnice

Distance Transform



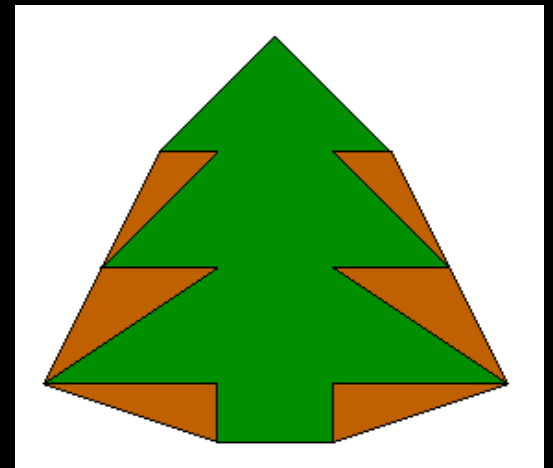
# Konvexný obal

Konvexná množina

$$x_1, x_2 \in R \Rightarrow \overline{x_1 x_2} \subseteq R$$

Konvexný obal (Convex Hull) množiny R

Najmenšia konvexná nadmnožina R



# Pruning

Orezávanie – odstraňuje výčnelky

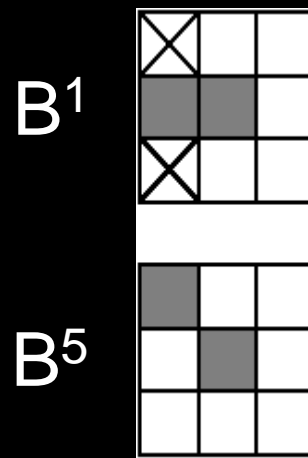
4 kroky

$$X_1 = A \oslash \{B^k\}$$

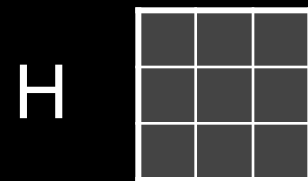
$$X_2 = \prod_{k=1}^8 (X_1 \otimes B^k)$$

$$X_3 = (X_2 \oplus H) \cap A$$

$$X_4 = X_1 \cup X_3$$



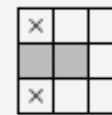
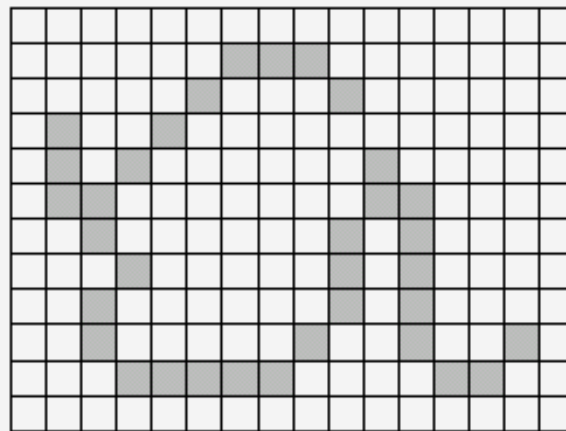
+ otočenie o  $90^\circ$



a	b
	c
d	e
f	g

**FIGURE 9.25**

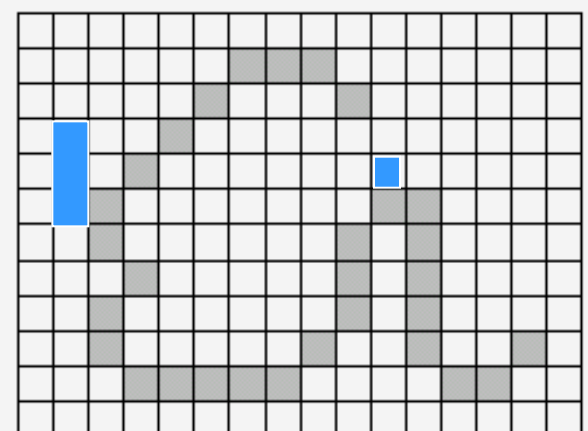
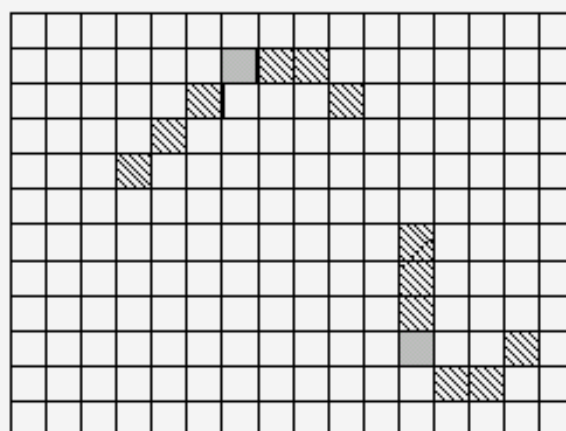
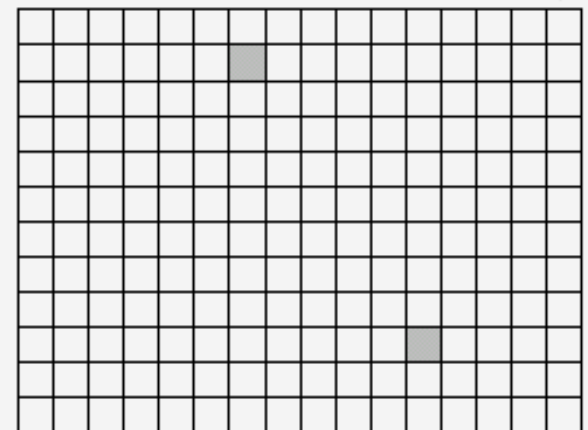
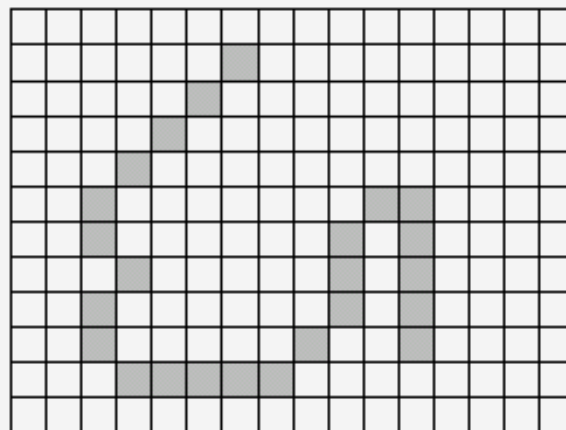
(a) Original image. (b) and (c) Structuring elements used for deleting end points. (d) Result of three cycles of thinning. (e) End points of (d). (f) Dilatation of end points conditioned on (a). (g) Pruned image.



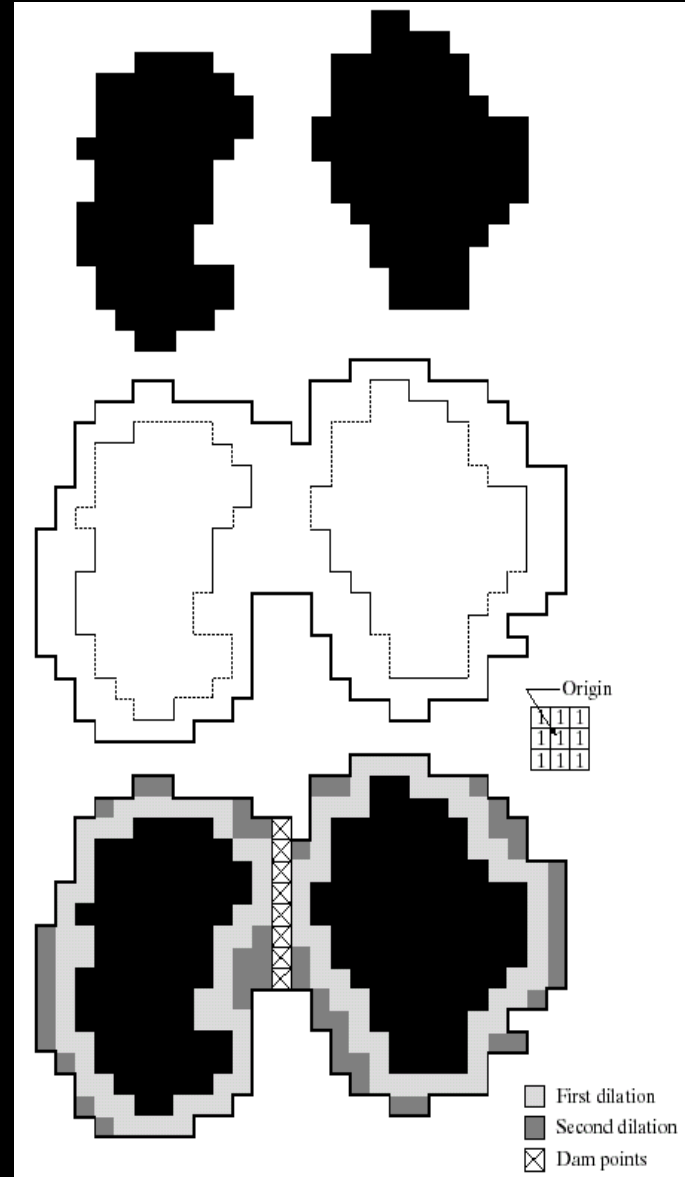
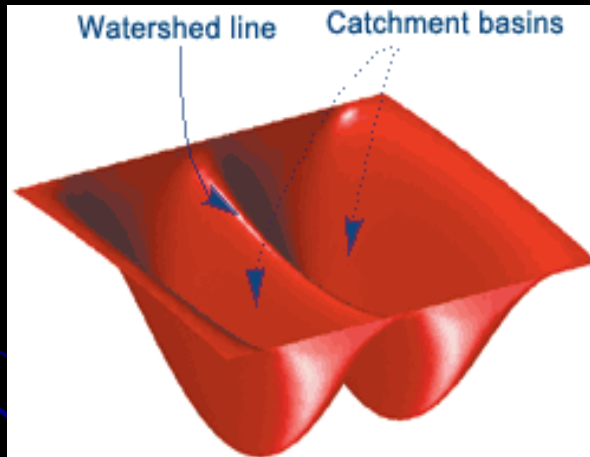
$B^1, B^2, B^3, B^4$  (rotated  $90^\circ$ )



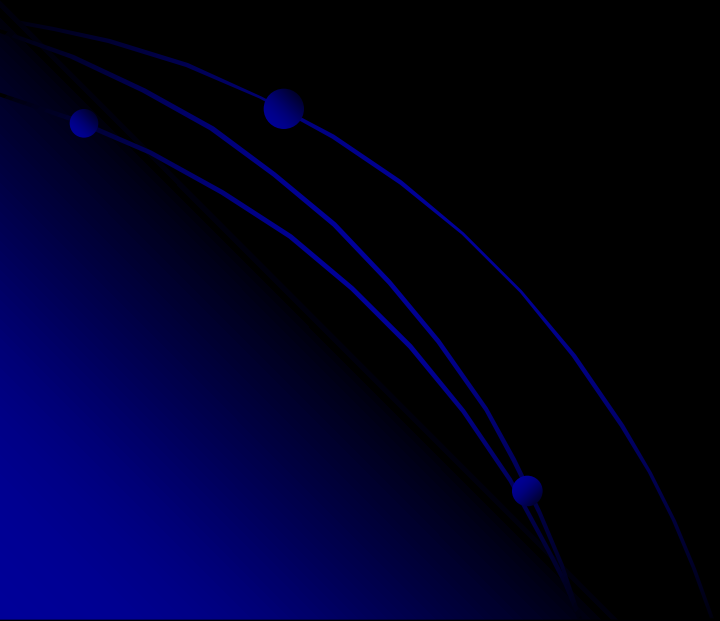
$B^5, B^6, B^7, B^8$  (rotated  $90^\circ$ )



# Watershed transformácia



# Zhrnutie



Operation	Equation	Comments
Translation	$(A)_z = \{w   w = a + z, \text{ for } a \in A\}$	(The Roman numerals refer to the structuring elements shown in Fig. 9.26). Translates the origin of $A$ to point $z$ .
Reflection	$\hat{B} = \{w   w = -b, \text{ for } b \in B\}$	Reflects all elements of $B$ about the origin of this set.
Complement	$A^c = \{w   w \notin A\}$	Set of points not in $A$ .
Difference	$A - B = \{w   w \in A, w \notin B\}$ $= A \cap B^c$	Set of points that belong to $A$ but not to $B$ .
Dilation	$A \oplus B = \{z   (\hat{B})_z \cap A \neq \emptyset\}$	"Expands" the boundary of $A$ . (I)
Erosion	$A \ominus B = \{z   (B)_z \subseteq A\}$	"Contracts" the boundary of $A$ . (I)
Opening	$A \circ B = (A \ominus B) \oplus B$	Smooths contours, breaks narrow isthmuses, and eliminates small islands and sharp peaks. (I)
Closing	$A \bullet B = (A \oplus B) \ominus B$	Smooths contours, fuses narrow breaks and long thin gulfs, and eliminates small holes. (I)



Hit-or-miss transform	$A \circledast B = (A \ominus B_1) \cap (A^c \ominus B_2)$ $= (A \ominus B_1) - (A \oplus \hat{B}_2)$	The set of points (coordinates) at which, simultaneously, $B_1$ found a match (“hit”) in $A$ and $B_2$ found a match in $A^c$ .
Boundary extraction	$\beta(A) = A - (A \ominus B)$	Set of points on the boundary of set $A$ . (I)
Region filling	$X_k = (X_{k-1} \oplus B) \cap A^c; X_0 = p \text{ and } k = 1, 2, 3, \dots$	Fills a region in $A$ , given a point $p$ in the region. (II)
Connected components	$X_k = (X_{k-1} \oplus B) \cap A; X_0 = p \text{ and } k = 1, 2, 3, \dots$	Finds a connected component $Y$ in $A$ , given a point $p$ in $Y$ . (I)
Convex hull	$X_k^i = (X_{k-1}^i \circledast B^i) \cup A; i = 1, 2, 3, 4;$ $k = 1, 2, 3, \dots; X_0^i = A; \text{ and}$ $D^i = X_{\text{conv}}^i.$	Finds the convex hull $C(A)$ of set $A$ , where “conv” indicates convergence in the sense that $X_k^i = X_{k-1}^i$ . (III)

Operation	Equation	Comments
Thinning	$A \otimes B = A - (A \otimes B)$ $= A \cap (A \otimes B)^c$ $A \otimes \{B\} =$ $((\dots ((A \otimes B^1) \otimes B^2) \dots) \otimes B^n)$ $\{B\} = \{B^1, B^2, B^3, \dots, B^n\}$	<p>(The Roman numerals refer to the structuring elements shown in Fig. 9.26).</p> <p>Thins set <math>A</math>. The first two equations give the basic definition of thinning. The last two equations denote thinning by a sequence of structuring elements. This method is normally used in practice. (IV)</p>
Thickening	$A \odot B = A \cup (A \otimes B)$ $A \odot \{B\} =$ $((\dots (A \odot B^1) \odot B^2 \dots) \odot B^n)$	<p>Thickens set <math>A</math>. (See preceding comments on sequences of structuring elements.) Uses IV with 0's and 1's reversed.</p>

Skeletons

$$S(A) = \bigcup_{k=0} S_k(A)$$

$$S_k(A) = \bigcup_{k=0}^K \{ (A \ominus kB) - [(A \ominus kB) \circ B] \}$$

Reconstruction of  $A$ :

$$A = \bigcup_{k=0}^K (S_k(A) \oplus kB)$$

Finds the skeleton  $S(A)$  of set  $A$ . The last equation indicates that  $A$  can be reconstructed from its skeleton subsets  $S_k(A)$ . In all three equations,  $K$  is the value of the iterative step after which the set  $A$  erodes to the empty set. The notation  $(A \ominus kB)$  denotes the  $k$ th iteration of successive erosion of  $A$  by  $B$ . (I)

Pruning

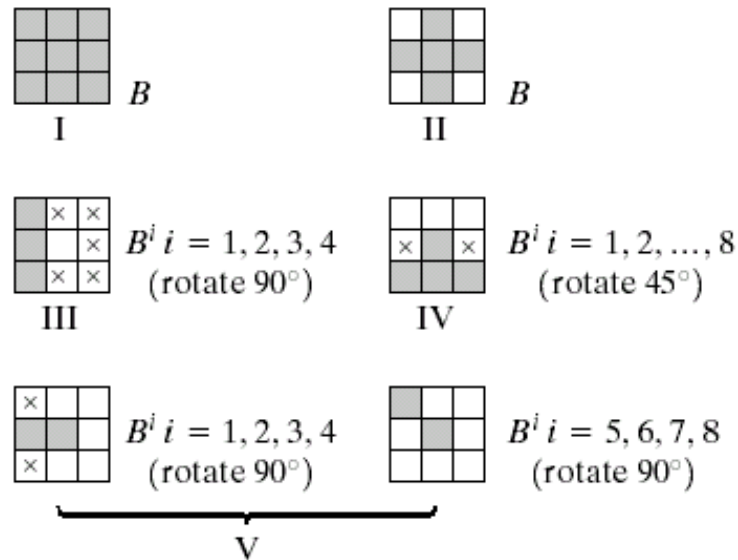
$$X_1 = A \otimes \{B\}$$

$$X_2 = \bigcup_{k=1}^8 (X_1 \circledast B^k)$$

$$X_3 = (X_2 \oplus H) \cap A$$

$$X_4 = X_1 \cup X_3$$

$X_4$  is the result of pruning set  $A$ . The number of times that the first equation is applied to obtain  $X_1$  must be specified. Structuring elements  $V$  are used for the first two equations. In the third equation  $H$  denotes structuring element  $I$ .



**FIGURE 9.26** Five basic types of structuring elements used for binary morphology. The origin of each element is at its center and the  $\times$ 's indicate "don't care" values.