

$$\textcircled{1} S = [(2, 1, -1, 0), (4, 3, 1, 2), (-1, 0, 2, 1)] \subset V_4(\mathbb{R})$$

- najdeme sklonovní deklinaci S

$$M_S = \begin{pmatrix} 2 & 1 & -1 & 0 \\ 4 & 3 & 1 & 2 \\ -1 & 0 & 2 & 1 \end{pmatrix} \sim \begin{pmatrix} 2 & 1 & -1 & 0 & | & 0 \\ 0 & 1 & 3 & 2 & | & 0 \\ 0 & \frac{1}{2} & \frac{3}{2} & 1 & | & 0 \end{pmatrix}$$

$$\sim \begin{pmatrix} 2 & 1 & -1 & 0 & | & \vec{v}_1 \\ 0 & 1 & 3 & 2 & | & \vec{v}_2 \\ 0 & 0 & 0 & 0 & | & 0 \end{pmatrix} \Rightarrow h(M_S) = 2 \Rightarrow \dim(H_S) = 2$$

- hledáme S^\perp kde $\dim(S^\perp) = 2$

$$\vec{x} \perp \vec{v}_1 \quad \langle \vec{x}, \vec{v}_1 \rangle = 0$$

$$\vec{x} \perp \vec{v}_2 \quad \langle \vec{x}, \vec{v}_2 \rangle = 0$$

- maticu M este upravime na redukovanu stupnici:

$$\begin{pmatrix} 1 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & 1 & 3 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -2 & -1 \\ 0 & 1 & 3 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Rieseni homogenniho systemu:

$$x_4 = b$$

$$x_3 = b$$

$$x_2 = -3b - 2b$$

$$x_1 = 2b + b$$

$$S_H = \{(2b, -3b - 2b, b, b), b \in \mathbb{R}\} = S^\perp$$

Za $b = a$ a b postupne dosadime 1:

$$S^\perp = \left[\underset{\vec{a}_1}{(2, -3, 1, 0)}, \underset{\vec{a}_2}{(1, -2, 0, 1)} \right]$$

②

$$a=2 \quad b=-1$$

$$M_f = \begin{pmatrix} 2 & 1 & 1 \\ -1 & 0 & 3 \\ 6 & 2 & -4 \end{pmatrix}$$

-jadro $\text{Ker}(f) : F(\vec{x}) = \vec{0} \quad \text{z. } M_f = \vec{0}$

$$(x_1, x_2, x_3) \cdot \begin{pmatrix} 2 & 1 & 1 \\ -1 & 0 & 3 \\ 6 & 2 & -4 \end{pmatrix} = (0, 0, 0)$$

$$\underbrace{(2x_1 + x_2 + 6x_3)}_0; \underbrace{(-x_1 + 2x_3)}_0; \underbrace{(x_1 + 3x_2 - 4x_3)}_0 = (0, 0, 0)$$

-řešíme homogenní systém

$$A = \left(\begin{array}{ccc|c} 2 & -1 & 6 & 0 \\ 1 & 0 & 2 & 0 \\ 1 & 2 & -4 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|c} 2 & -1 & 6 & 0 \\ 0 & \frac{1}{2} & -1 & 0 \\ 0 & \frac{3}{2} & -7 & 0 \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|c} 2 & -1 & 6 & 0 \\ 0 & \frac{1}{2} & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & -\frac{1}{2} & 3 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$x_3 = t$$

$$x_2 + (-2)x_3 = 0$$

$$x_2 = 2x_3 = 2t$$

$$x_1 + 2x_3 = 0 \Rightarrow x_1 = -2t$$

5)

$$(1, 1, 1) \stackrel{f}{=} (-1, 1)$$

$$\mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$(-2, -1, 1) \stackrel{f}{=} (2, 1)$$

$$(-1, 2, 0) \stackrel{f}{=} (0, 2)$$

- skúmajme, či sú pôvodné vektory LN

$$A = \begin{pmatrix} 1 & 1 & 1 \\ -2 & -1 & 1 \\ -1 & 2 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 3 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & -8 \end{pmatrix}$$

$\text{h}(A) = \mathbb{B}$ sú LN sme v \mathbb{R}^3 teda existuje práve 1 lineárne zobrazenie

Hľadáme $H(f)$

$$\left(\begin{array}{ccc|cc} 1 & 1 & 1 & -1 & 1 \\ -2 & -1 & 1 & 2 & 1 \\ -1 & 2 & 0 & 0 & 2 \end{array} \right) \sim \left(\begin{array}{ccc|cc} 1 & 1 & 1 & -1 & 1 \\ 0 & 1 & 3 & 0 & 3 \\ 0 & 3 & 1 & -1 & 3 \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|cc} 1 & 1 & 1 & -1 & 1 \\ 0 & 1 & 3 & 0 & 3 \\ 0 & 0 & 1 & \frac{1}{3} & \frac{2}{3} \end{array} \right) \sim \left(\begin{array}{ccc|cc} 1 & 0 & -2 & -1 & -2 \\ 0 & 1 & 3 & 0 & 3 \\ 0 & 0 & 1 & \frac{1}{3} & \frac{2}{3} \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|cc} 1 & 0 & 0 & -\frac{5}{3} & -\frac{10}{3} \\ 0 & 1 & 0 & \frac{1}{3} & \frac{7}{3} \\ 0 & 0 & 1 & \frac{1}{3} & \frac{2}{3} \end{array} \right) \Rightarrow H(f) = \begin{pmatrix} -\frac{5}{3} & -\frac{10}{3} \\ \frac{1}{3} & \frac{7}{3} \\ \frac{1}{3} & \frac{2}{3} \end{pmatrix}$$

② - podľa zobrazenia:

$$f(\vec{x}) = f(x_1, x_2, x_3) = (x_1, x_2, x_3) \quad \text{Hf} = \begin{pmatrix} -\frac{3}{4}x_1 - \frac{3}{8}x_2 + \frac{1}{8}x_3, & -\frac{1}{2}x_1 + \frac{3}{4}x_2 \\ & + \frac{3}{4}x_3 \end{pmatrix}$$

- dokážu, že zobrazenie je lineárne.

$$\begin{aligned} f(\vec{x} + \vec{y}) &= f((x_1, x_2, x_3) + (y_1, y_2, y_3)) = f(x_1 + y_1, x_2 + y_2, x_3 + y_3) \\ &= \left[-\frac{3}{4}(x_1 + y_1) - \frac{3}{8}(x_2 + y_2) + \frac{1}{8}(x_3 + y_3), -\frac{1}{2}(x_1 + y_1) + \frac{3}{4}(x_2 + y_2) \right. \\ &\quad \left. + \frac{3}{4}(x_3 + y_3) \right] \\ &= \left[-\frac{3}{4}x_1 - \frac{3}{4}y_1 - \frac{3}{8}x_2 - \frac{3}{8}y_2 + \frac{1}{8}x_3 + \frac{1}{8}y_3, -\frac{1}{2}x_1 - \frac{1}{2}y_1 + \frac{3}{4}x_2 + \frac{3}{4}y_2 \right. \\ &\quad \left. + \frac{3}{4}x_3 + \frac{3}{4}y_3 \right] \\ &= \left(-\frac{3}{4}x_1 - \frac{3}{8}x_2 + \frac{1}{8}x_3, -\frac{1}{2}x_1 + \frac{3}{4}x_2 + \frac{3}{4}x_3 \right) + \left(-\frac{3}{4}y_1 - \frac{3}{8}y_2 + \frac{1}{8}y_3, -\frac{1}{2}y_1 + \frac{3}{4}y_2 \right. \\ &\quad \left. + \frac{3}{4}y_3 \right) \\ &= f(\vec{x}) + f(\vec{y}) \end{aligned}$$

$$\begin{aligned} f(\lambda \vec{x}) &= f(\lambda(x_1, x_2, x_3)) = \left(-\frac{3\lambda}{4}x_1 - \frac{3\lambda}{8}x_2 + \frac{\lambda}{8}x_3, -\frac{\lambda}{2}x_1 + \frac{3\lambda}{4}x_2 + \frac{3\lambda}{4}x_3 \right) \\ &= \lambda \left(-\frac{3}{4}x_1 - \frac{3}{8}x_2 + \frac{1}{8}x_3, -\frac{1}{2}x_1 + \frac{3}{4}x_2 + \frac{3}{4}x_3 \right) = \lambda \cdot f(\vec{x}) \end{aligned}$$

$$4) \left[\overset{\vec{a}_1}{(1, 0, 2)}, \overset{\vec{a}_2}{(1, 1, -3)}, \overset{\vec{a}_3}{(0, 1, -1)} \right] = V_3(\mathbb{R})$$

↳ będzie trzeba zobaczyć czy wektorzy są liniowo niezależni w $V_3(\mathbb{R})$ musimy to kontrolować i on LN , albo nie!

$$\vec{g}_1 = (1, 0, 2) = \vec{a}_1$$

$$\vec{g}_2 = \vec{a}_2 + \alpha \cdot \vec{g}_1 = (1, 1, -3) + \alpha \cdot (1, 0, 2)$$

$$\alpha = -\frac{\langle \vec{a}_2, \vec{g}_1 \rangle}{\langle \vec{g}_1, \vec{g}_1 \rangle} = -\frac{1-6}{1+4} = -\frac{-5}{5} = 1$$

$$\vec{g}_2 = (1, 1, -3) + 1 \cdot (1, 0, 2) = (2, 1, -1)$$

$$\vec{g}_3 = \vec{a}_3 + \alpha \cdot \vec{g}_1 + \beta \cdot \vec{g}_2$$

$$\alpha = -\frac{\langle \vec{a}_3, \vec{g}_1 \rangle}{\langle \vec{g}_1, \vec{g}_1 \rangle} = -\frac{-2}{5} = \frac{2}{5}$$

$$\beta = -\frac{\langle \vec{a}_3, \vec{g}_2 \rangle}{\langle \vec{g}_2, \vec{g}_2 \rangle} = -\frac{1+1}{4+1+1} = -\frac{2}{6} = -\frac{1}{3}$$

$$\vec{g}_3 = (0, 1, -1) + \frac{2}{5}(1, 0, 2) - \frac{1}{3}(2, 1, -1)$$

$$= (0, 1, -1) + \left(\frac{2}{5}, 0, \frac{4}{5}\right) + \left(-\frac{2}{3}, -\frac{1}{3}, \frac{1}{3}\right)$$

$$= \left(\frac{-4}{15}, \frac{2}{3}, \frac{2}{15}\right) \cdot 15 = (-4, 10, 2)$$

- wektorzy $(1, 0, 2)$, $(2, 1, -1)$, $(-4, 10, 2)$ są liniowo niezależni a LN będą generują całą $VP V_3(\mathbb{R})$

5)

$$A = \left(\begin{array}{cccc|c} 4 & 4 & 0 & 2 & 4 \\ 0 & -1 & -1 & 0 & -3 \\ 1 & 4 & 3 & 1 & 4 \\ 3 & 2 & -1 & 1 & 6 \end{array} \right) \sim \left(\begin{array}{cccc|c} 4 & 4 & 0 & 2 & 4 \\ 0 & -1 & -1 & 0 & -3 \\ 0 & 3 & 3 & \frac{1}{2} & 3 \\ 0 & -1 & -1 & -\frac{1}{2} & 3 \end{array} \right)$$

$$\sim \left(\begin{array}{cccc|c} 4 & 4 & 0 & 2 & 4 \\ 0 & -1 & -1 & 0 & -3 \\ 0 & 0 & 0 & \frac{1}{2} & -6 \\ 0 & 0 & 0 & -\frac{1}{2} & 6 \end{array} \right) \sim \left(\begin{array}{cccc|c} 4 & 4 & 0 & 2 & 4 \\ 0 & -1 & -1 & 0 & -3 \\ 0 & 0 & 0 & \frac{1}{2} & -6 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$h(A) = 3$ $h(A|B) = 3 \Rightarrow$ sistemul nu are soluții

-este în formă echivalentă cu sistemul de ecuații:

$$\left(\begin{array}{cccc|c} 1 & 1 & 0 & \frac{1}{2} & 1 \\ 0 & 1 & 1 & 0 & 3 \\ 0 & 0 & 0 & 1 & -12 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \sim \left(\begin{array}{cccc|c} 1 & 0 & -1 & 0 & 4 \\ 0 & 1 & 1 & 0 & 3 \\ 0 & 0 & 0 & 1 & -12 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$x_3 = \lambda$ $x_2 + \lambda = 3 \Rightarrow x_2 = 3 - \lambda$

$x_4 = -12$ $x_1 = 4 + \lambda$

$S_N = \{ (4 + \lambda, 3 - \lambda, \lambda, -12), \lambda \in \mathbb{R} \}$

$S_N = \underbrace{(4, 3, 0, -12)}_K + \underbrace{\{ (\lambda, -\lambda, \lambda, 0), \lambda \in \mathbb{R} \}}_{S_H}$